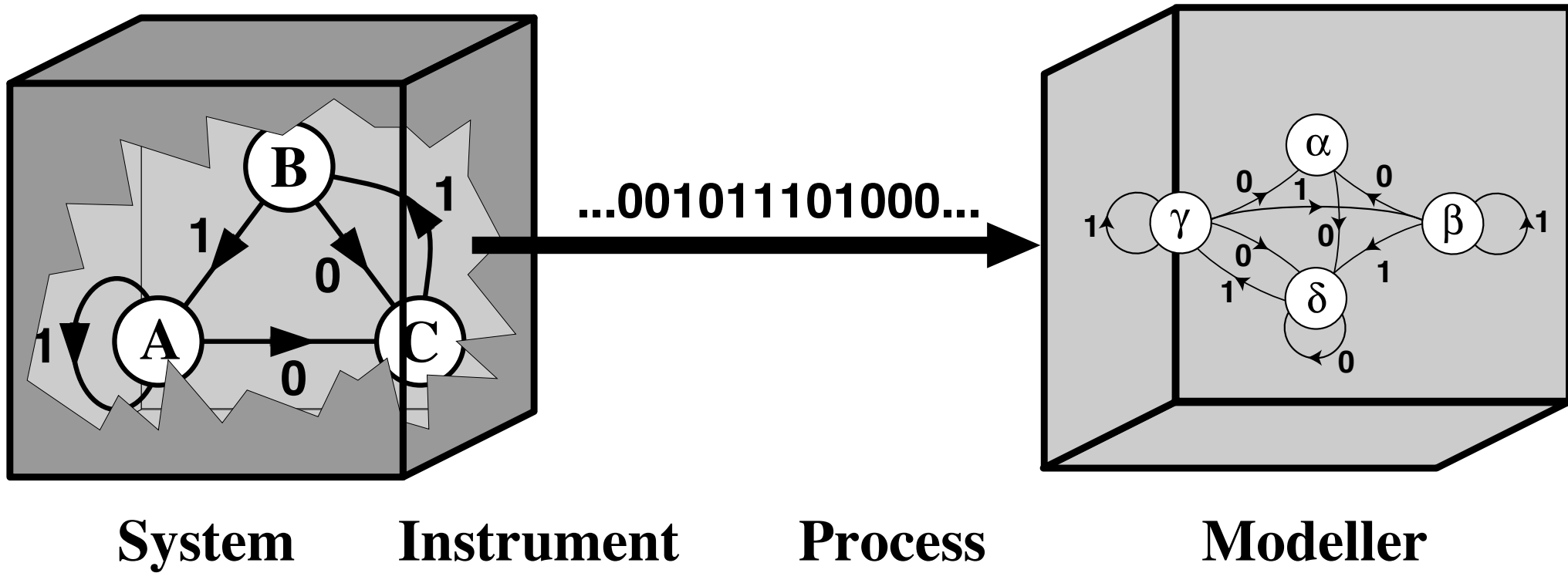


Complexity

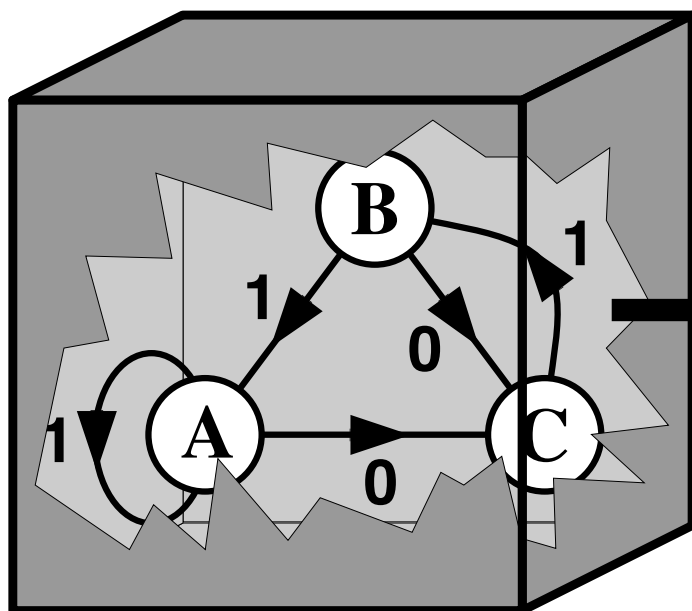
Jim Crutchfield & Ryan James
Complexity Sciences Center
Physics Department
University of California at Davis

Complex Systems Summer School
Santa Fe Institute
St. John's College, Santa Fe, NM
11 June 2012



The Learning Channel

Last Week

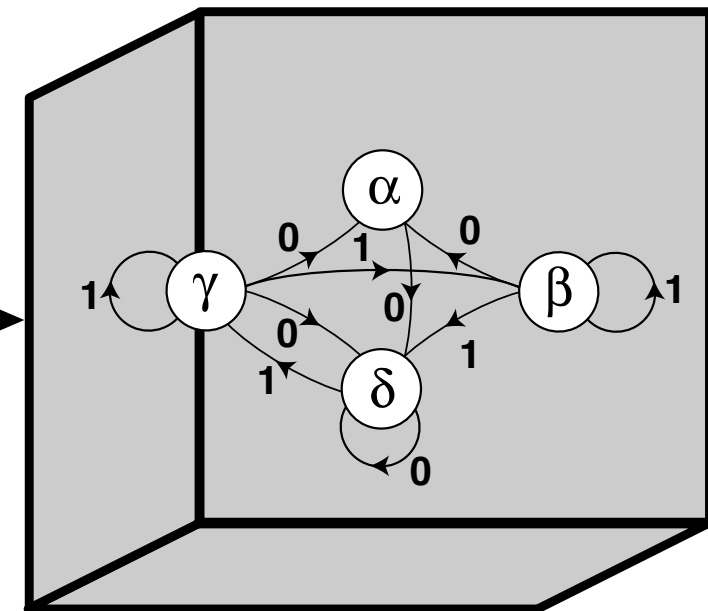


System

Instrument

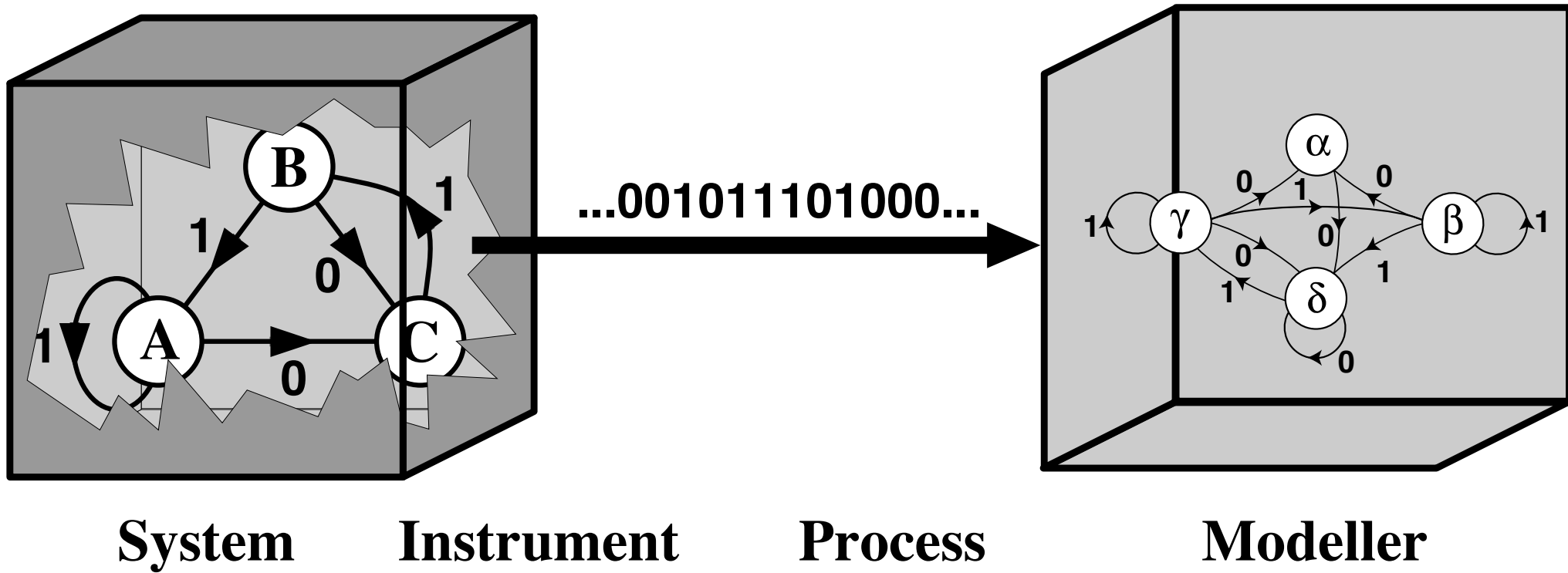
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Process



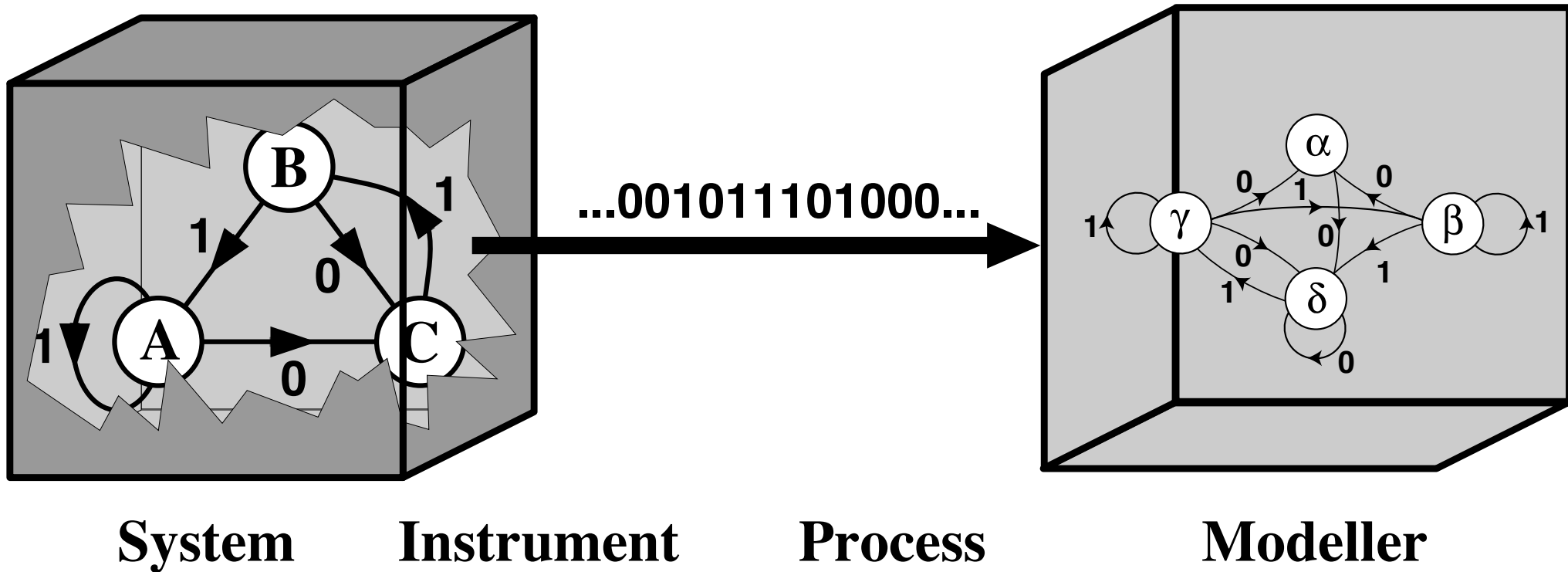
Modeller

The Learning Channel

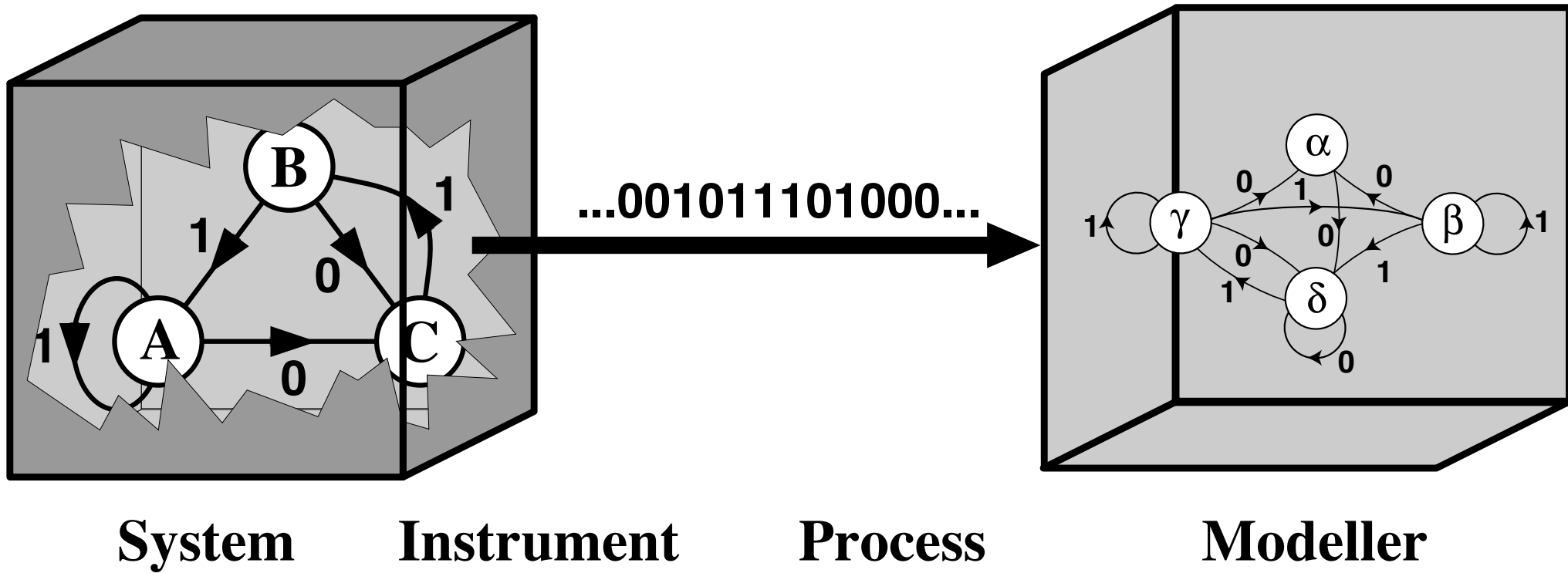


The Learning Channel

Morning

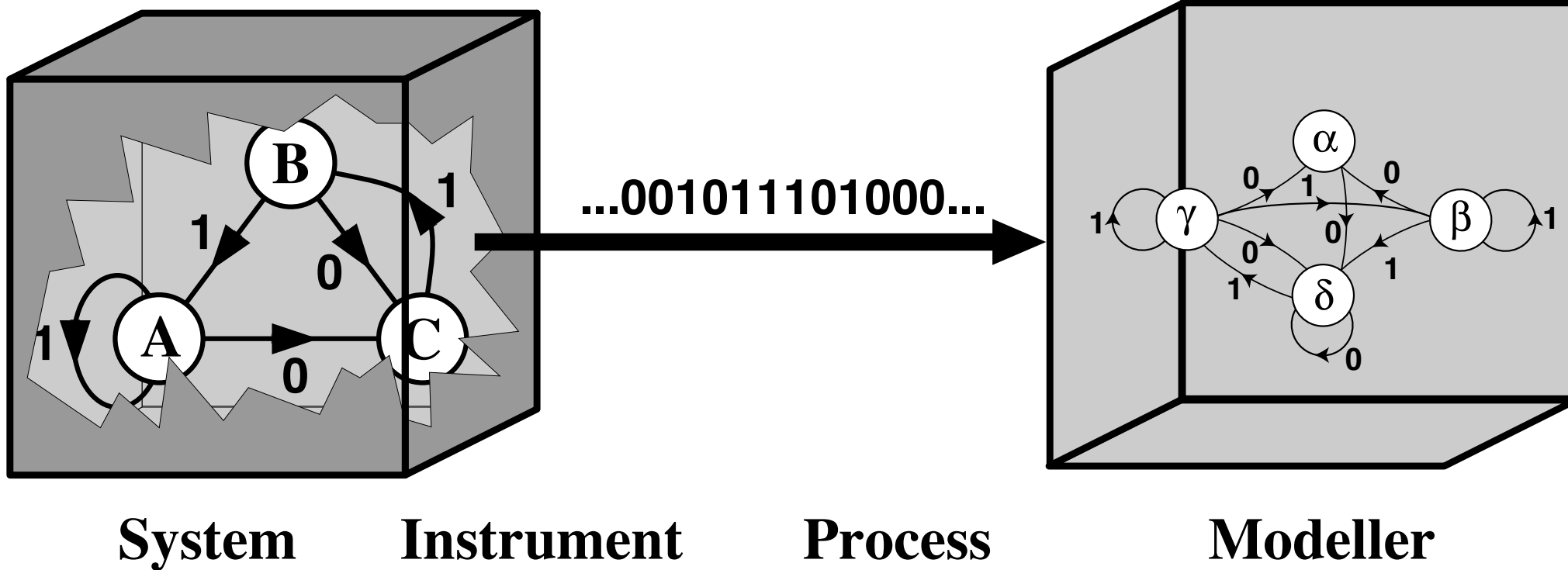
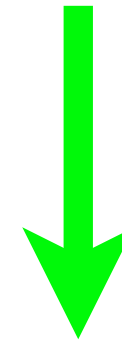


The Learning Channel



The Learning Channel

Afternoon



The Learning Channel

Complexity

Morning:

Processes (Jim: 9:30-10:45 AM)

Information (Jim + Ryan: 11:00 AM-12:00 PM)

Afternoon:

Structure (Jim: 1:30-2:45 PM)

Measures of Complexity (Jim: 3:00-4:00 PM)

Evening 6:30-8:00 PM:

Labs (Ryan)

Complexity

References? Many, for example.

Stanislaw Lem, *Chance and Order*, New Yorker **59** (1984) 88-98.

T. Cover and J. Thomas, *Elements of Information Theory*,
Wiley, Second Edition (2006) Chapters 1 - 7.

M. Li and P.M.B. Vitanyi, *An Introduction to Kolmogorov Complexity and its Applications*,
Springer, New York (1993).

J. P. Crutchfield and D. P. Feldman,
“Regularities Unseen, Randomness Observed: Levels of Entropy Convergence”, CHAOS
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J. P. Crutchfield, C. J. Ellison, and J. R. Mahoney,
“Time's Barbed Arrow: Irreversibility, Crypticity, and Stored Information”,
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R. G. James, C. J. Ellison, and J. P. Crutchfield,
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037109.

J. P. Crutchfield,
“Between Order and Chaos”, Nature Physics **8** (January 2012) 17-24.

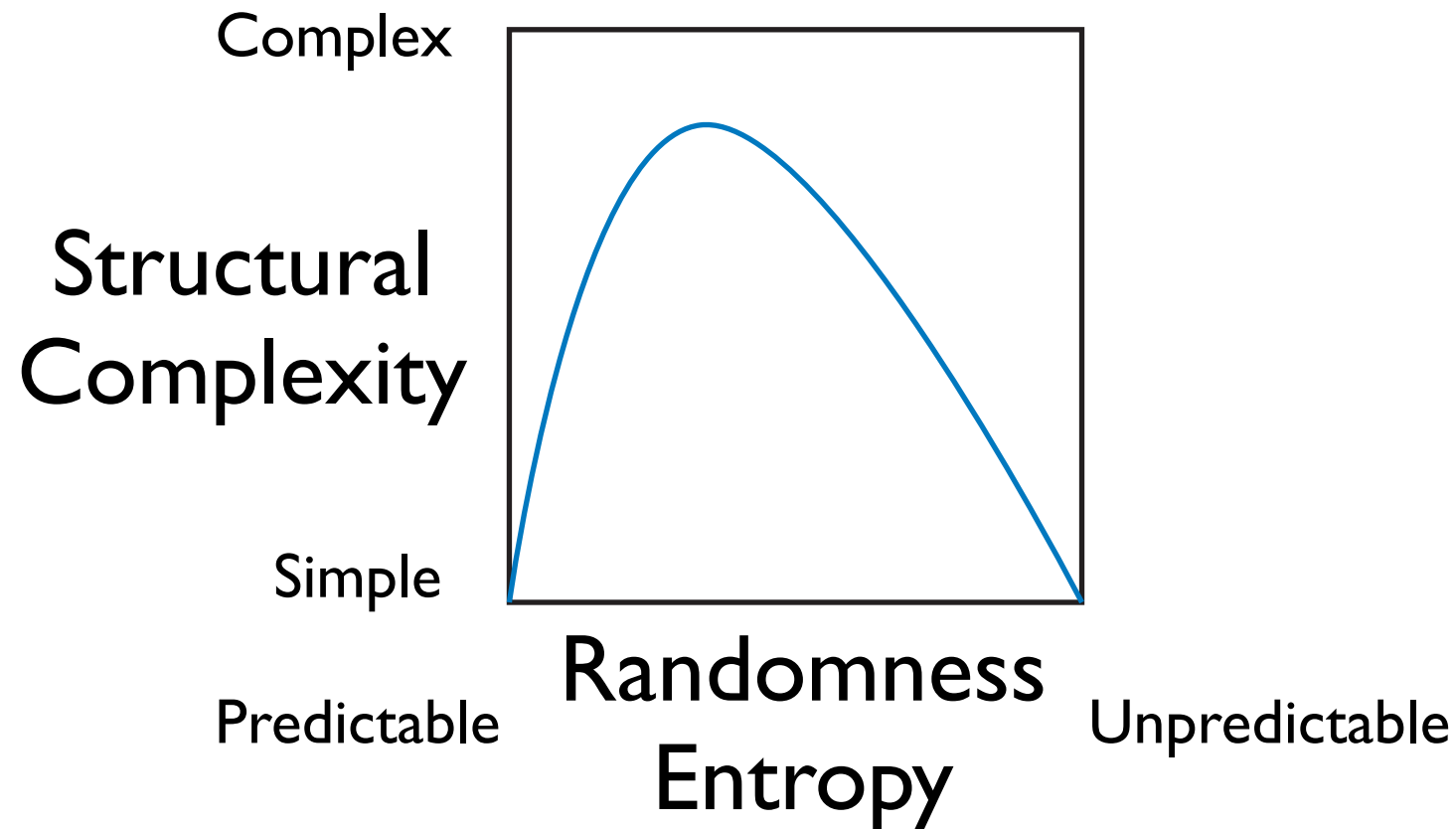
See <http://csc.ucdavis.edu/~cmg/>

Applications?

Computational Mechanics

Complexity-Entropy Diagram:

Analyze a class of processes: Chaos, spin systems, biosequences, hydrodynamics, ...



Analogous to Thermodynamic Phase Diagram (gas, liquid, solid).
But uses only intrinsic computation properties.

A wide diversity of Complexity-Entropy Diagrams.

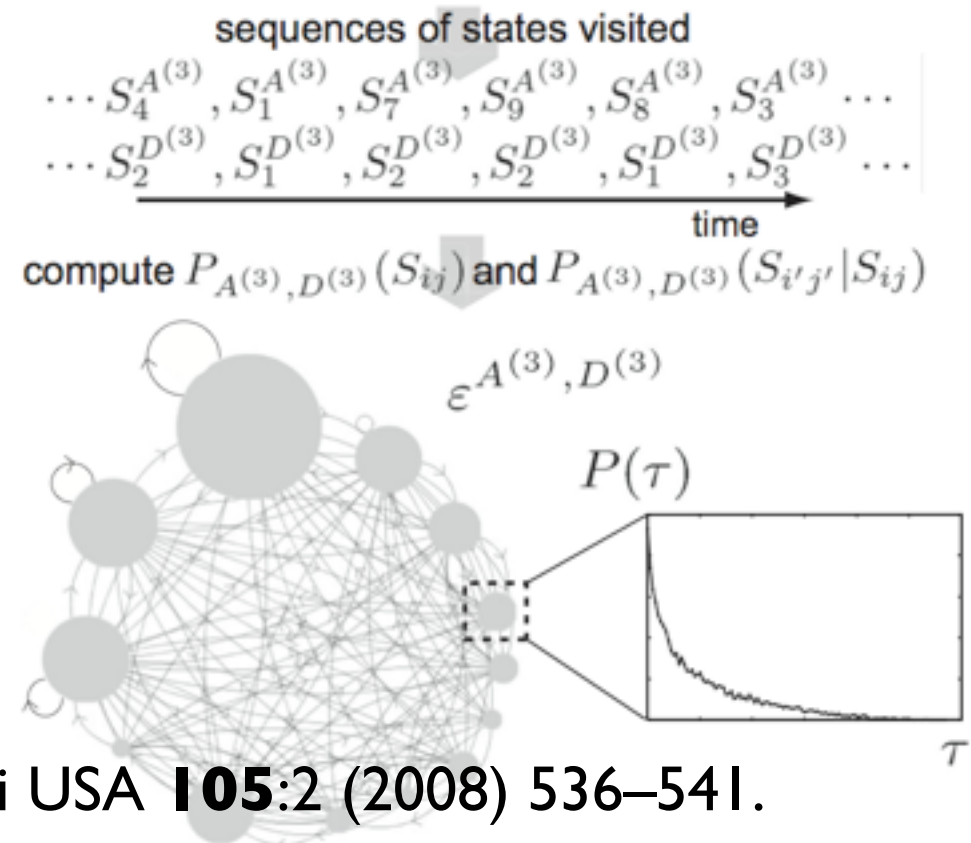
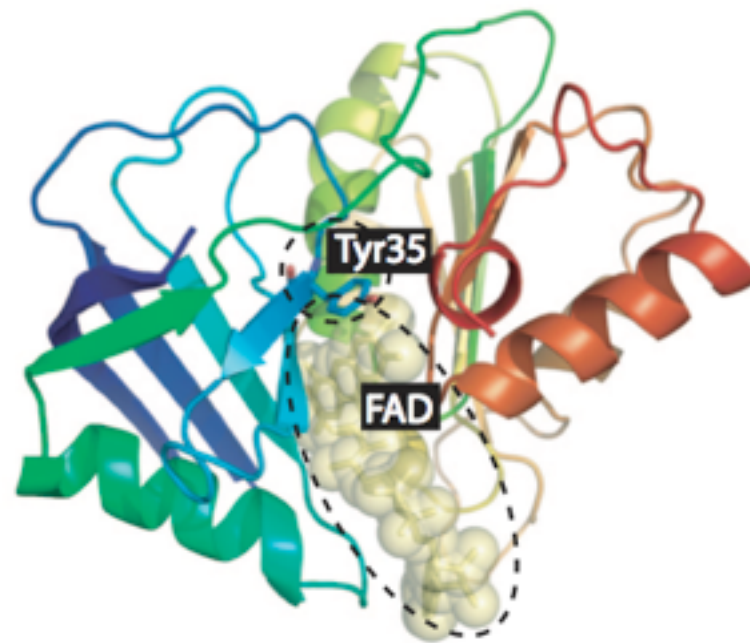
D. P. Feldman, C. S. McTague, J. P. Crutchfield, "Organization of Intrinsic Computation: Complexity-Entropy Diagrams and the Diversity of Natural Information Processing", CHAOS **18**:4 (2008) 53-73.

Computational Mechanics: Application to Experimental Molecular Dynamics Spectroscopy

Multiscale complex network of protein conformational fluctuations in single-molecule time series

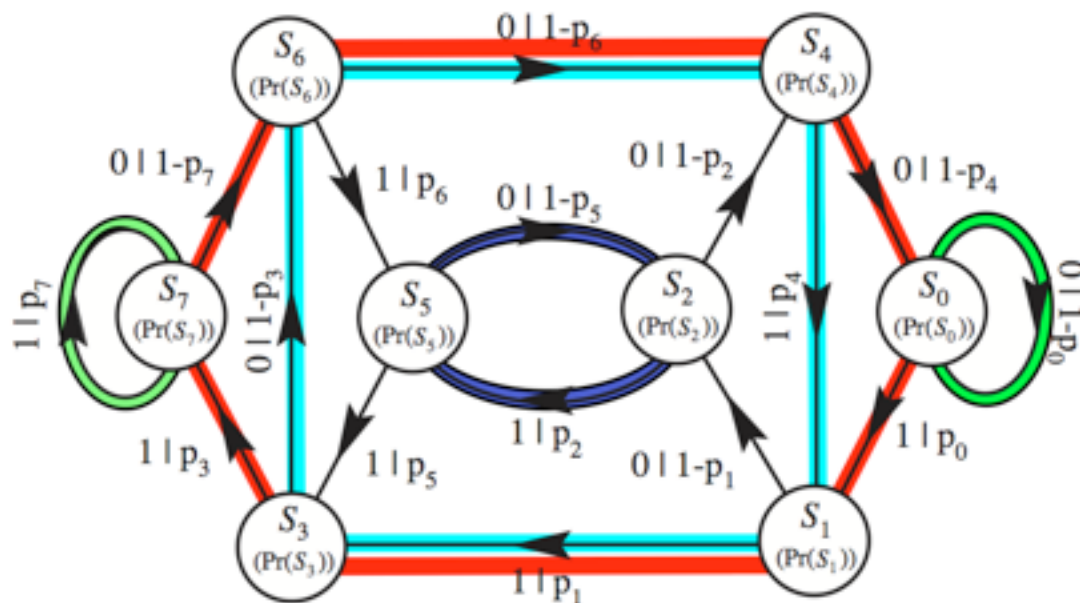
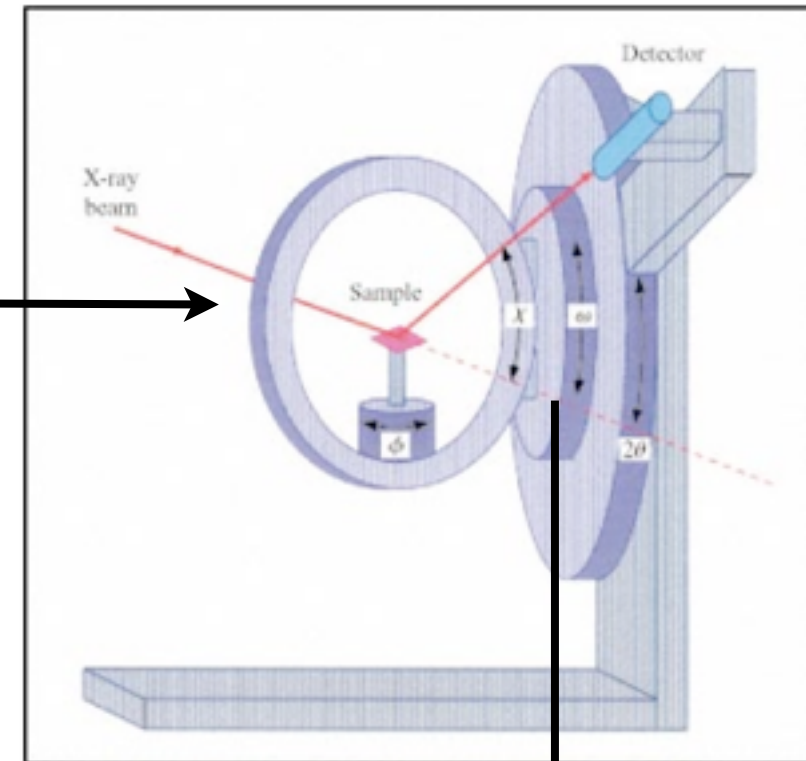
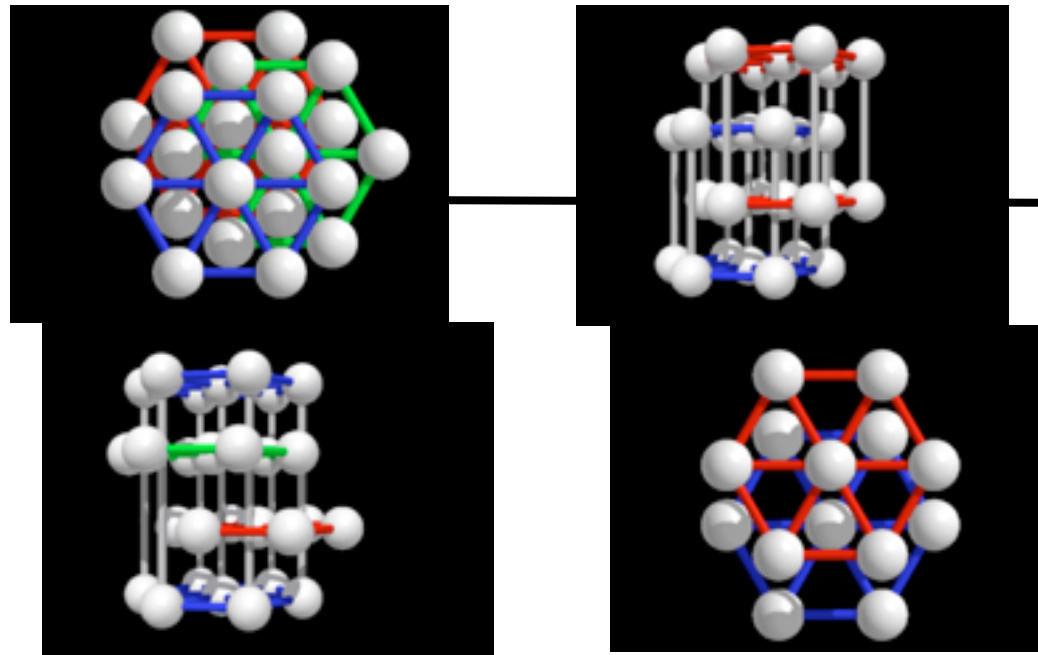
Chun-Biu Li^{*†‡}, Haw Yang^{§¶}, and Tamiki Komatsuzaki^{*†¶||}

^{*}Nonlinear Sciences Laboratory, Department of Earth and Planetary Sciences, Faculty of Science, Kobe University, Nada, Kobe 657-8501, Japan; [†]Core Research for Evolutional Science and Technology (CREST), Japan Science and Technology Agency (JST), Kawaguchi, Saitama 332-0012, Japan; [‡]Department of Chemistry, University of California, Berkeley, CA 94720; and [§]Physical Biosciences Division, Lawrence Berkeley National Laboratory, Berkeley, CA 94720

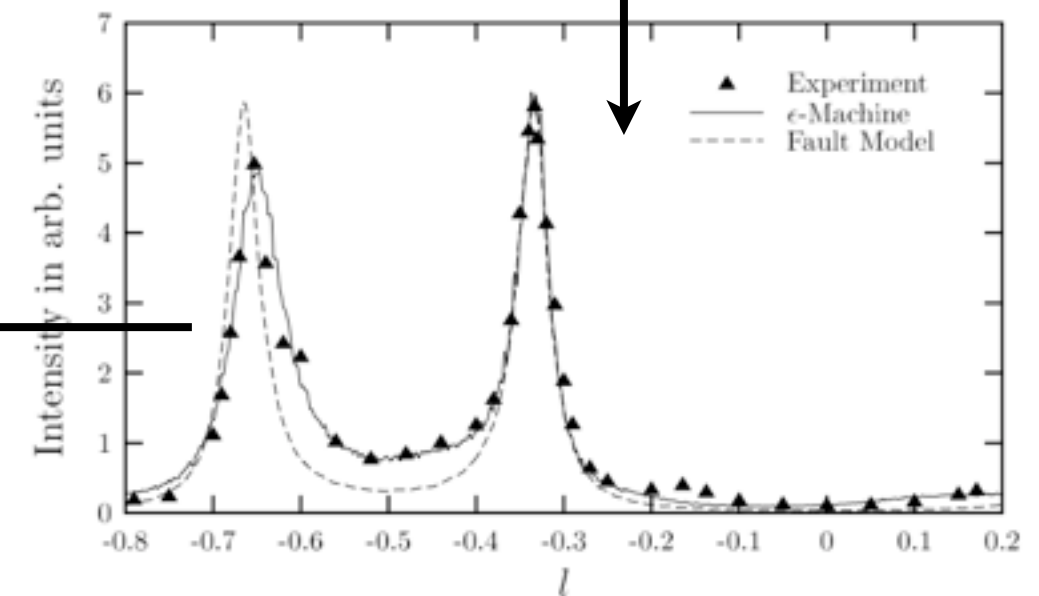


C.-B. Li, H. Yang, & T. Komatsuzaki, Proc. Natl. Acad. Sci USA **105**:2 (2008) 536–541.

Computational Mechanics: Application to Experimental X-Ray Diffraction



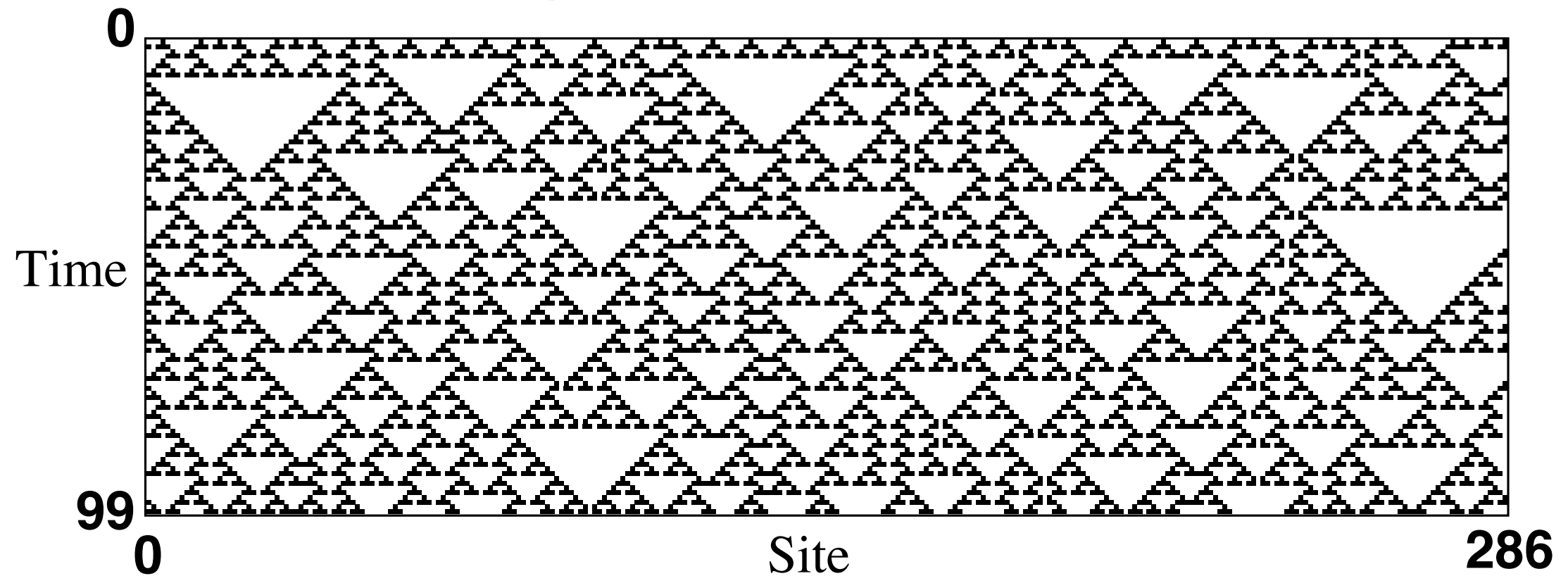
ϵ -MSR



D. P. Varn, G. S. Canright, J. P. Crutchfield, "Discovering Planar Disorder in Close-Packed Structures from X-Ray Diffraction: Beyond the Fault Model", Phys. Rev. B **66**: 17 (2002) 174110-2.

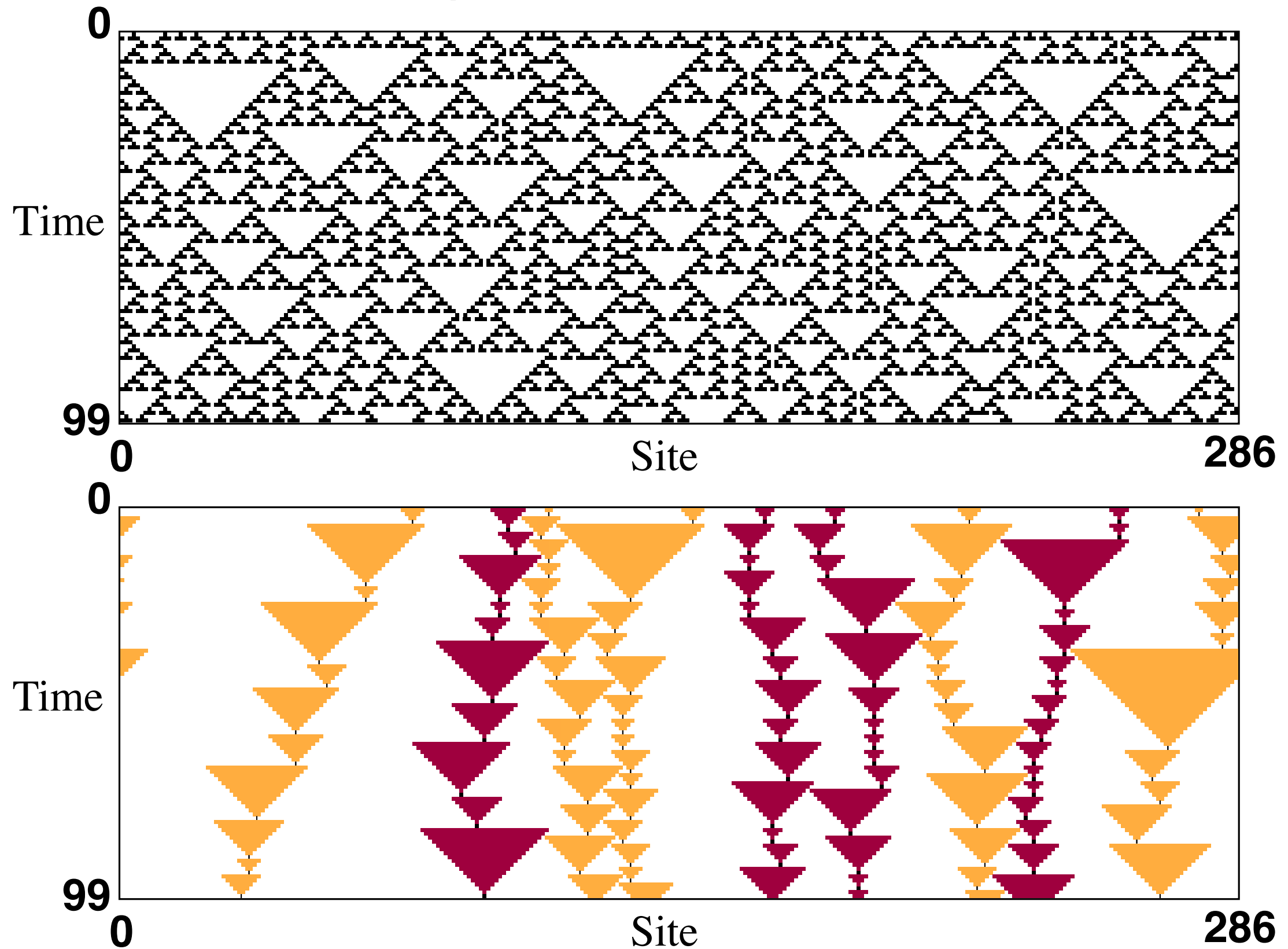
Measures of Complexity ...

Cellular Automata Computational Mechanics

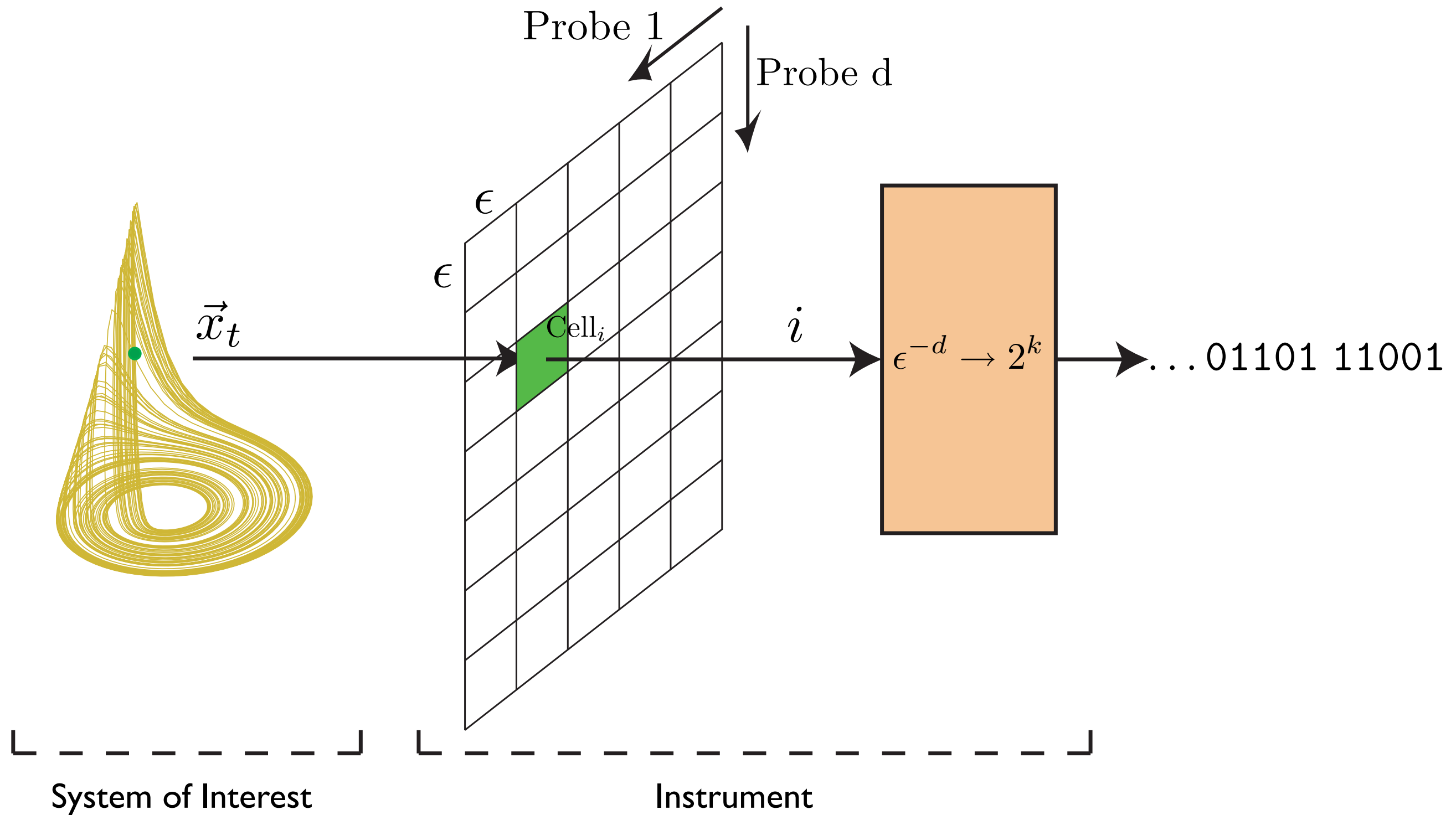


Measures of Complexity ...

Cellular Automata Computational Mechanics



Processes and Their Models ...



Measurement Channel

Processes and Their Models ...

Measurement Theory ...

Main questions now:

How do we characterize the resulting process?

Measure degrees of unpredictability & randomness.

What correlational structure is there?

How do we build a model from the process itself?

How much can we reconstruct about the
hidden internal dynamics?

Processes and Their Models ...

Stochastic Processes:

Chain of random variables:

$$\overleftrightarrow{S} \equiv \dots S_{-2} S_{-1} S_0 S_1 S_2 \dots$$

Random variable: S_t

Alphabet: \mathcal{A}

Realization:

$$\dots s_{-2} s_{-1} s_0 s_1 s_2 \dots ; s_t \in \mathcal{A}$$

Processes and Their Models ...

Stochastic Processes:

Chain of random variables: $\overleftrightarrow{S} = \overleftarrow{S}_t \overrightarrow{S}_t$

Past: $\overleftarrow{S}_t = \dots S_{t-3} S_{t-2} S_{t-1}$

Future: $\overrightarrow{S}_t = S_t S_{t+1} S_{t+2} \dots$

L-Block: $S_t^L \equiv S_t S_{t+1} \dots S_{t+L-1}$

Word: $s_t^L \equiv s_t s_{t+1} \dots s_{t+L-1} \in \mathcal{A}^L$

Processes and Their Models ...

Stochastic Processes ...

Process:

$$\Pr(\vec{S}) = \Pr(\dots S_{-2}S_{-1}S_0S_1S_2\dots)$$

Sequence (or word) distributions:

$$\{\Pr(S_t^L) = \Pr(S_t S_{t+1} \dots S_{t+L-1}) : S_t \in \mathcal{A}\}$$

Process:

$$\{\Pr(S_t^L) : \forall t, L\}$$

Consistency conditions:

$$\Pr(S_t^{L-1}) = \sum_{S_{t+L-1}} \Pr(S_t^L) \qquad \Pr(S_{t+1}^{L-1}) = \sum_{S_t} \Pr(S_t^L)$$

Processes and Their Models ...

Types of Stochastic Process:

Stationary process:

$$\Pr(S_t S_{t+1} \dots S_{t+L-1}) = \Pr(S_0 S_1 \dots S_{L-1})$$

Assume stationarity, unless otherwise noted.

Notation: Drop time indices.

Processes and Their Models ...

Models of Stochastic Processes:

Markov chain model of a Markov process:

States: $v \in \mathcal{A} = \{1, \dots, k\}$

$$\overleftrightarrow{V} = \dots V_{-2} V_{-1} V_0 V_1 \dots$$

Transition matrix: $T_{ij} = \Pr(v_{t+1} | v_t) \equiv p_{vv'}$

$$T = \begin{pmatrix} p_{11} & \cdots & p_{1k} \\ \vdots & \ddots & \vdots \\ p_{k1} & \cdots & p_{kk} \end{pmatrix}$$

Stochastic matrix: $\sum_{j=1}^k T_{ij} = 1$

Processes and Their Models ...

Models of Stochastic Processes ...

Markov chain ...

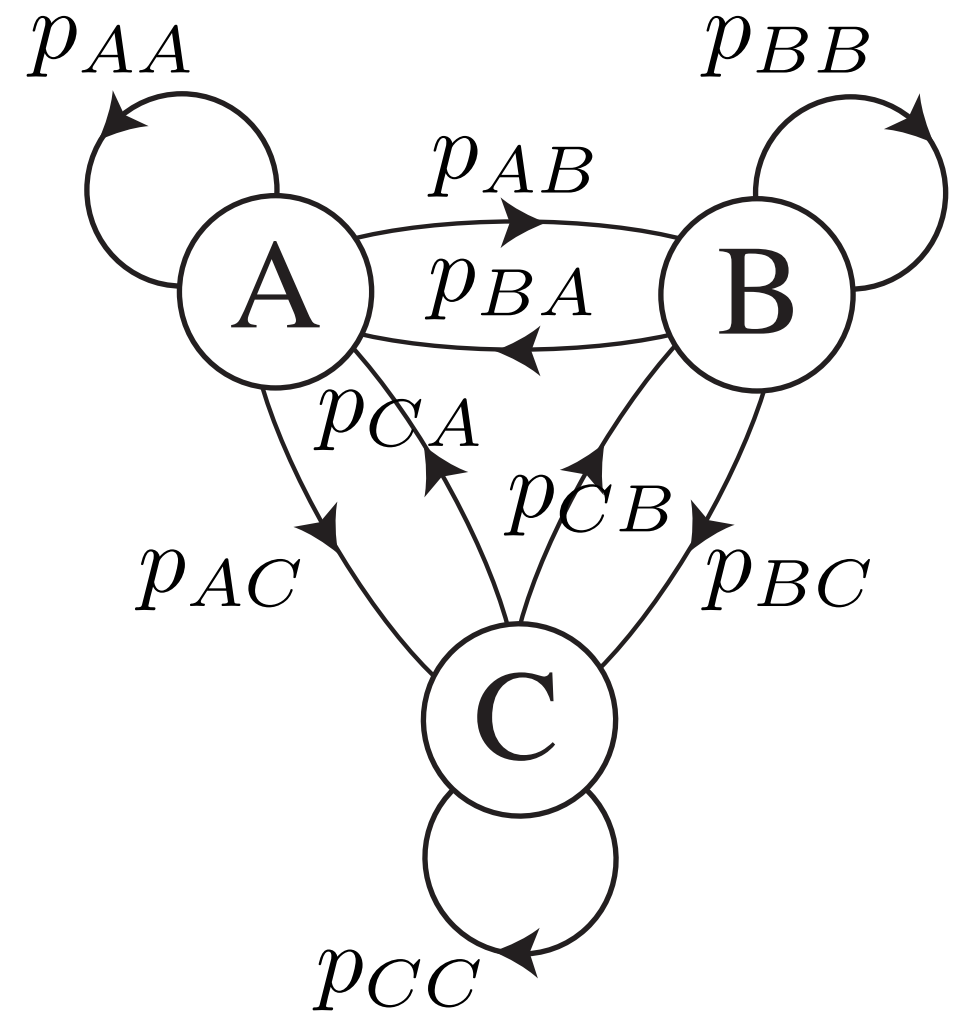
Example: $\mathcal{A} = \{A, B, C\}$

$$T = \begin{pmatrix} p_{AA} & p_{AB} & p_{AC} \\ p_{BA} & p_{BB} & p_{BC} \\ p_{CA} & p_{CB} & p_{CC} \end{pmatrix}$$

$$p_{AA} + p_{AB} + p_{AC} = 1$$

$$p_{BA} + p_{BB} + p_{BC} = 1$$

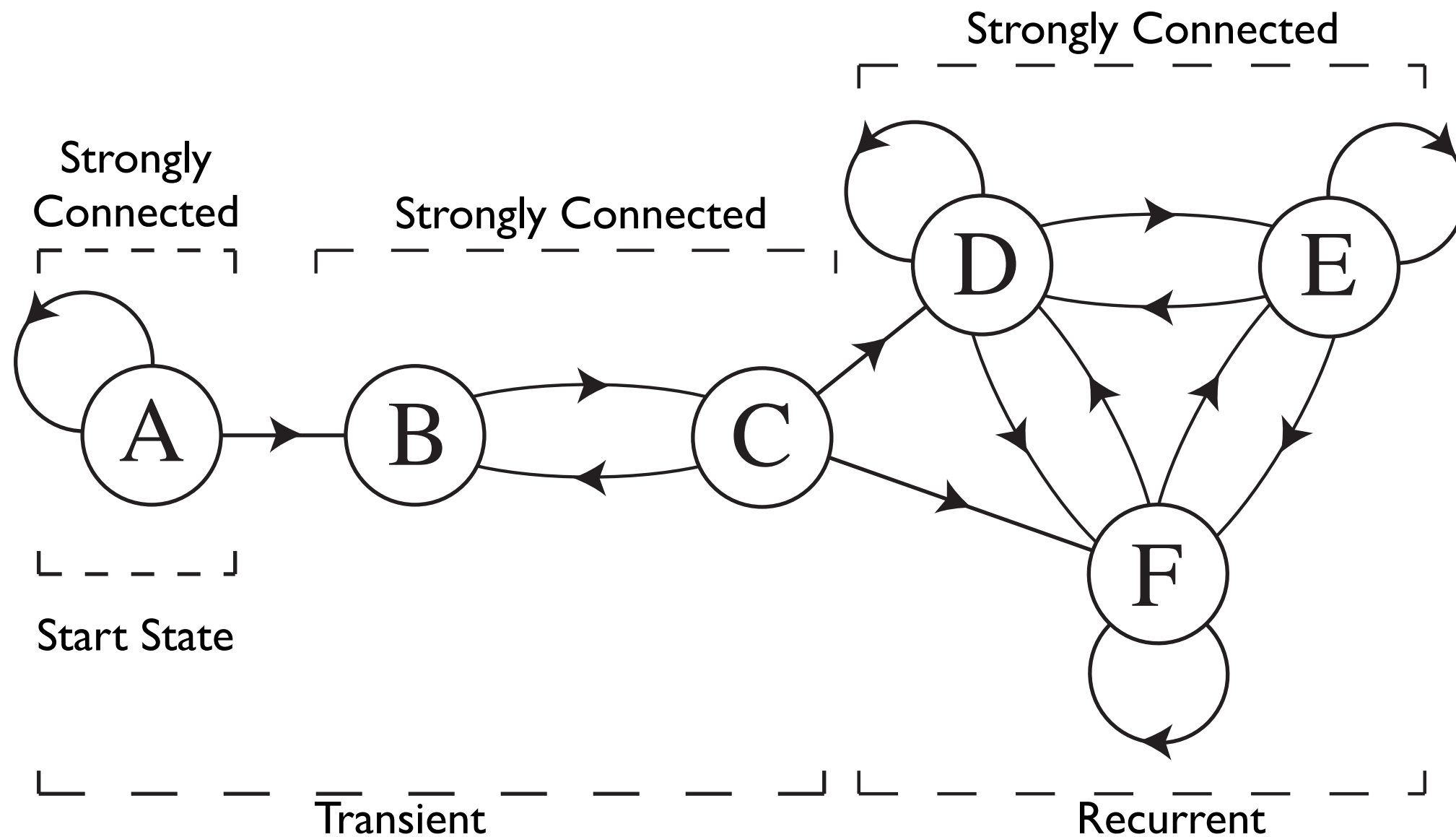
$$p_{CA} + p_{CB} + p_{CC} = 1$$



Processes and Their Models ...

Models of Stochastic Processes ...

Kinds of state:



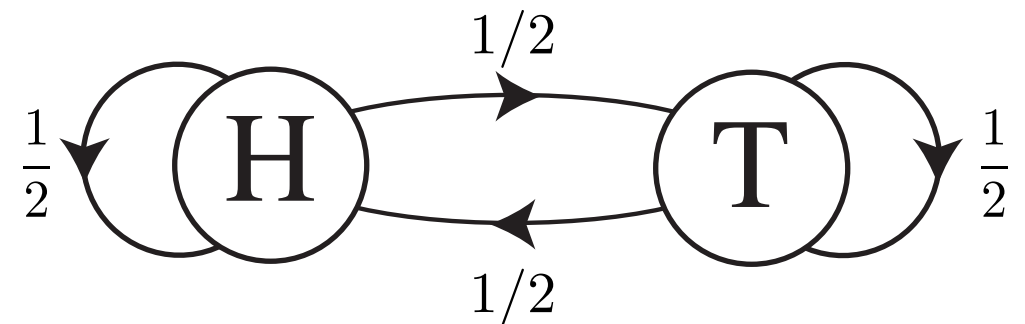
Processes and Their Models ...

Models of Stochastic Processes ...

Example:

Fair Coin: $\mathcal{A} = \{H, T\}$

$$T = \begin{pmatrix} \frac{1}{2} & \frac{1}{2} \\ \frac{1}{2} & \frac{1}{2} \end{pmatrix}$$



$$\Pr(H) = \Pr(T) = 1/2$$

Processes and Their Models ...

Models of Stochastic Processes ...

Example:

Fair Coin ...

Sequence Distribution: $\Pr(v^L) = 2^{-L}$

Word as binary fraction:

$$s^L = s_1 s_2 \dots s_L$$

$$“s^L” = \sum_{i=1}^L \frac{s_i}{2^i}$$

$$s^L \in [0, 1]$$

Processes and Their Models ...

Models of Stochastic Processes ...

Example:

Fair Coin ...

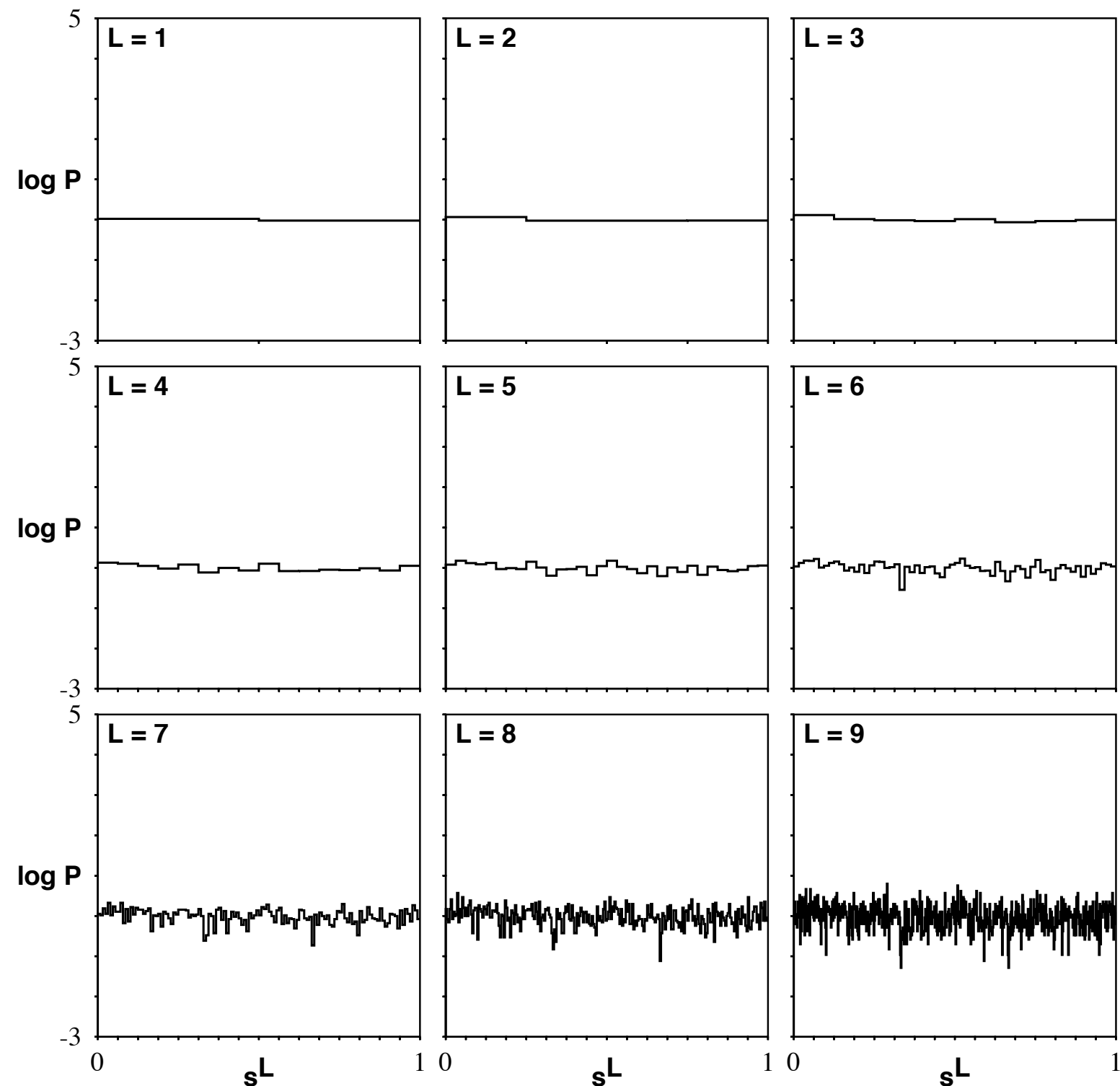
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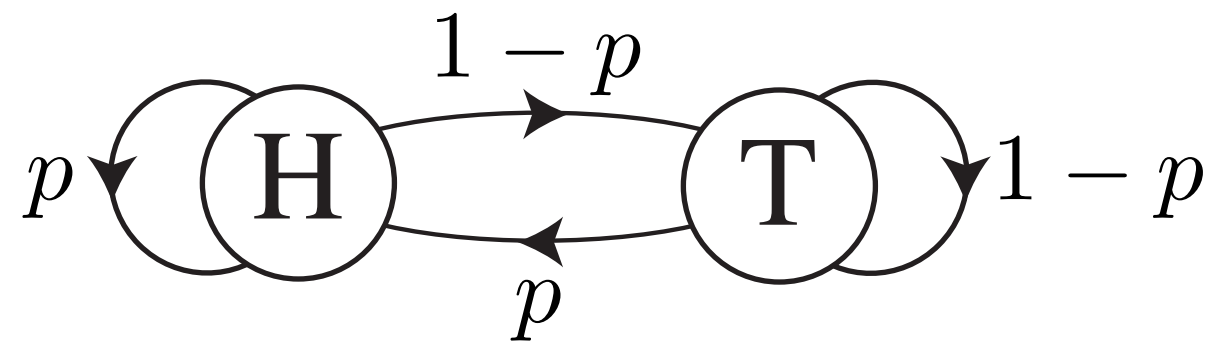
Processes and Their Models ...

Models of Stochastic Processes ...

Example:

Biased Coin: $\mathcal{A} = \{H, T\}$

$$T = \begin{pmatrix} p & 1 - p \\ p & 1 - p \end{pmatrix}$$



$$\Pr(H) = p$$

$$\Pr(T) = 1 - p$$

Processes and Their Models ...

Models of Stochastic Processes ...

Example:

Biased Coin ...

Sequence Distribution:

$$\Pr(s^L) = p^n (1 - p)^{L-n},$$

$n = \text{Number } H\text{s in } s^L$

Processes and Their Models ...

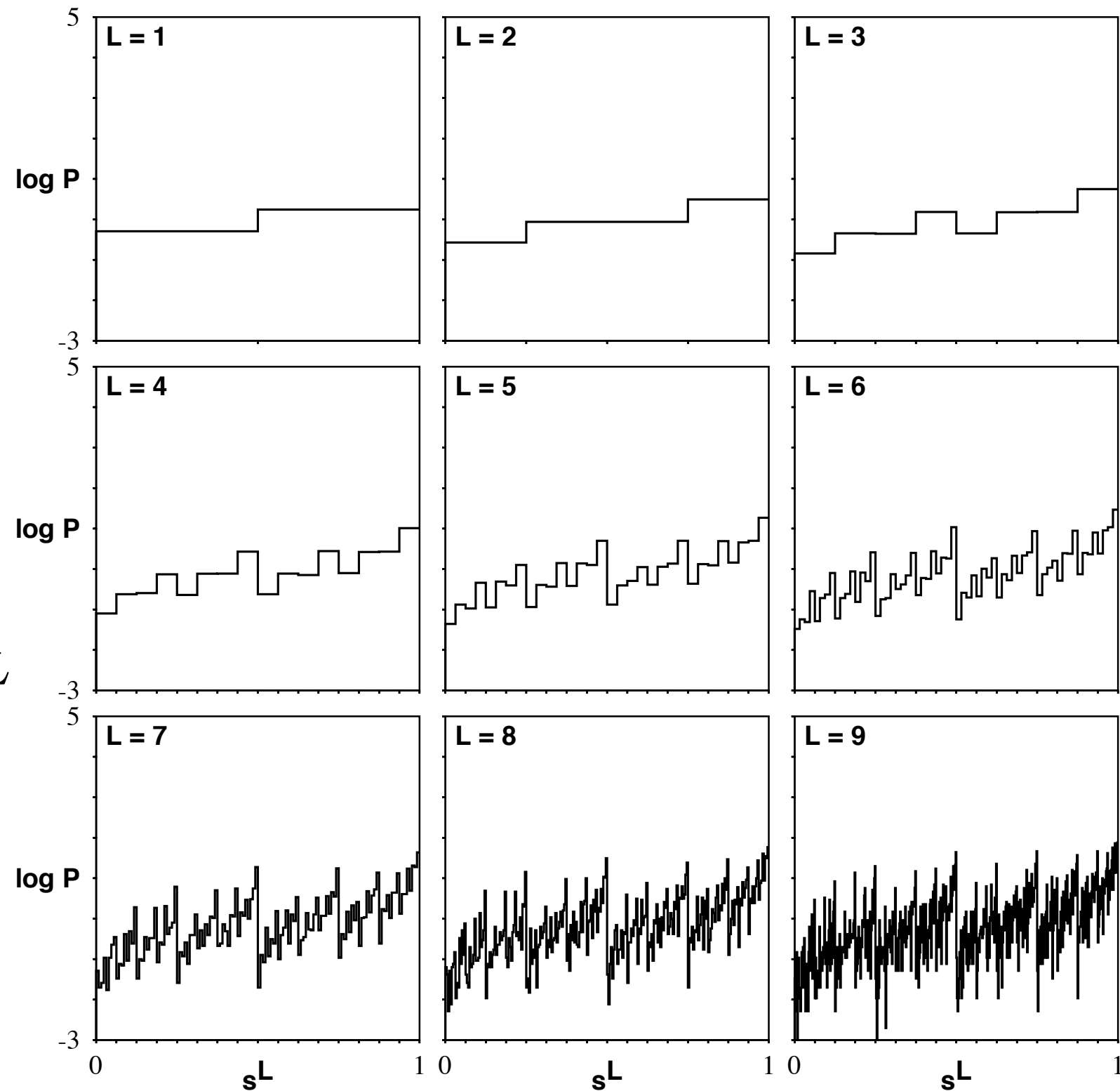
Models of Stochastic Processes ...

Example:
Biased Coin ...

Sequence Distribution:

$$\Pr(s^L) = p^n (1 - p)^{L-n},$$

$n = \text{Number } H\text{s in } s^L$



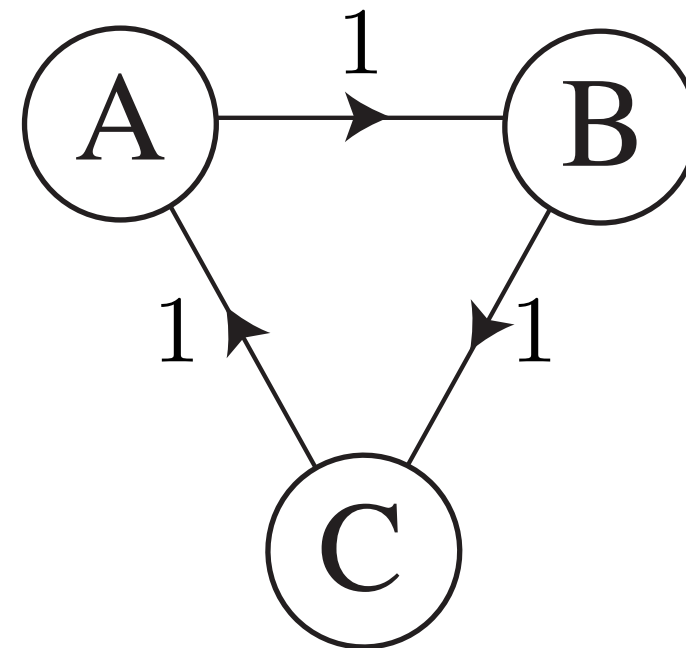
Processes and Their Models ...

Models of Stochastic Processes ...

Example:

Periodic: $\mathcal{A} = \{A, B, C\}$

$$T = \begin{pmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 1 & 0 & 0 \end{pmatrix}$$



Sequence distribution:

$$\Pr(A) = \Pr(B) = \Pr(C) = \frac{1}{3}$$

$$\Pr(AB) = \Pr(BC) = \Pr(CA) = \frac{1}{3} \quad \Pr(s^2) = 0 \quad \text{otherwise}$$

$$\Pr(ABC) = \Pr(BCA) = \Pr(CAB) = \frac{1}{3} \quad \Pr(s^3) = 0 \quad \text{otherwise}$$

Processes and Their Models ...

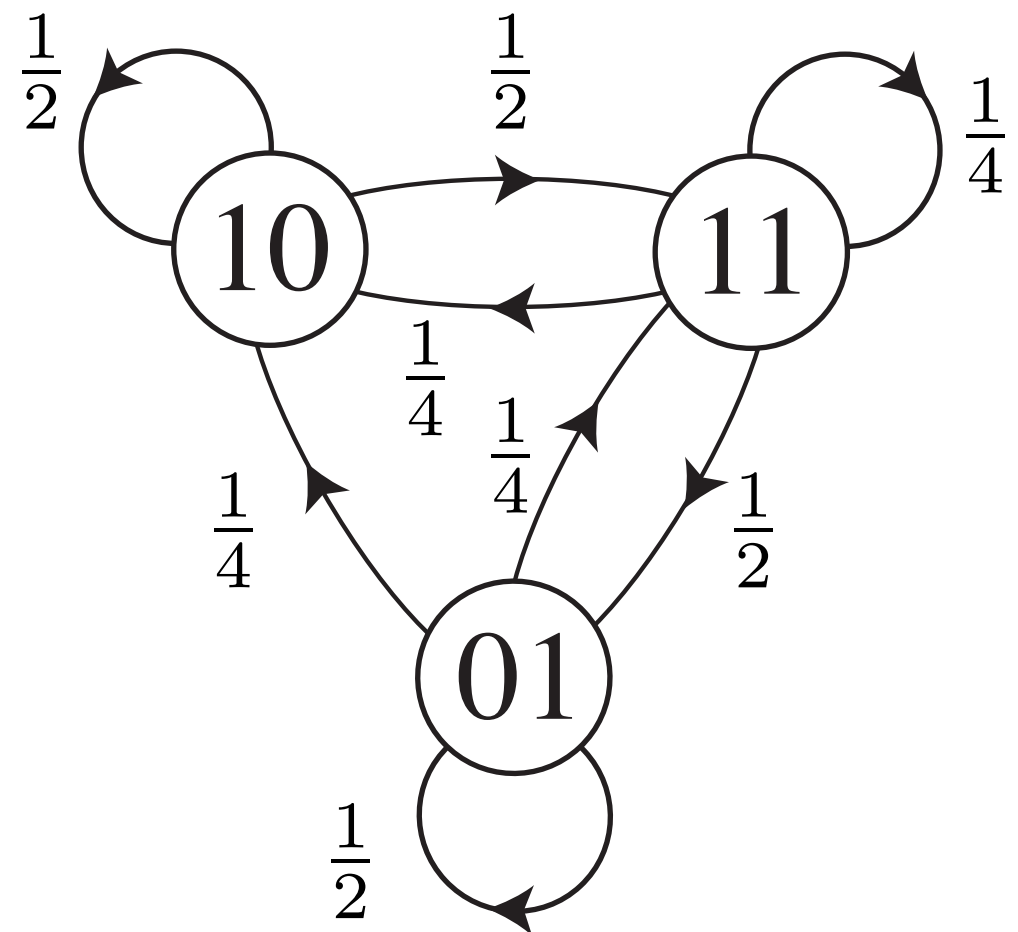
Models of Stochastic Processes ...

Example: Golden Mean Process = “No consecutive 0s”

Markov chain over 2-Blocks: $\mathcal{A} = \{10, 01, 11\}$

$$T = \begin{matrix} & \begin{matrix} 10 & 01 & 11 \end{matrix} \\ \begin{pmatrix} \frac{1}{2} & 0 & \frac{1}{2} \\ \frac{1}{4} & \frac{1}{2} & \frac{1}{4} \\ \frac{1}{4} & \frac{1}{2} & \frac{1}{4} \end{pmatrix} \end{matrix}$$

$$\pi = \left(\frac{1}{3}, \frac{1}{3}, \frac{1}{3} \right)$$



Processes and Their Models ...

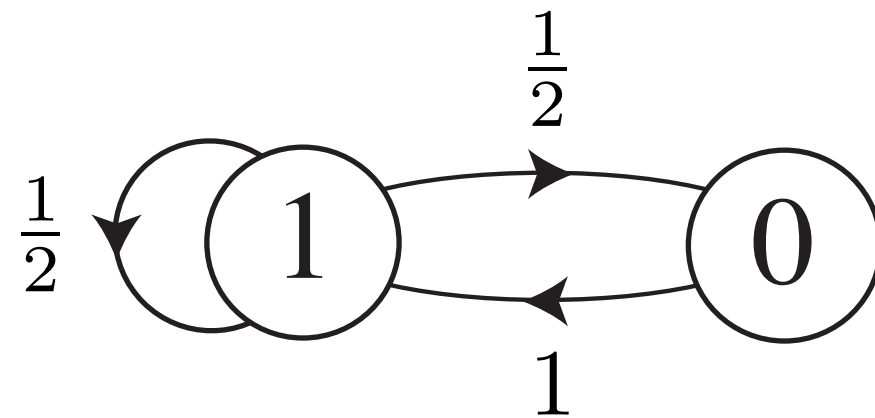
Models of Stochastic Processes ...

Example: Golden Mean Process ...

Markov chain over 1-Blocks: $\mathcal{A} = \{0, 1\}$

$$T = \begin{pmatrix} \frac{1}{2} & \frac{1}{2} \\ 1 & 0 \end{pmatrix}$$

$$\pi = \left(\frac{2}{3}, \frac{1}{3} \right)$$



Also an order-1 Markov chain. Minimal order.

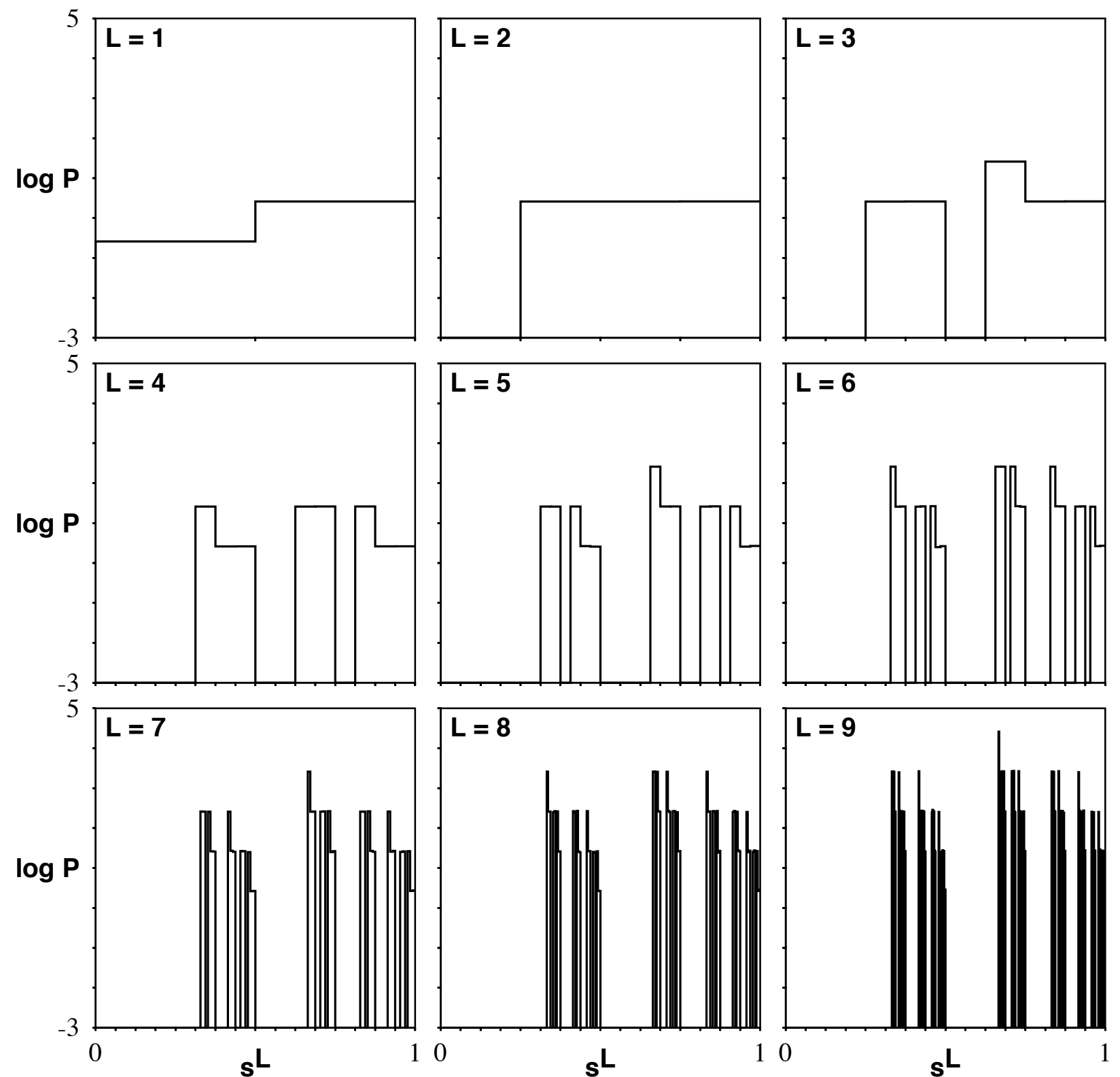
Previous model and this:

Different **presentations** of the same Golden Mean Process

Processes and Their Models ...

Models of Stochastic Processes ...

Example:
Golden Mean:



Processes and Their Models ...

Models of Stochastic Processes ...

Two Lessons:

Structure in the behavior: $\text{supp } \Pr(s^L)$

Structure in the distribution of behaviors: $\Pr(s^L)$

Processes and Their Models ...

Models of Stochastic Processes ...

Hidden Markov Models of Processes:

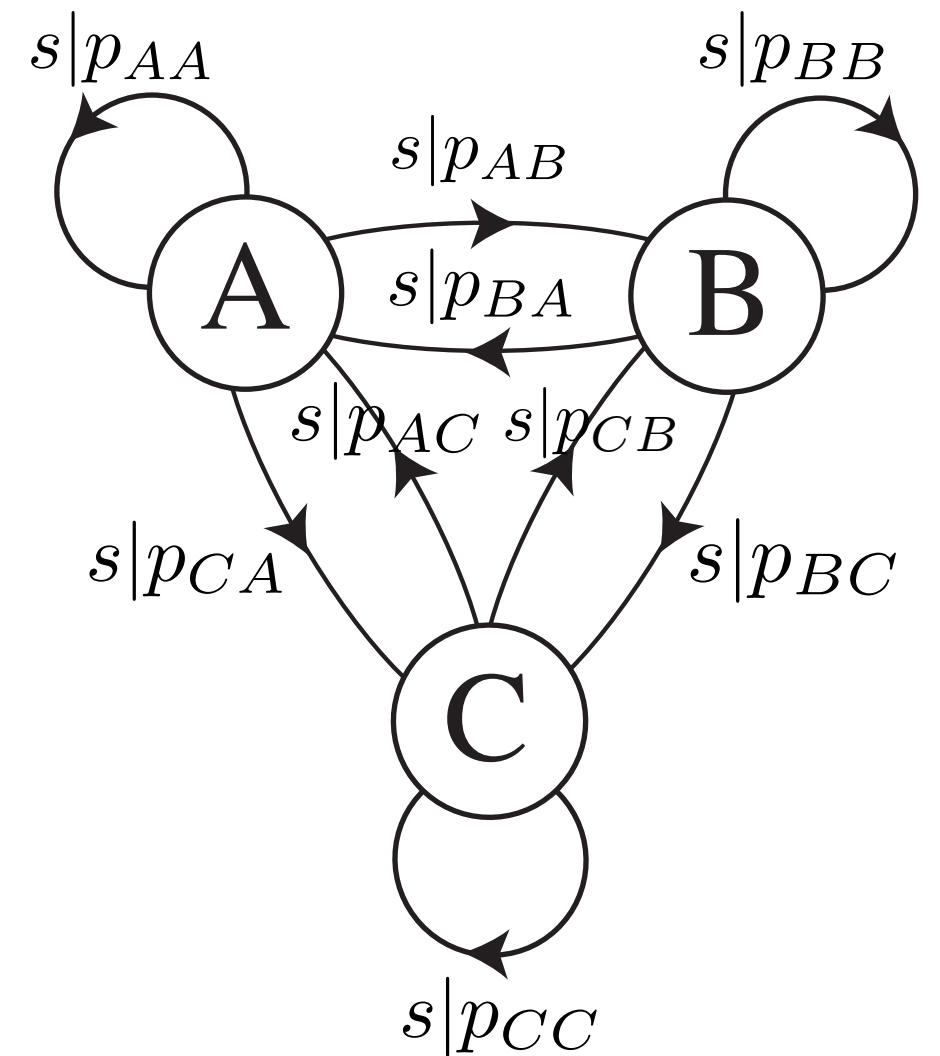
Internal: $\mathcal{A} = \{A, B, C\}$

$$T = \begin{pmatrix} p_{AA} & p_{AB} & p_{AC} \\ p_{BA} & p_{BB} & p_{BC} \\ p_{CA} & p_{CB} & p_{CC} \end{pmatrix}$$

Observed: $\mathcal{B} = \{0, 1\}$

$$T^{(s)} = \begin{pmatrix} p_{AA;s} & p_{AB;s} & p_{AC;s} \\ p_{BA;s} & p_{BB;s} & p_{BC;s} \\ p_{CA;s} & p_{CB;s} & p_{CC;s} \end{pmatrix}$$

$$p_{AA} = \sum_{s \in \mathcal{B}} p_{AA;s}$$



symbol | transition probability

Processes and Their Models ...

Models of Stochastic Processes ...

Hidden Markov Models of Processes ...

Internal states: $v \in \mathcal{A}$

Transition matrix: $T = \Pr(v'|v), v, v' \in \mathcal{A}$

Observation: **Symbol-labeled transition matrices**

$$T^{(s)} = \Pr(v', s|v), s \in \mathcal{B}$$

$$T = \sum_{s \in \mathcal{B}} T^{(s)}$$

Stochastic matrices:

$$\sum_j T_{ij} = \sum_j \sum_s T_{ij}^{(s)} = 1$$

Processes and Their Models ...

Models of Stochastic Processes ...

Hidden Markov Models ...

Internal state distribution: $\vec{p}_V = (p_1, p_2, \dots, p_k)$

Evolve internal distribution: $\vec{p}_n = \vec{p}_0 T^n$

State sequence distribution: $v^L = v_0 v_1 v_2 \dots v_{L-1}$

$$\Pr(v^L) = \pi(v_0) p(v_1 | v_0) p(v_2 | v_1) \cdots p(v_{L-1} | v_{L-2})$$

Observed sequence distribution: $s^L = s_0 s_1 s_2 \dots s_{L-1}$

$$\Pr(s^L) = \sum_{v^L \in \mathcal{A}^L} \pi(v_0) p(v_1, s_1 | v_0) p(v_2, s_2 | v_1) \cdots p(v_{L-1}, s_{L-1} | v_{L-2})$$

No longer 1-1 map between internal & observed sequences:
Multiple state sequences can produce *same* observed sequence.

Processes and Their Models ...

Models of Stochastic Processes ...

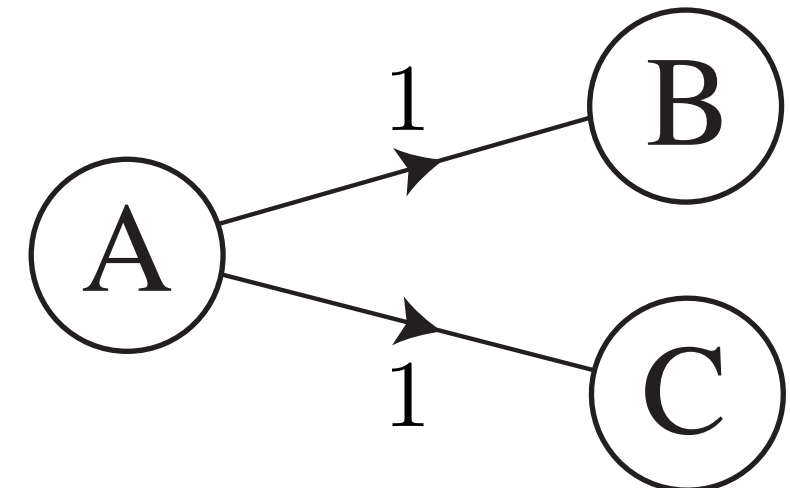
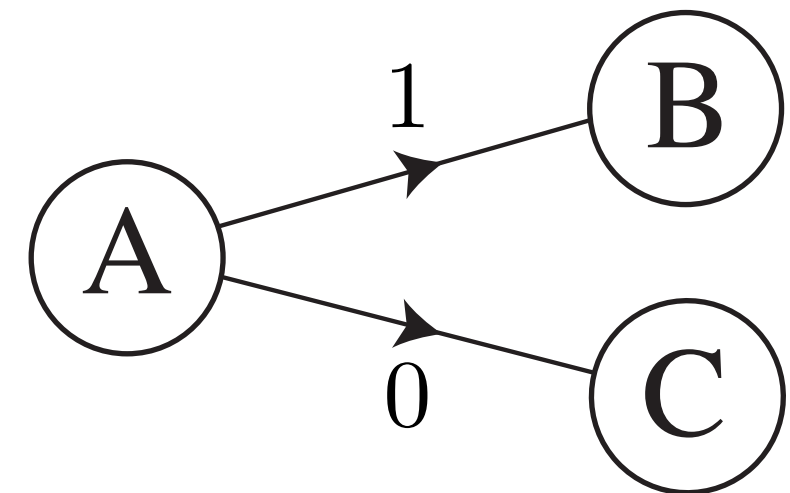
Types of Hidden Markov Model:

“**Unifilar**”: current state + symbol “determine” next state

$$\Pr(v'|v, s) = \begin{cases} 1 \\ 0 \end{cases}$$

$$\Pr(v', s|v) = p(s|v)$$

$$\Pr(v'|v) = \sum_{s \in \mathcal{A}} p(s|v)$$



“**Nonunifilar**”: no restriction

Multiple internal edge paths can generate same observed sequence.

Processes and Their Models ...

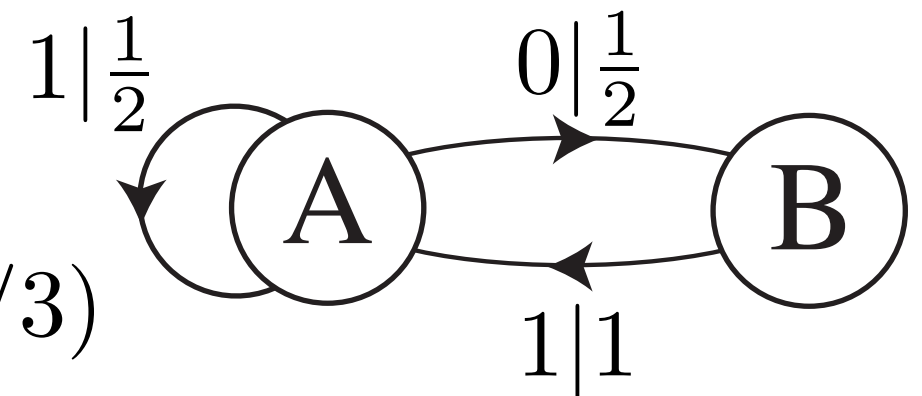
Models of Stochastic Processes ...

Example:

Golden Mean Process as a unifilar HMM:

Internal: $\mathcal{A} = \{A, B\}$

$$T = \begin{pmatrix} \frac{1}{2} & \frac{1}{2} \\ 1 & 0 \end{pmatrix} \quad \pi_V = (2/3, 1/3)$$



Observed: $\mathcal{B} = \{0, 1\}$

$$T^{(0)} = \begin{pmatrix} 0 & \frac{1}{2} \\ 0 & 0 \end{pmatrix} \quad T^{(1)} = \begin{pmatrix} \frac{1}{2} & 0 \\ 1 & 0 \end{pmatrix}$$

Initial ambiguity only: At most 2-to-1 mapping

$$BA^n = 1^n$$

$$AA^n = 1^n$$

$$\begin{aligned} \text{Sync'd: } s = 0 &\Rightarrow v = B \\ s = 1 &\Rightarrow v = A \end{aligned}$$

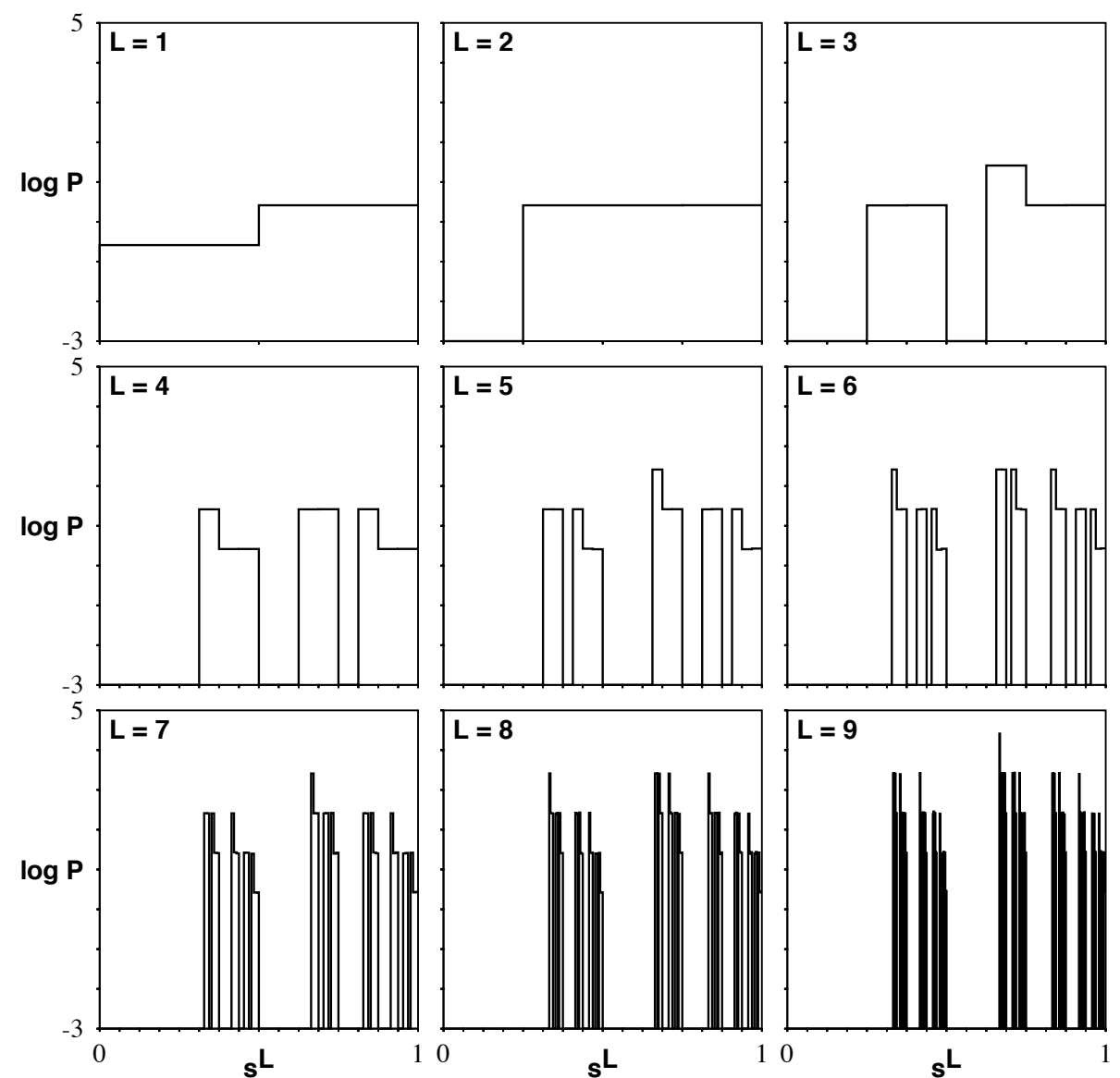
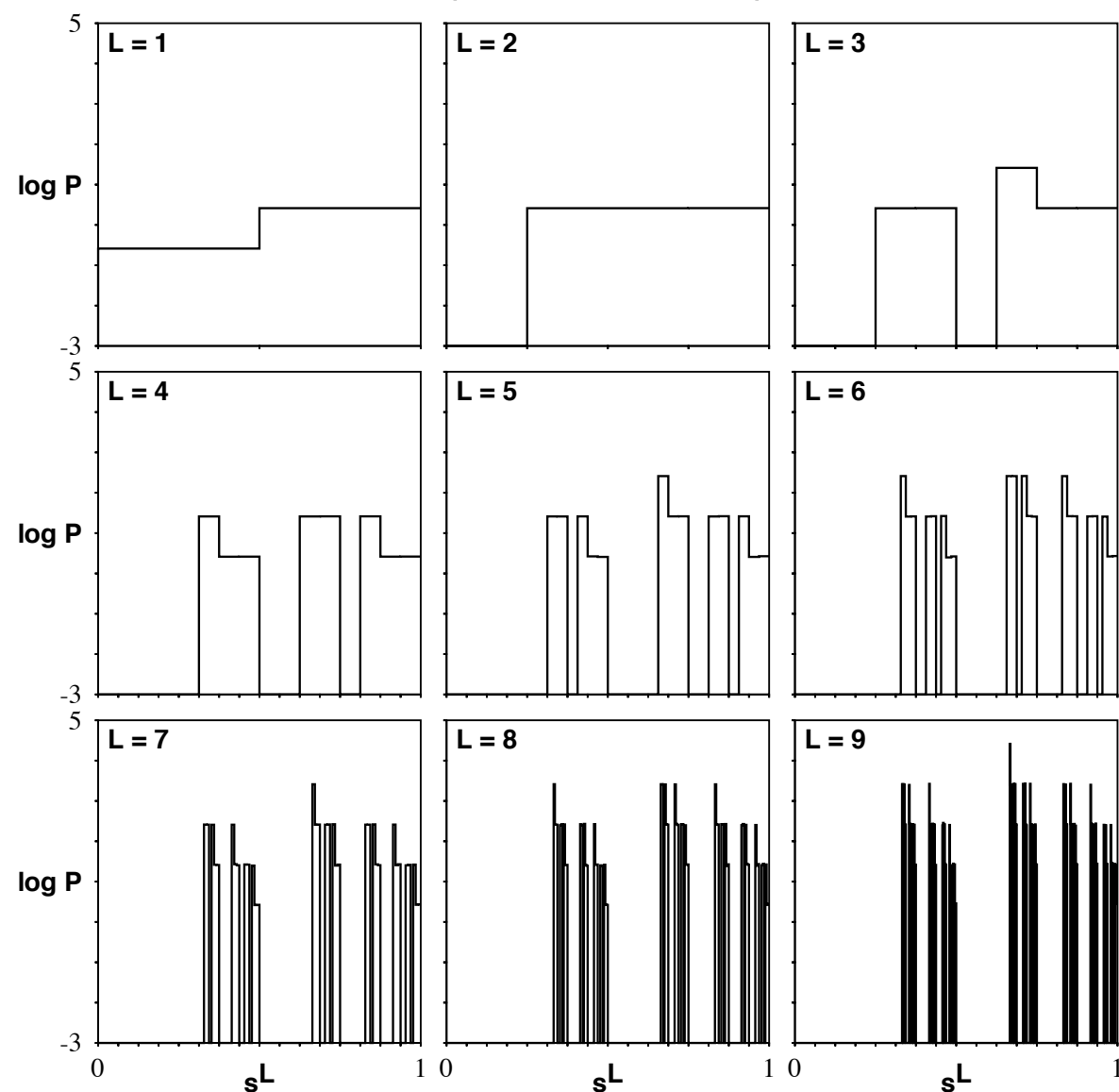
Irreducible forbidden words: $\mathcal{F} = \{00\}$

Processes and Their Models ...

Models of Stochastic Processes ...

Example:

Golden Mean Process ... Sequence distributions:
Internal state sequences Observed sequences
($A = 1; B = 0$)



Same!

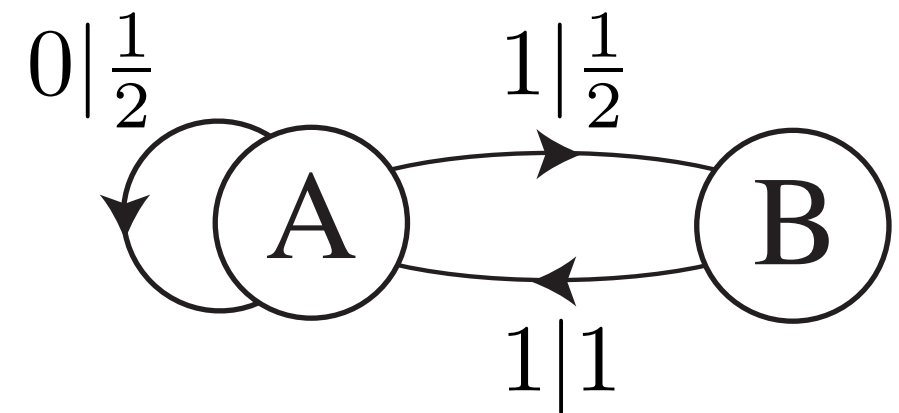
Processes and Their Models ...

Models of Stochastic Processes ...

Example: Even Process = Even #Is

As a unifilar HMM:

Internal (= GMP): $\mathcal{A} = \{A, B\}$



$$T = \begin{pmatrix} \frac{1}{2} & \frac{1}{2} \\ 1 & 0 \end{pmatrix} \quad \pi_V = (2/3, 1/3)$$

Observed: $\mathcal{B} = \{0, 1\}$

$$T^{(0)} = \begin{pmatrix} \frac{1}{2} & 0 \\ 0 & 0 \end{pmatrix} \quad T^{(1)} = \begin{pmatrix} 0 & \frac{1}{2} \\ 1 & 0 \end{pmatrix}$$

$$v^L = \dots AAB AAB ABA A \dots$$

$$s^L = \dots 011011110 \dots \quad s^L = \{\dots 01^{2n}0 \dots\}$$

Irreducible forbidden words: $\mathcal{F} = \{010, 01110, 0111110, \dots\}$

No finite-order Markov process can model the Even process!

Lesson: Finite Markov Chains are a subset of HMMs.

Processes and Their Models ...

Models of Stochastic Processes ...

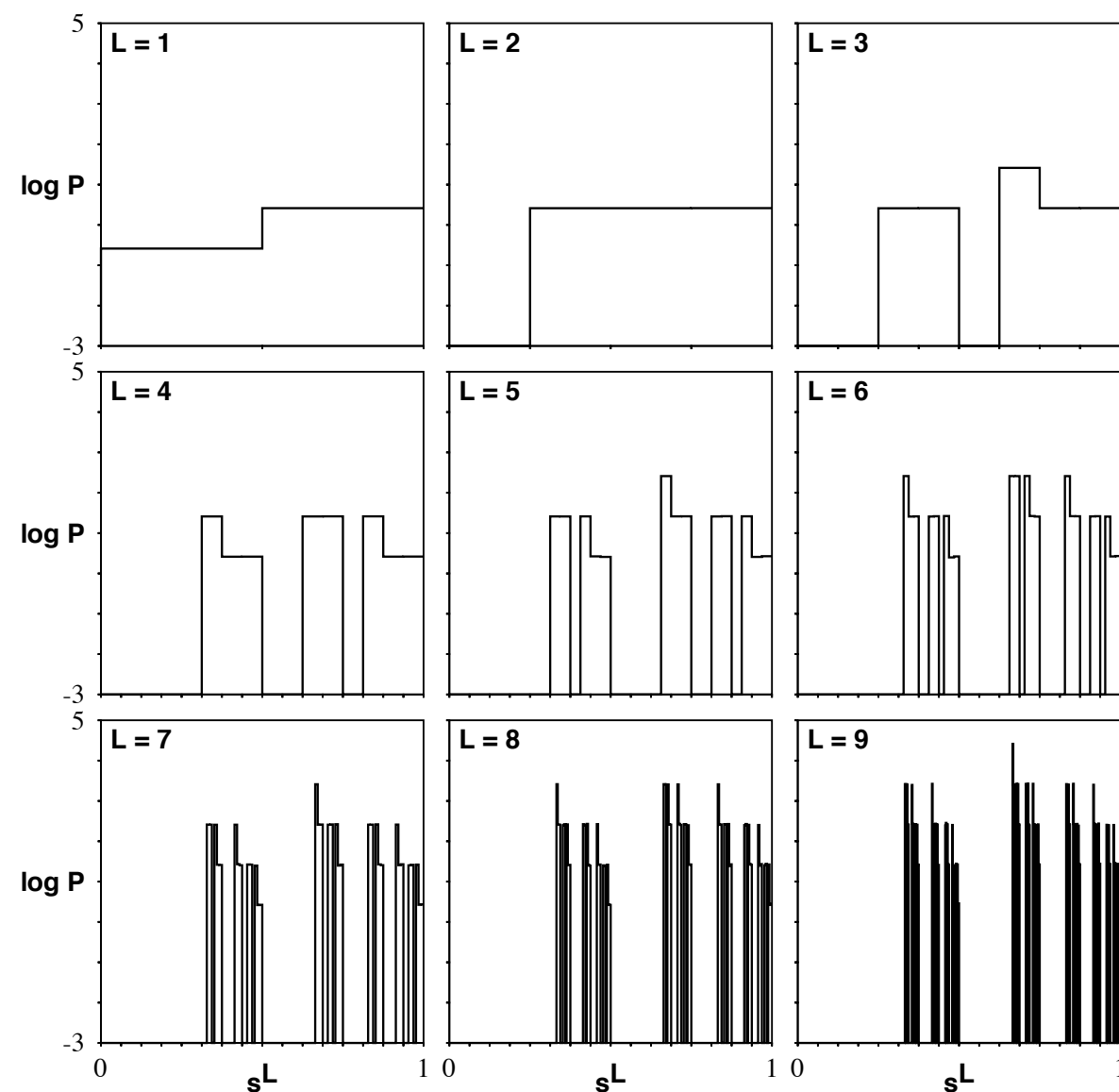
Example:

Even Process ... Sequence distributions:

Internal states (= GMP)

($A = 1; B = 0$)

Observed sequences



Rather different!

Processes and Their Models ...

Models of Stochastic Processes ...

Example:

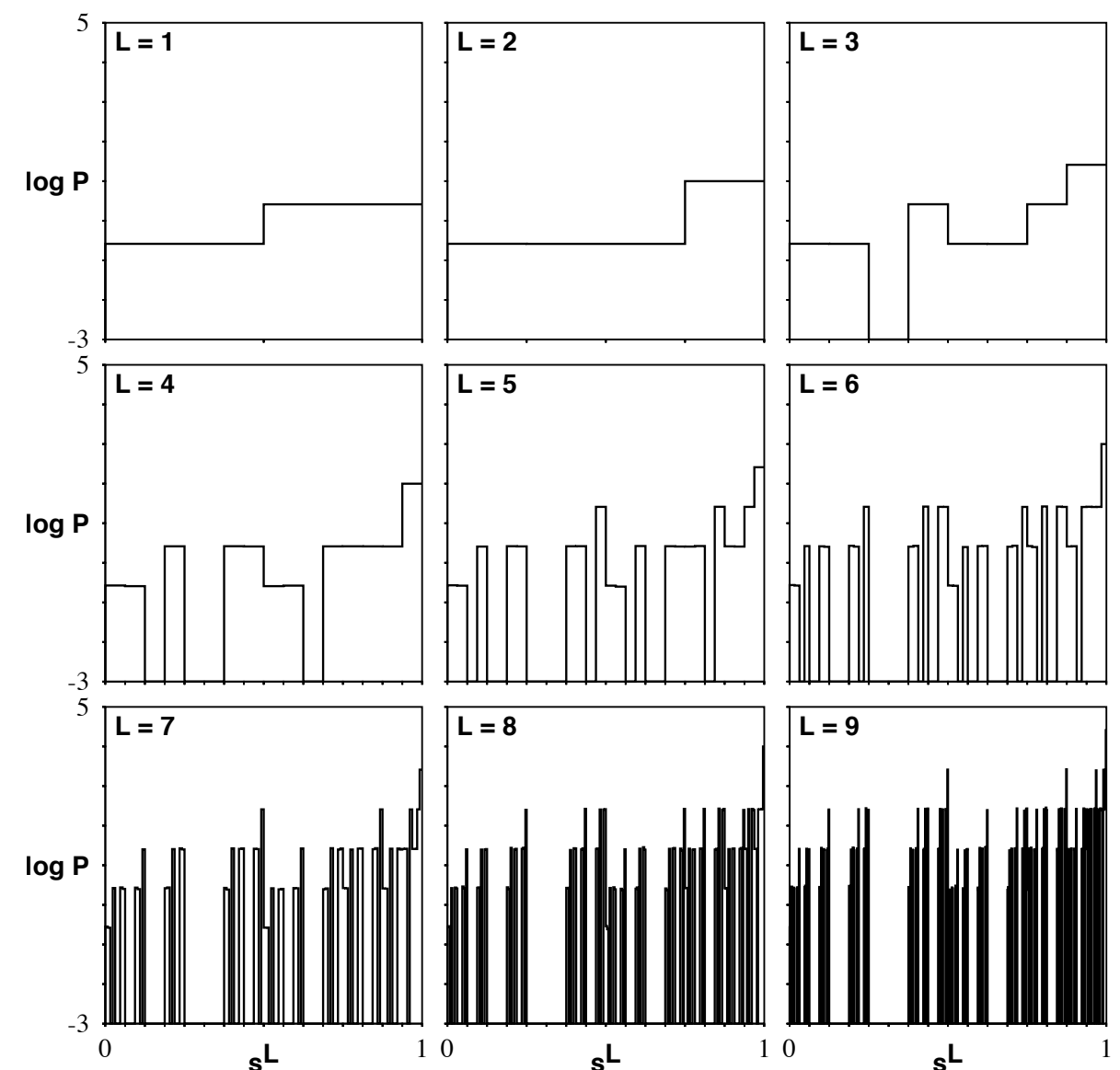
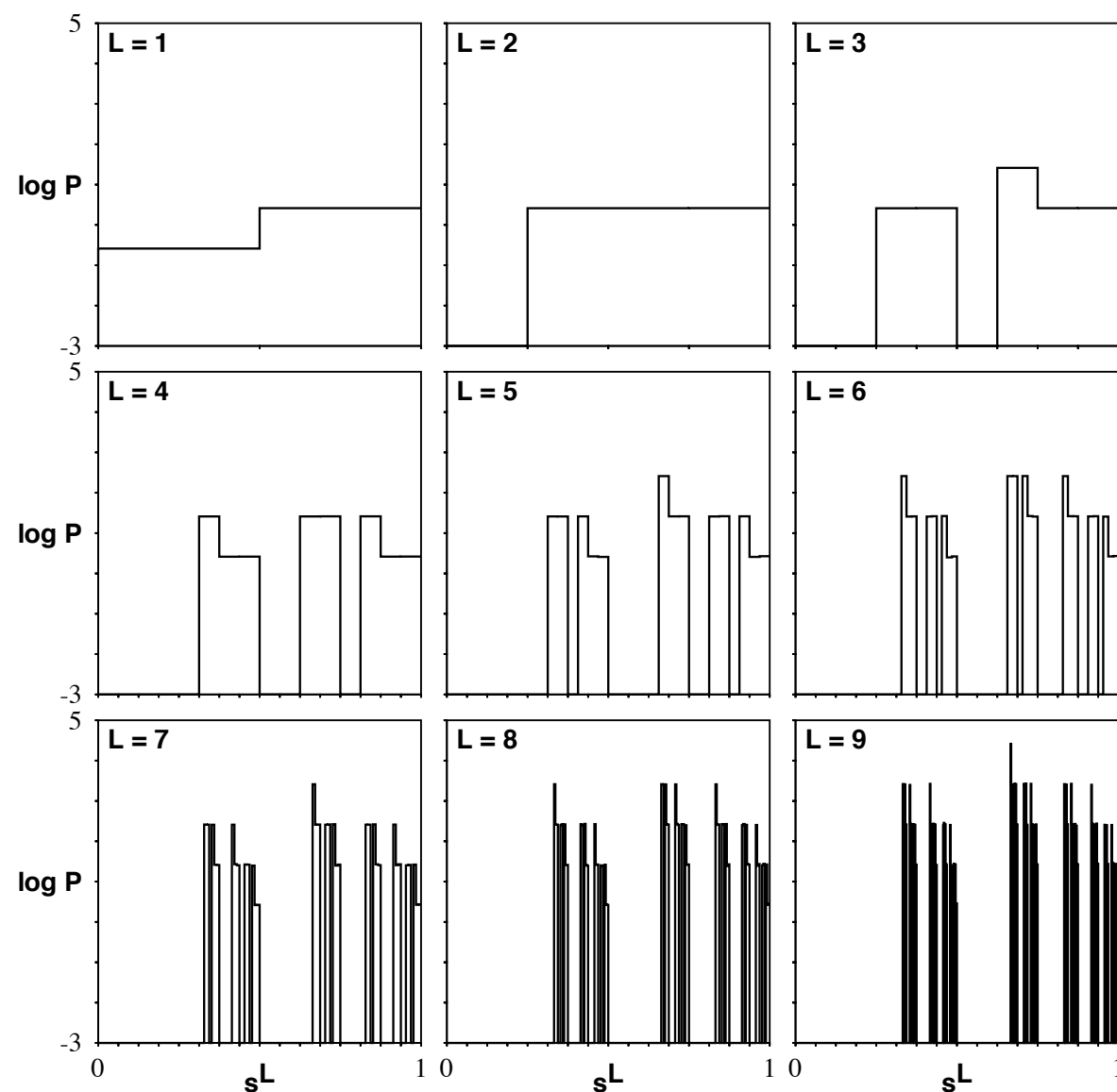
Even Process ...

Sequence distributions:

Internal states (= GMP)

Observed sequences

($A = 1; B = 0$)



Rather different!

Processes and Their Models ...

Models of Stochastic Processes ...

Example:

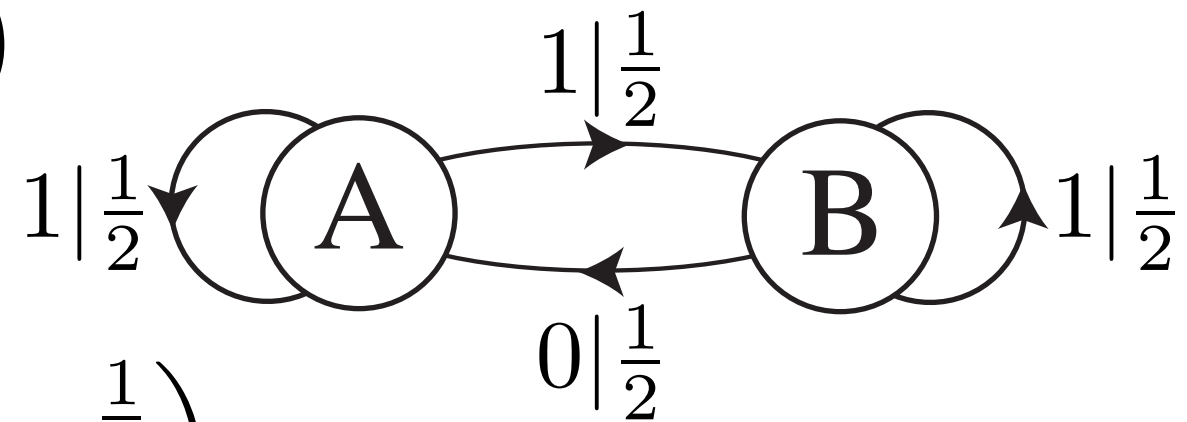
Simple Nonunifilar Source:

Internal (= Fair Coin): $\mathcal{A} = \{A, B\}$

$$T = \begin{pmatrix} \frac{1}{2} & \frac{1}{2} \\ \frac{1}{2} & \frac{1}{2} \end{pmatrix} \quad \pi_V = \left(\frac{1}{2}, \frac{1}{2}\right)$$

Observed: $\mathcal{B} = \{0, 1\}$

$$T^{(0)} = \begin{pmatrix} 0 & 0 \\ \frac{1}{2} & 0 \end{pmatrix} \quad T^{(1)} = \begin{pmatrix} \frac{1}{2} & \frac{1}{2} \\ 0 & \frac{1}{2} \end{pmatrix}$$



Many to one: $11111111 \Leftarrow \begin{cases} AAAAAAAAAA\dots \\ ABBBBBBBB\dots \\ AABBBBBBB\dots \\ AAABBBBBB\dots \\ \dots \\ BBBBBBBBBB\dots \end{cases}$

Is there a unifilar HMM presentation of the observed process?

Processes and Their Models ...

Models of Stochastic Processes ...

Example:

Simple Nonuniform Process ...

Internal states (= Fair coin)

(A = 1; B = 0)

Observed sequences

Processes and Their Models ...

Models of Stochastic Processes ...

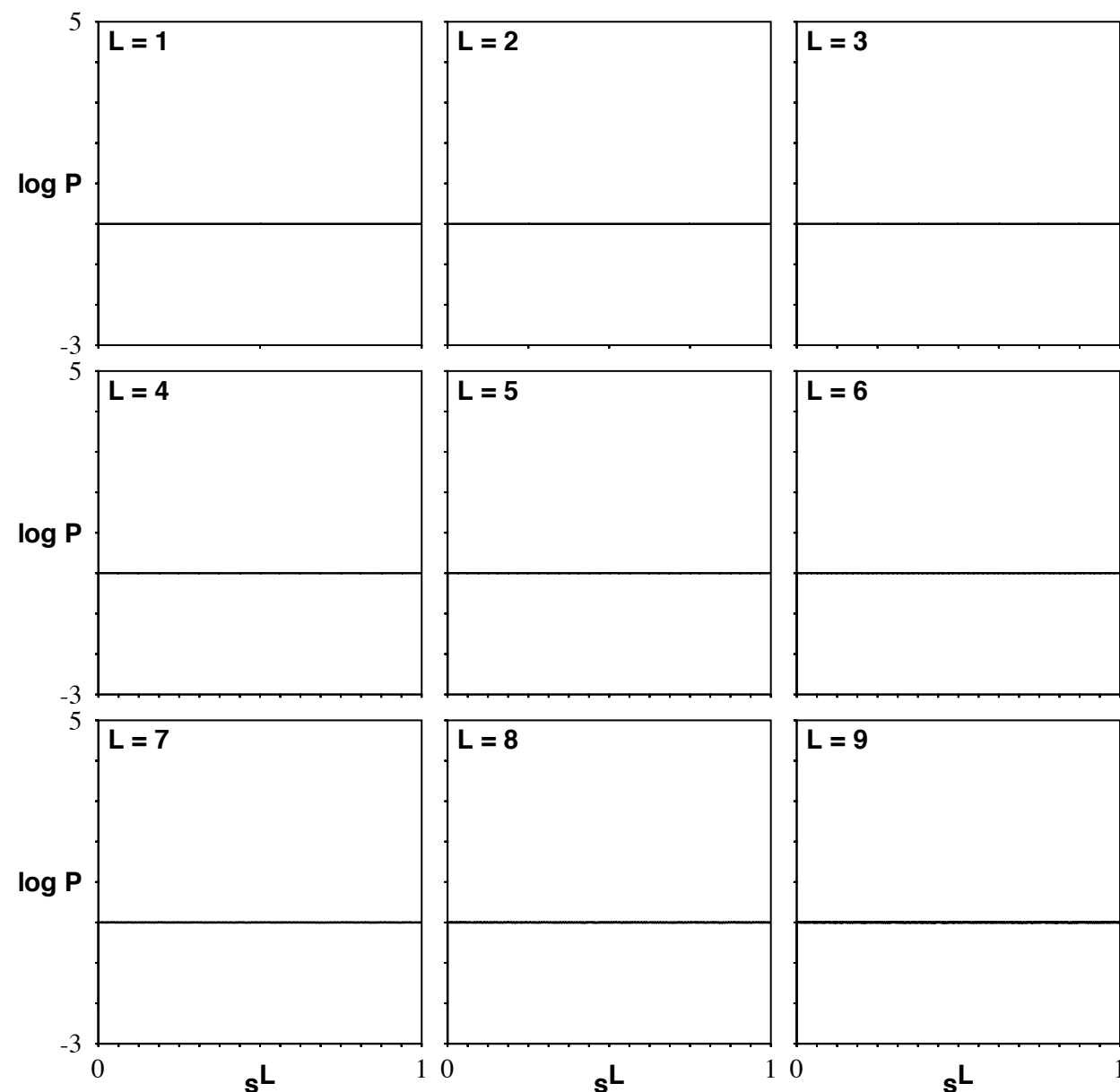
Example:

Simple Nonunifilar Process ...

Internal states (= Fair coin)

(A = 1; B = 0)

Observed sequences



Processes and Their Models ...

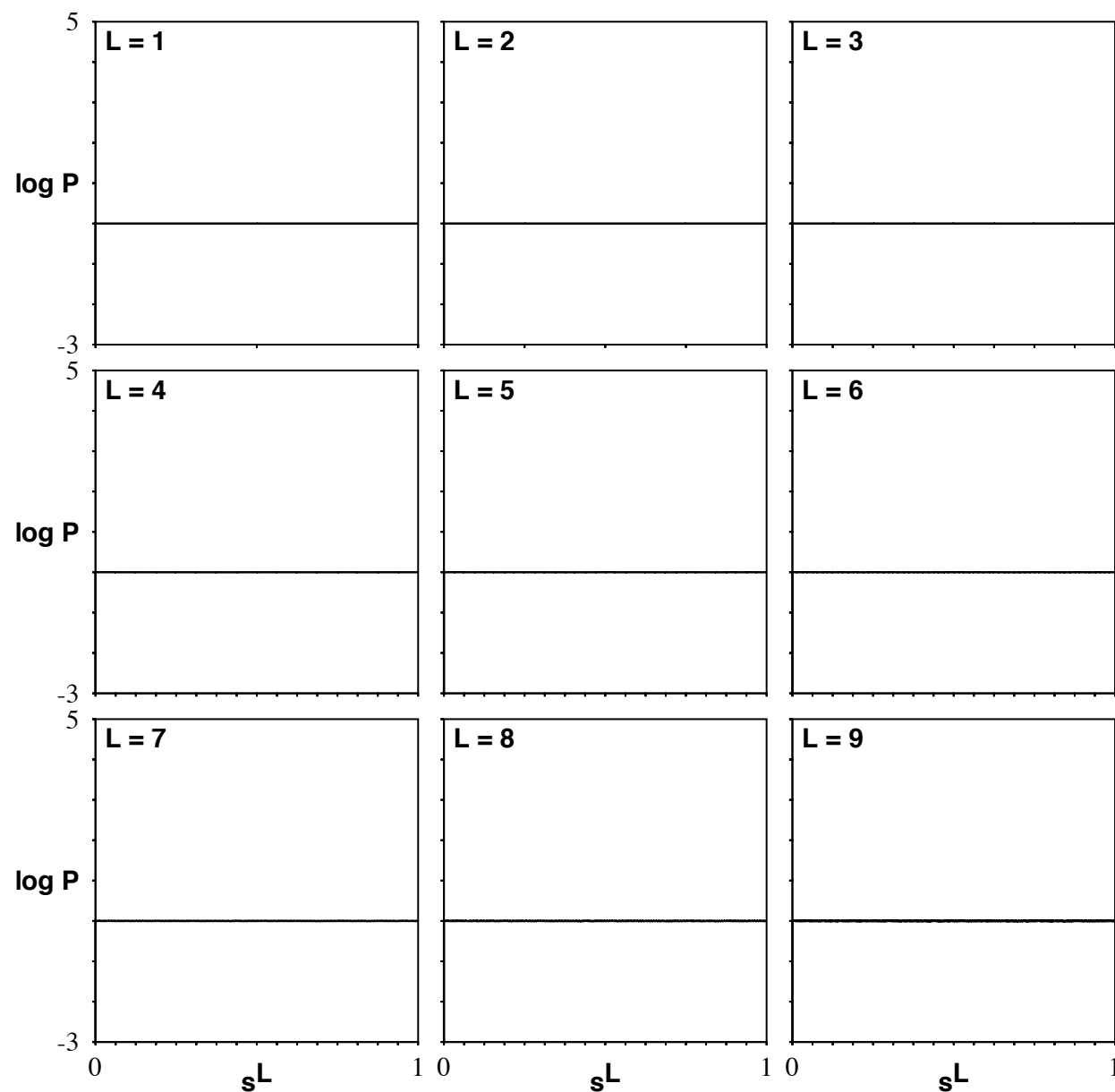
Models of Stochastic Processes ...

Example:

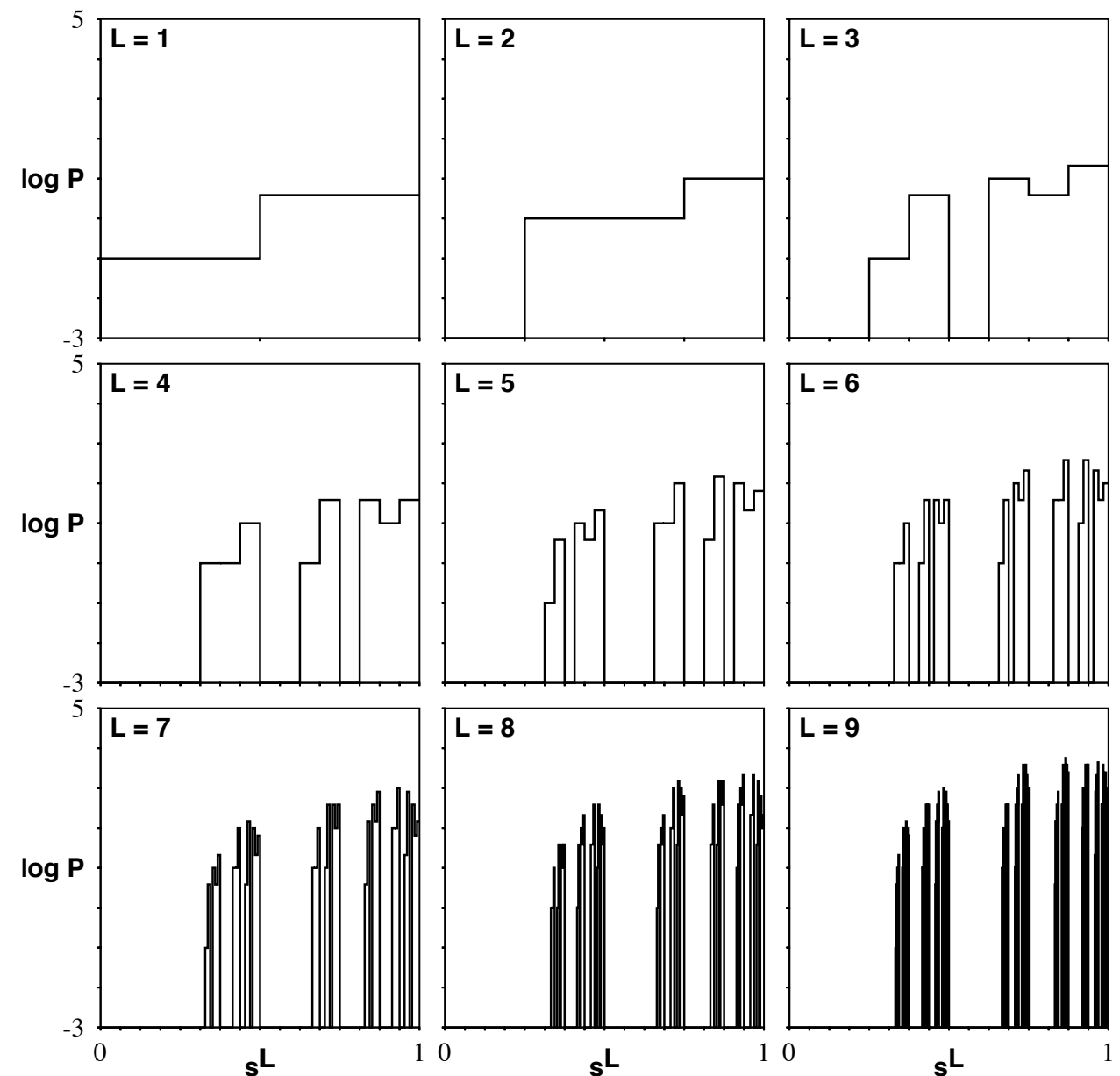
Simple Nonuniform Process ...

Internal states (= Fair coin)

($A = 1; B = 0$)



Observed sequences



Processes and Their Models ...

What to do with all of this complicatedness?

1. Information theory for general stochastic processes

2. Measures of complexity

3. Optimal models and how to build them

Labs:

Track these topics closely.

Ryan will give a tour in evening session.

Work through them on your own.

Information!

Sources of Information:

Apparent randomness:

- Uncontrolled initial conditions

- Actively generated: Deterministic chaos

Hidden regularity:

- Ignorance of forces

- Limited capacity to model structure

Why information?

1. Accounts for any type of co-relation
 - Statistical correlation \sim linear only
 - Information measures nonlinear correlation
2. Broadly applicable:
 - Many systems don't have “energy”, physical modeling precluded
 - Information defined: social, biological, engineering, ... systems
3. Comparable units across different systems:
 - Distance v. volts v. populations v. energy v. ...
4. Probability theory \sim Statistics \sim Information
5. Complex systems:
 - Emergent patterns!
 - We don't know these ahead of time

Information ...

Information as uncertainty and surprise:

Observe something unexpected:
Gain information

Bateson: “A difference that makes a difference”

Information ...

Information as uncertainty and surprise ...

How to formalize?

Shannon's approach:

A measure of surprise.

Connection with Boltzmann's thermodynamic entropy

Self-information of an event $\propto -\log \text{Pr}(\text{event})$.

Predictable: No surprise $-\log 1 = 0$

Completely unpredictable: Maximally surprised

$$-\log \frac{1}{\text{Number of Events}} = \log(\text{Number of Events})$$

Information ...

Shannon Entropy: $X \sim P$

$$x \in \mathcal{X} = \{1, 2, \dots, k\}$$
$$P = \{\Pr(x = 1), \Pr(x = 2), \dots\}$$

$$H(X) = - \sum_{x \in \mathcal{X}} p(x) \log_2 p(x)$$

Note: $0 \log 0 = 0$

$$H(X) = \langle -\log_2 p(x) \rangle$$

Units:

Log base 2: $H(X) = [\text{bits}]$

Natural log: $H(X) = [\text{nats}]$

Properties:

1. **Positivity:** $H(X) \geq 0$

2. **Predictive:** $H(X) = 0 \Leftrightarrow p(x) = 1$ for one and only one x

3. **Random:** $H(X) = \log_2 k \Leftrightarrow p(x) = U(x) = 1/k$

Information ...

Examples: Binary random variable X

$$\mathcal{X} = \{0, 1\} \quad \Pr(1) = p \text{ \& } \Pr(0) = 1 - p$$

$H(X)$?

Binary entropy function:

$$H(p) = -p \log_2 p - (1 - p) \log_2 (1 - p)$$

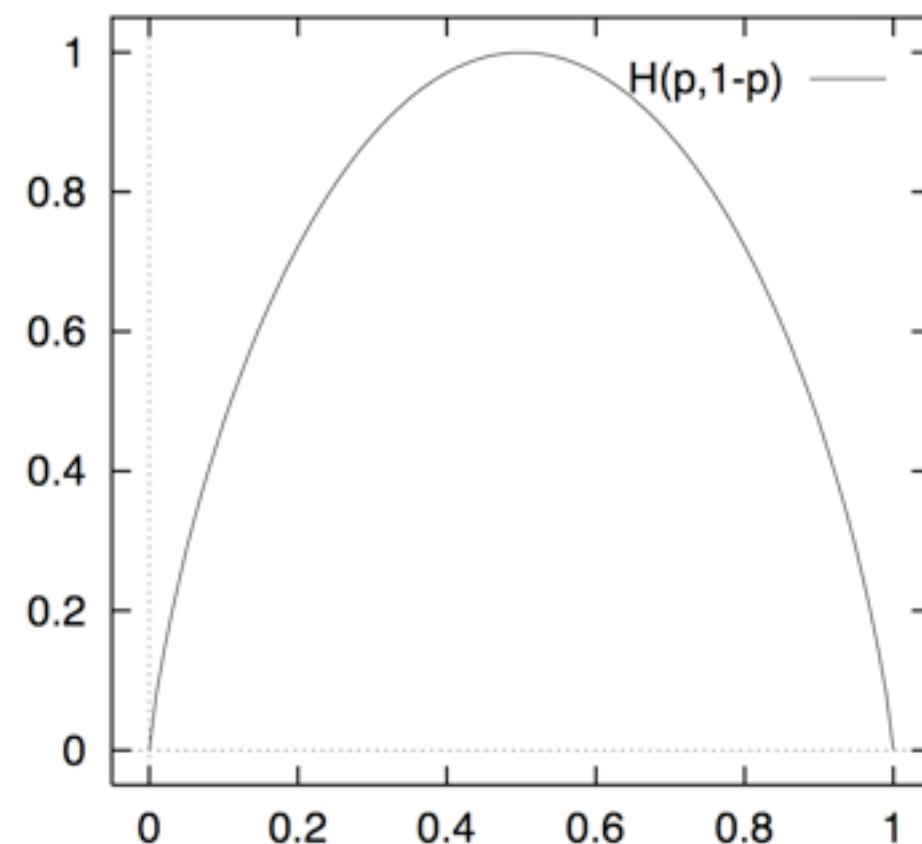
Fair coin: $p = \frac{1}{2}$

$$H(p) = 1 \text{ bit}$$

Completely biased coin: $p = 0$ (or 1)

$$H(p) = 0 \text{ bits}$$

Recall: $0 \cdot \log 0 = 0$



Information ...

Example: Independent, Identically Distributed (IID) Process
over four events

$$\mathcal{X} = \{a, b, c, d\} \quad \Pr(X) = \left(\frac{1}{2}, \frac{1}{4}, \frac{1}{8}, \frac{1}{8}\right)$$

Entropy: $H(X) = \frac{7}{4}$ bits

Number of questions to identify the event?

$x = a$? (must always ask at least one question)

$x = b$? (this is necessary only half the time)

$x = c$? (only get this far a quarter of the time)

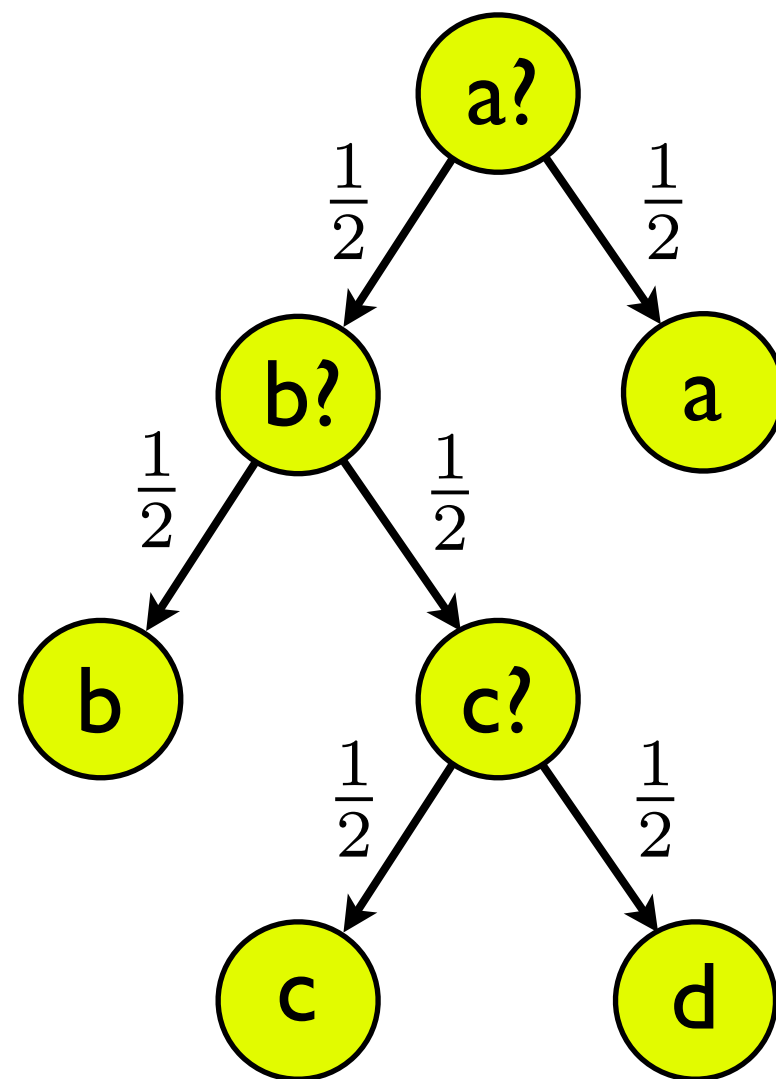
Average number: $1 \cdot 1 + 1 \cdot \frac{1}{2} + 1 \cdot \frac{1}{4} = 1.75$ questions

Interpretation? Optimal way to ask questions.

Information ...

Example: IID Process over four events ...

Average number: $1 \cdot 1 + 1 \cdot \frac{1}{2} + 1 \cdot \frac{1}{4} = 1.75$ questions



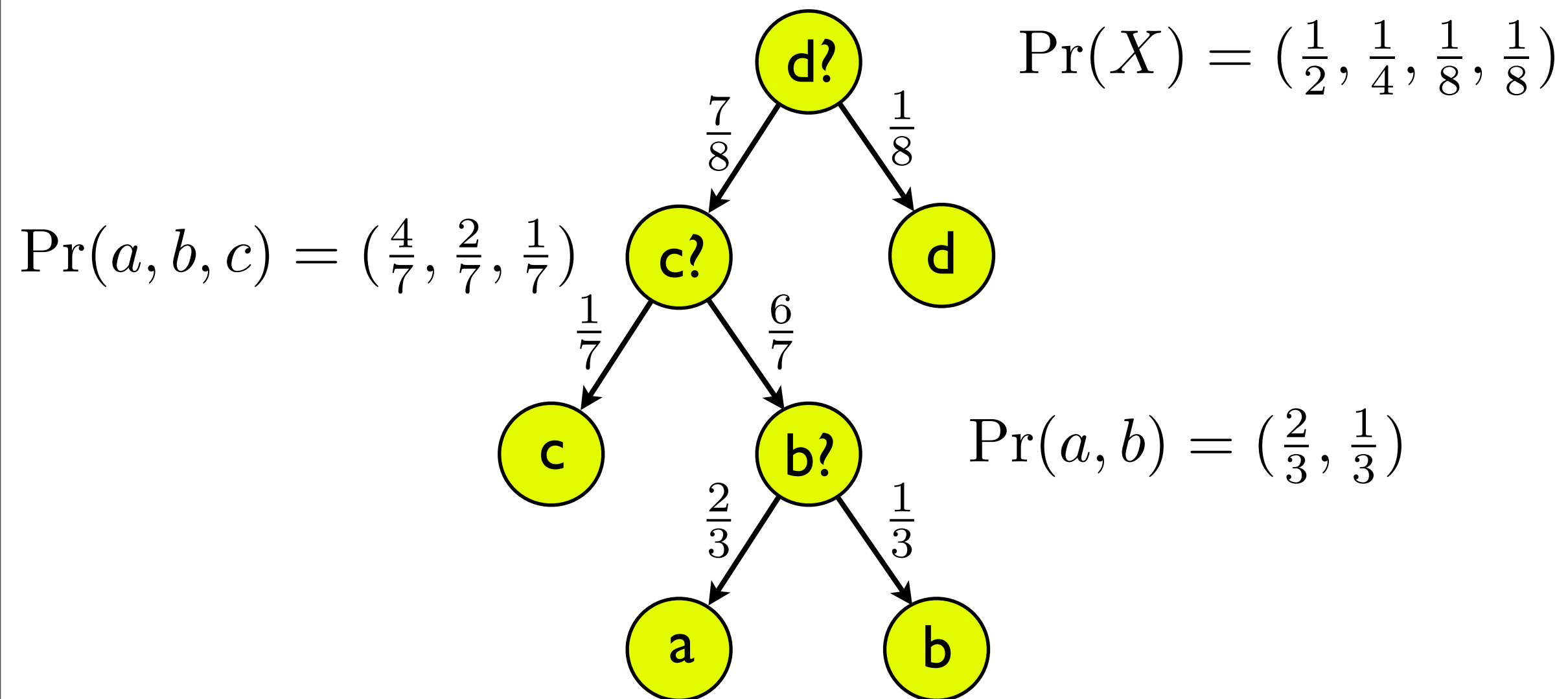
$$\Pr(X) = \left(\frac{1}{2}, \frac{1}{4}, \frac{1}{8}, \frac{1}{8}\right)$$

Information ...

Example: IID Process over four events ...

Query in a different order:

Average number: $1 \cdot 1 + 1 \cdot \frac{7}{8} + 1 \cdot \frac{6}{7} \approx 2.7$ questions



Information ...

Example: IID Process over four events

Entropy: $H(X) = \frac{7}{4}$ bits

At each stage, ask questions that are most informative.

Choose partitions of event space that give “most random” measurements.

Theorem:

Entropy gives the smallest number of questions to identify an event, on average.

Information ...

Interpretations of Shannon Entropy:

Observer's *degree of surprise* in outcome of a random variable

Uncertainty *in* random variable

Information required to *describe* random variable

A measure of *flatness* of a distribution

Information ...

Two random variables: $(X, Y) \sim p(x, y)$

Joint Entropy: Average uncertainty in X and Y occurring

$$H(X, Y) = - \sum_{x \in \mathcal{X}} \sum_{y \in \mathcal{Y}} p(x, y) \log_2 p(x, y)$$

Independent:

$$X \perp Y \Rightarrow H(X, Y) = H(X) + H(Y)$$

Conditional Entropy: Average uncertainty in X , knowing Y

$$H(X|Y) = - \sum_{x \in \mathcal{X}} \sum_{y \in \mathcal{Y}} p(x, y) \log_2 p(x|y)$$

$$H(X|Y) = H(X, Y) - H(Y)$$

Not symmetric: $H(X|Y) \neq H(Y|X)$

Information ...

Common Information Between Two Random Variables:

$$X \sim p(x) \text{ \& } Y \sim p(y)$$

$$(X, Y) \sim p(x, y)$$

Mutual Information:

$$I(X; Y) = \mathcal{D}(P(x, y) || P(x)P(y))$$

$$I(X; Y) = \sum_{(x, y) \in \mathcal{X} \times \mathcal{Y}} p(x, y) \log_2 \frac{p(x, y)}{p(x)p(y)}$$

Information ...

Mutual Information ...

Properties:

$$(1) \ I(X; Y) \geq 0$$

$$(2) \ I(X; Y) = I(Y; X)$$

$$(3) \ I(X; Y) = H(X) - H(X|Y)$$

$$(4) \ I(X; Y) = H(X) + H(Y) - H(X, Y)$$

$$(5) \ I(X; X) = H(X)$$

$$(6) \ X \perp Y \Rightarrow I(X; Y) = 0$$

Interpretations:

Information one variable has about another

Information shared between two variables

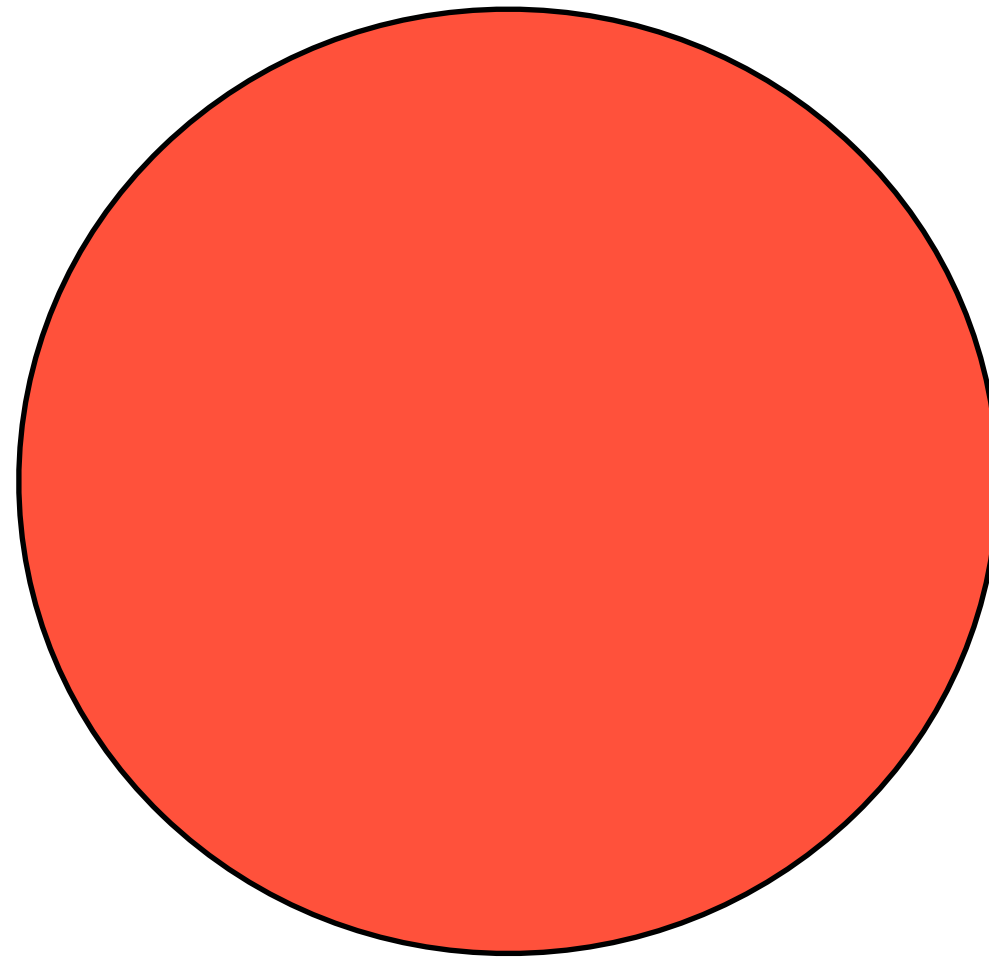
Measure of dependence between two variables

Information ...

Event Space Relationships of Information Quantifiers:

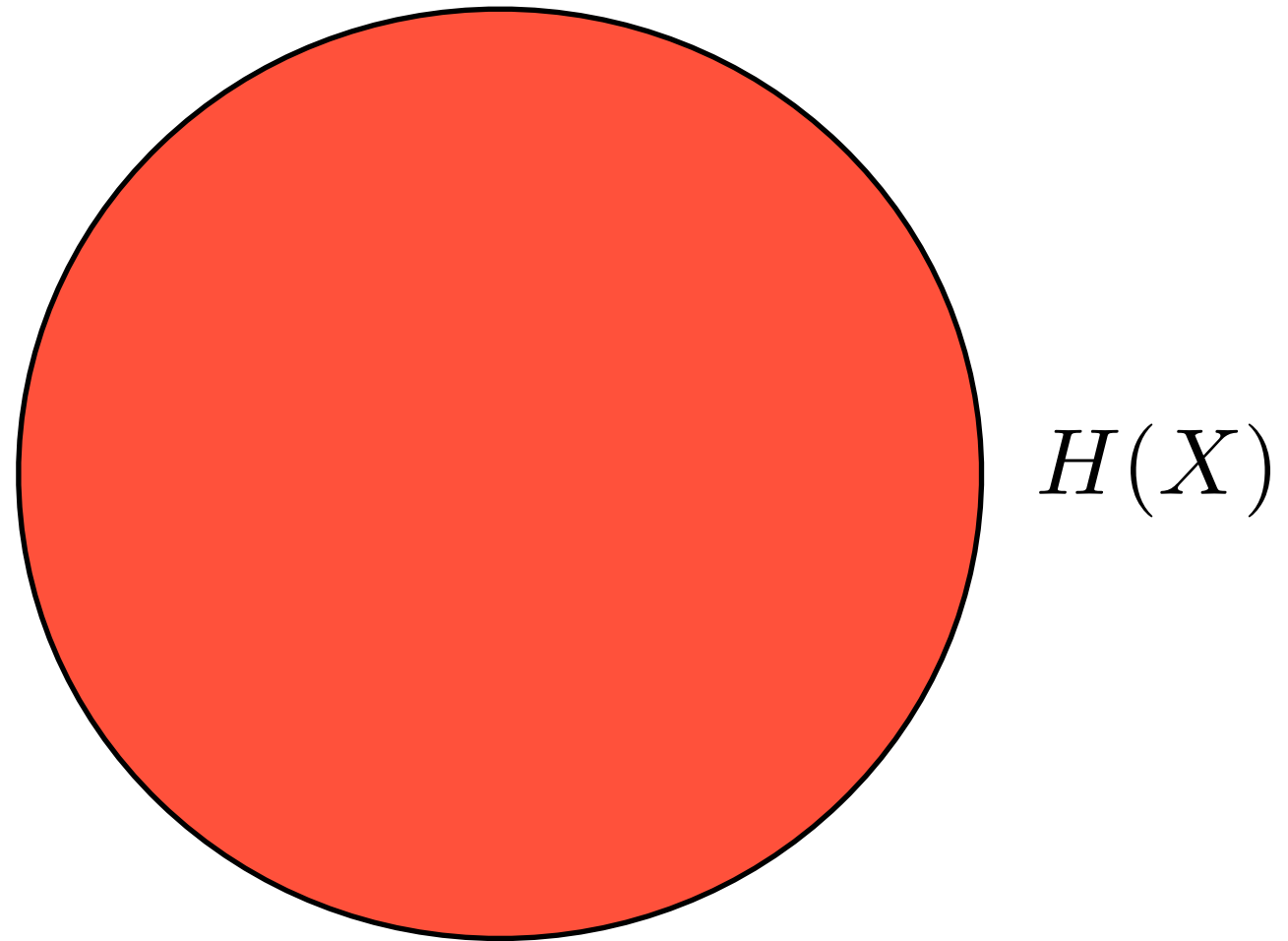
Information ...

Event Space Relationships of Information Quantifiers:



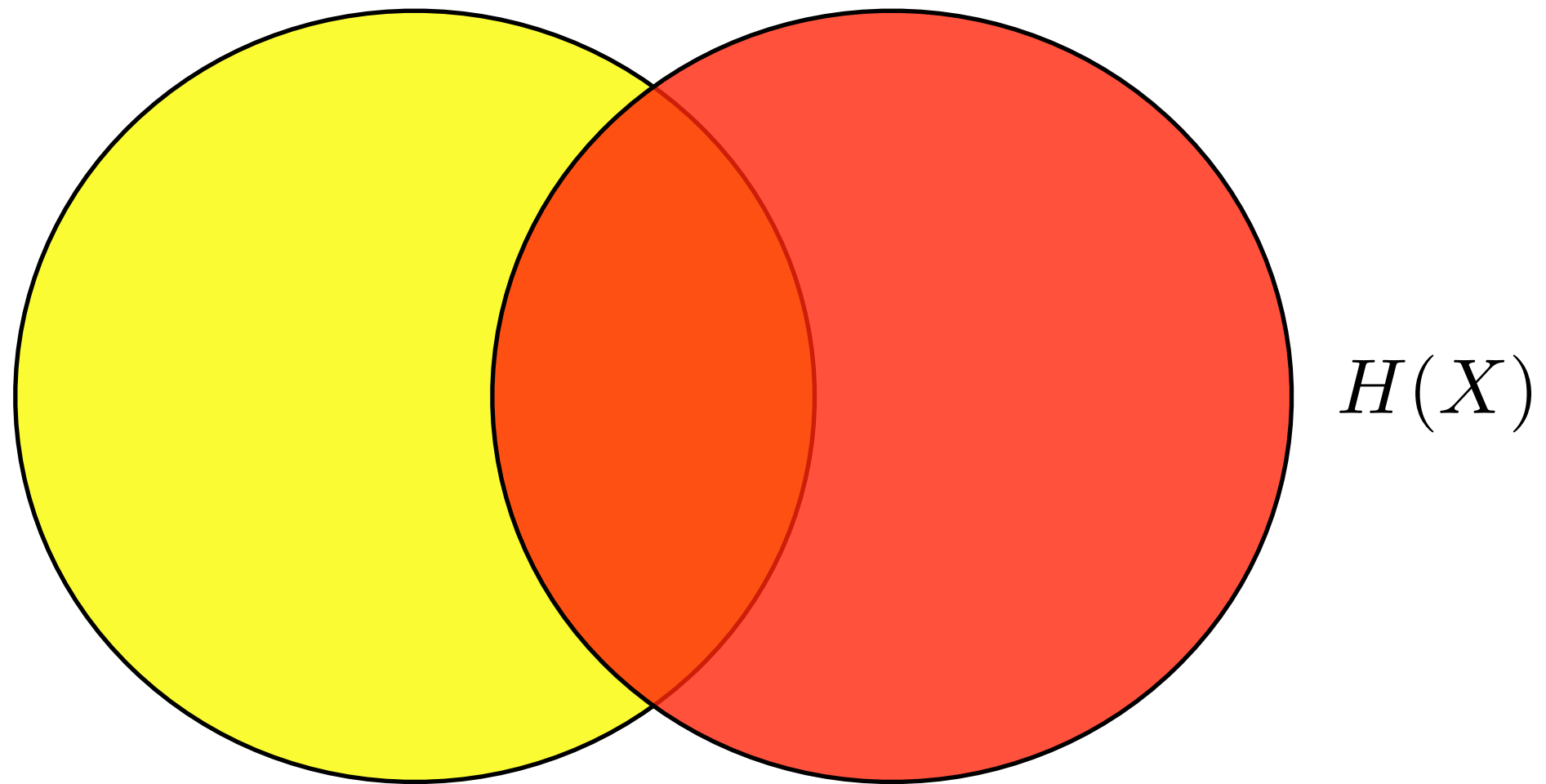
Information ...

Event Space Relationships of Information Quantifiers:



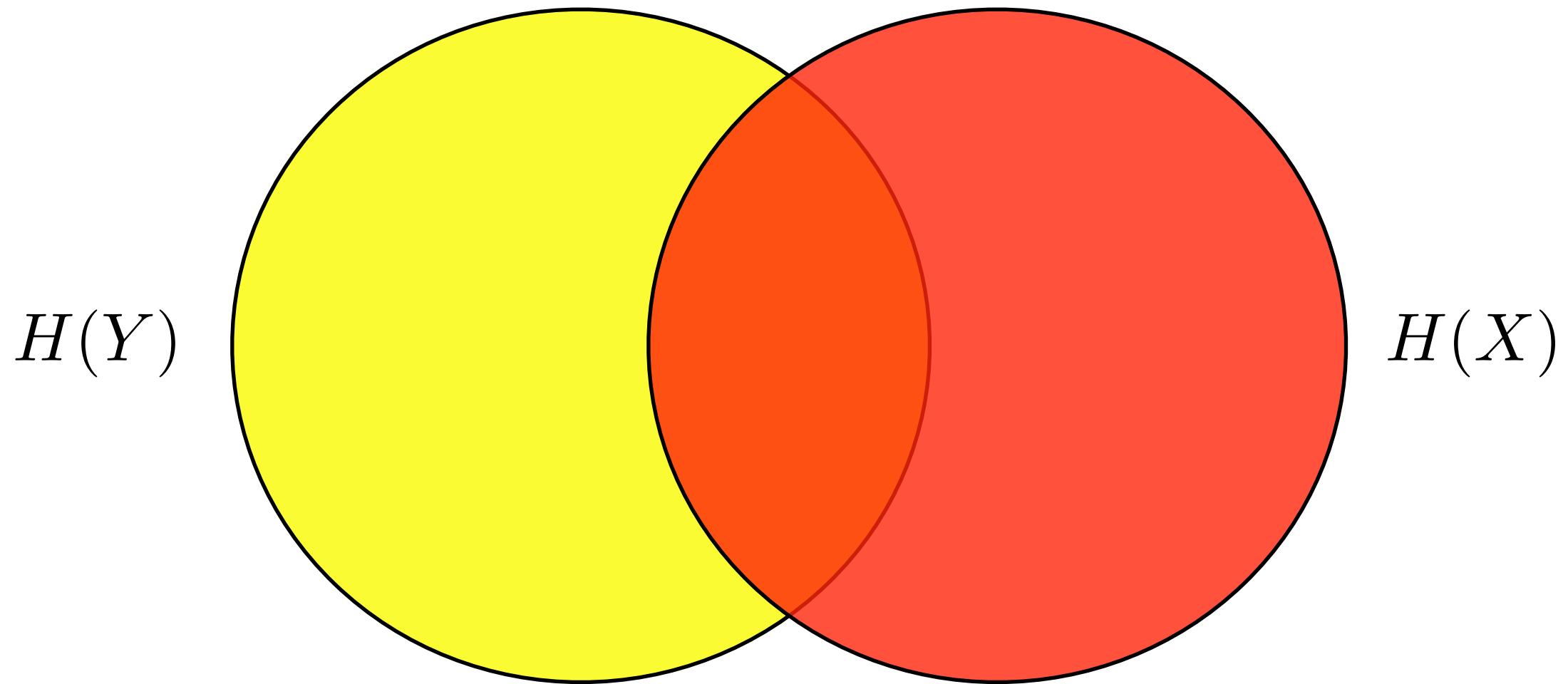
Information ...

Event Space Relationships of Information Quantifiers:



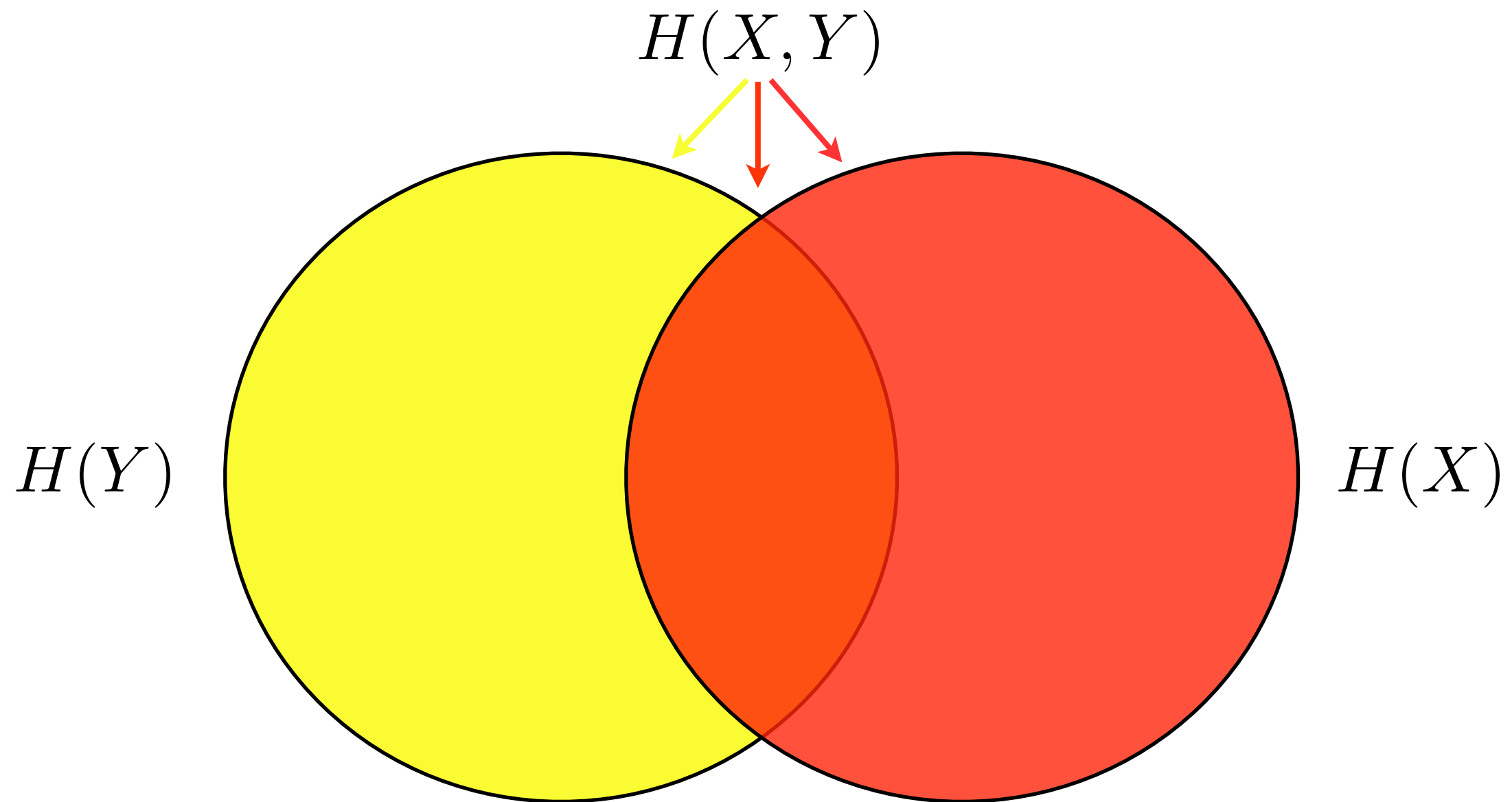
Information ...

Event Space Relationships of Information Quantifiers:



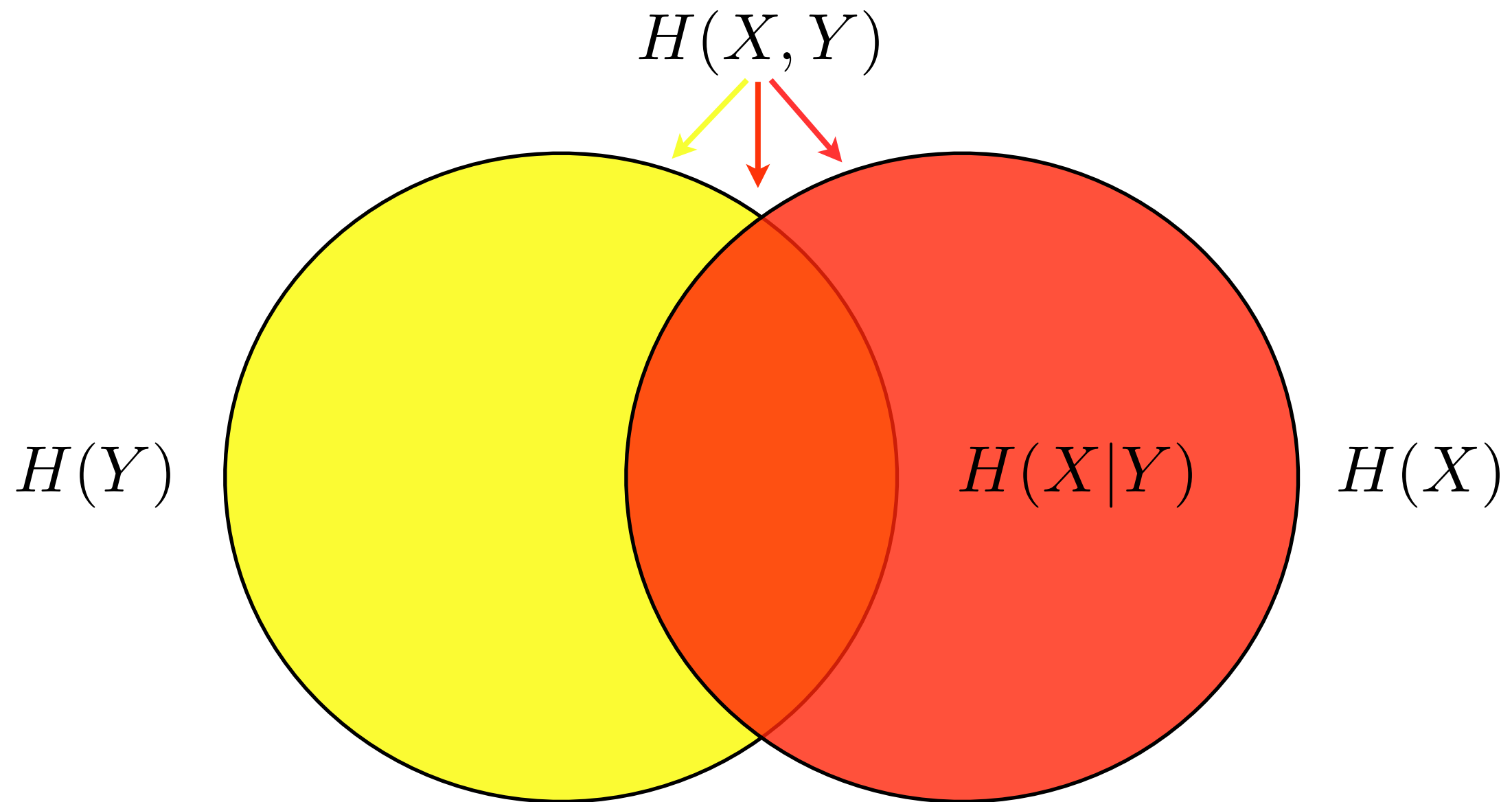
Information ...

Event Space Relationships of Information Quantifiers:



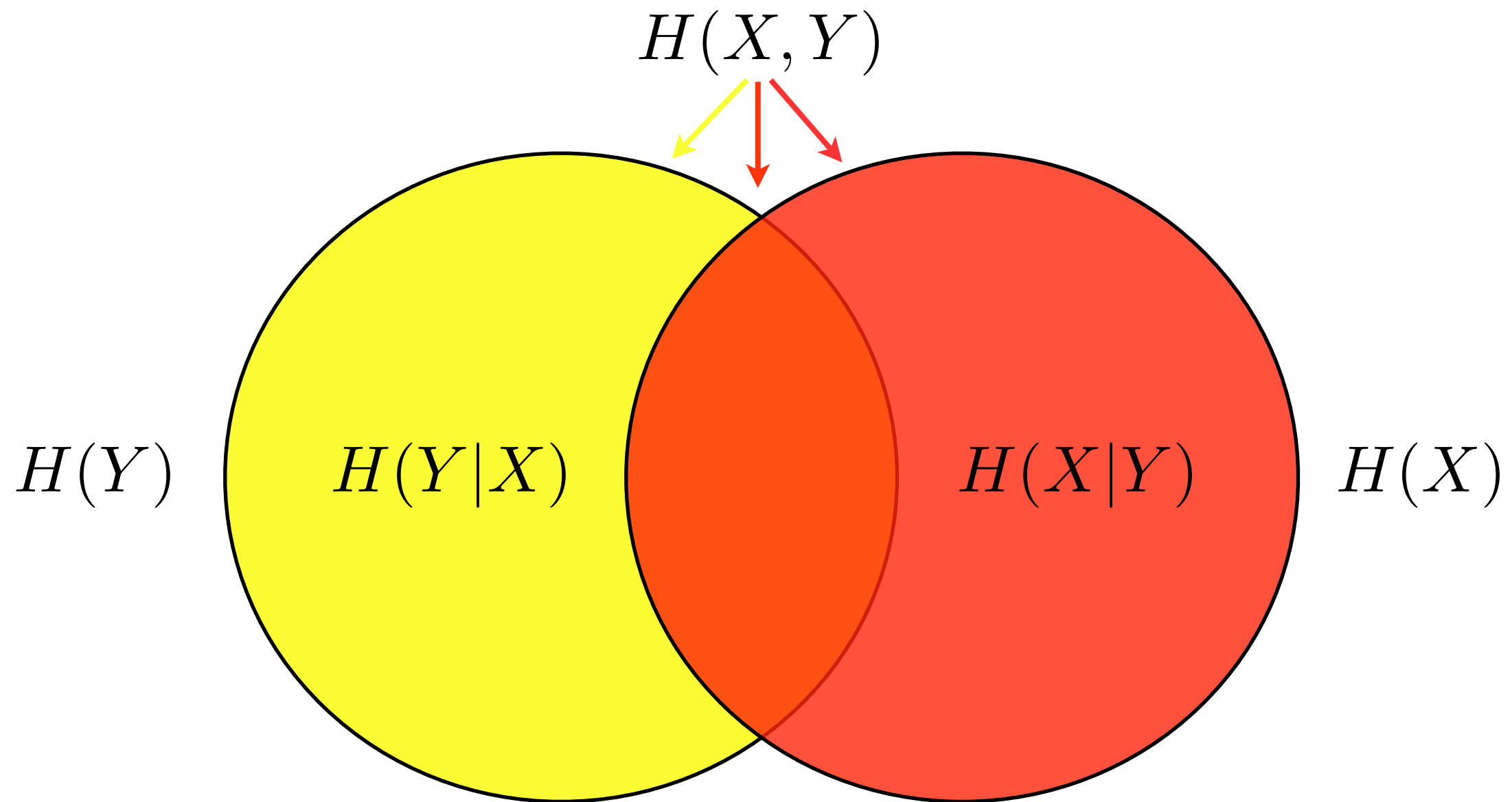
Information ...

Event Space Relationships of Information Quantifiers:



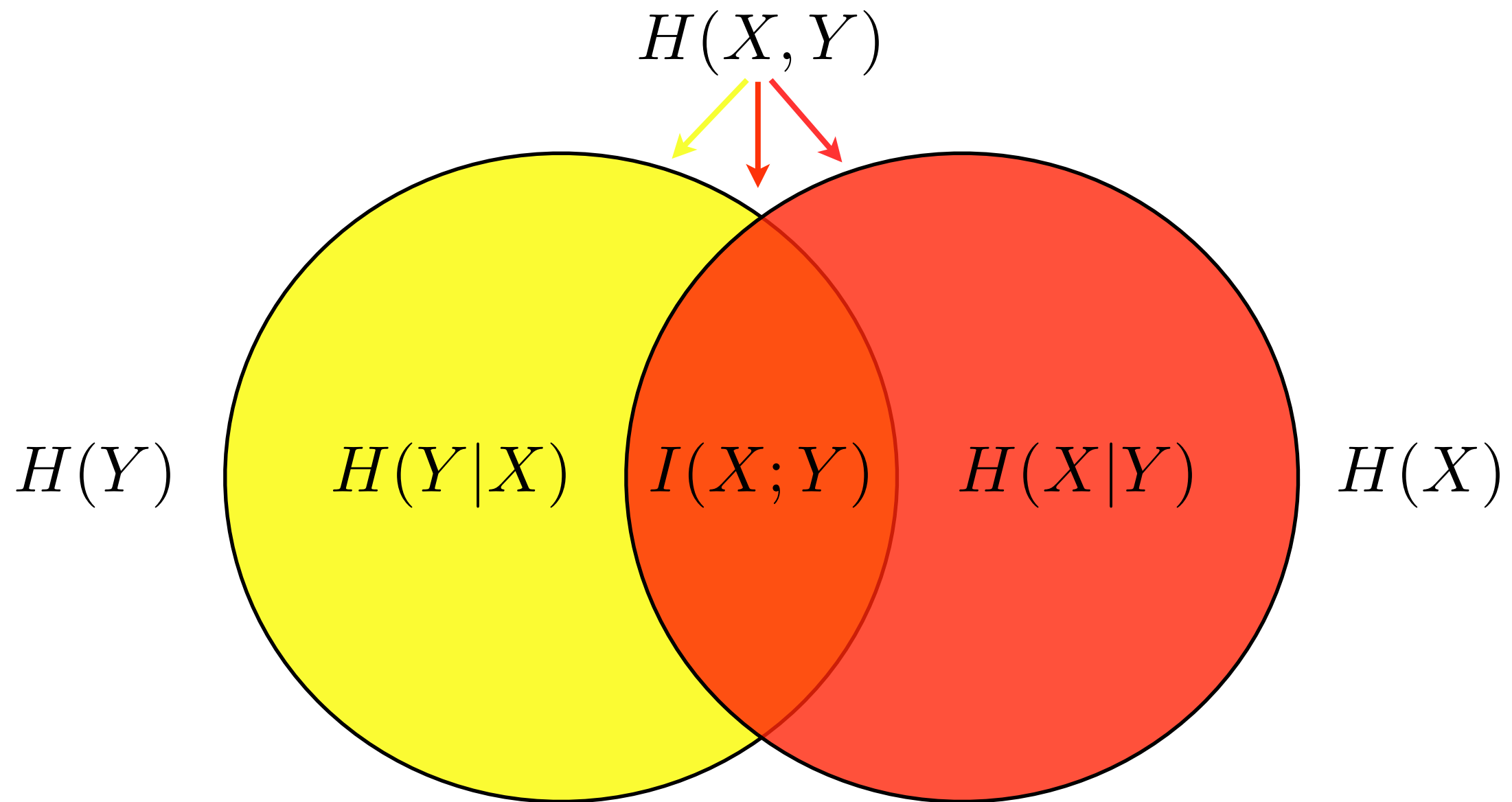
Information ...

Event Space Relationships of Information Quantifiers:



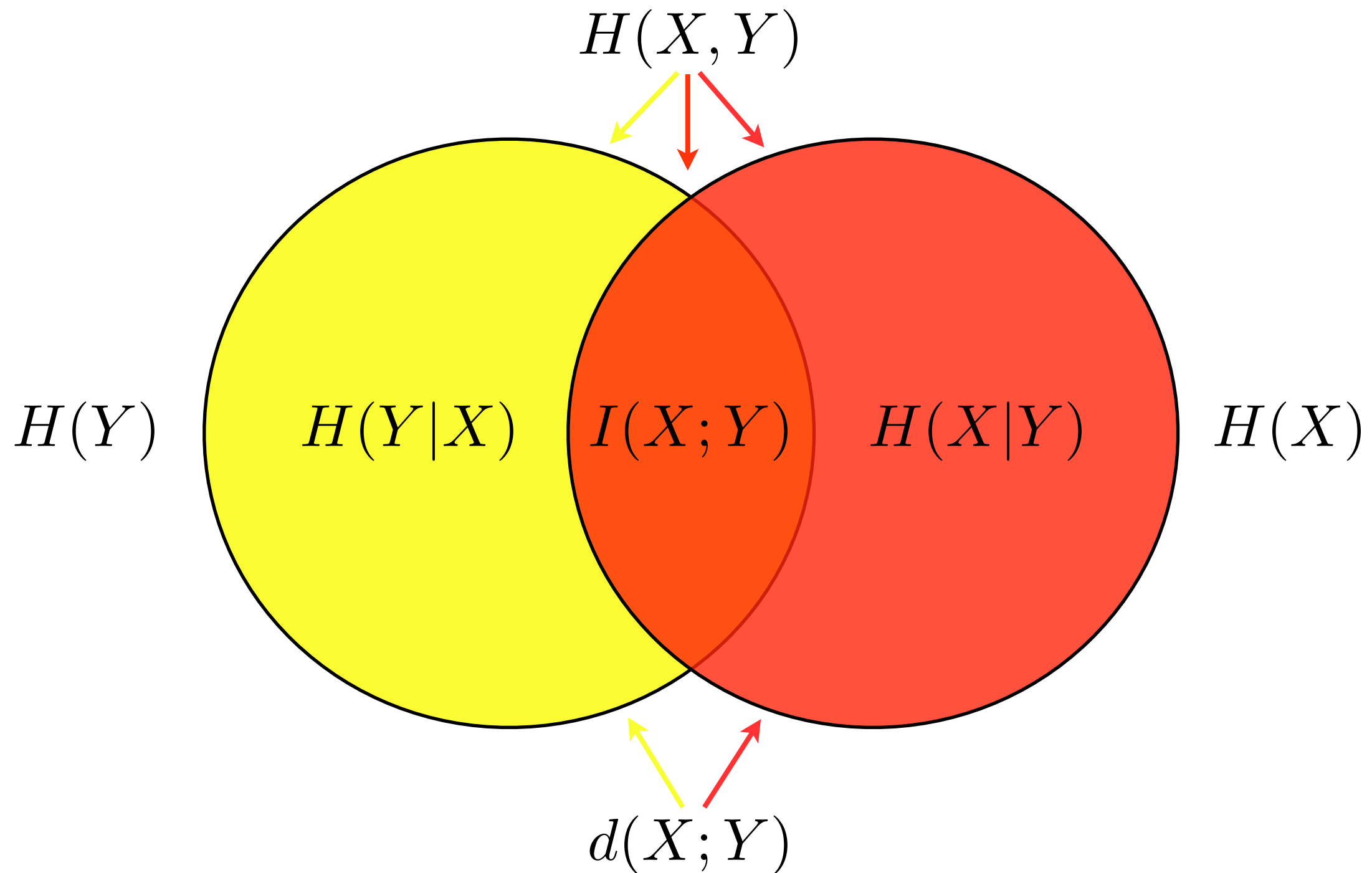
Information ...

Event Space Relationships of Information Quantifiers:



Information ...

Event Space Relationships of Information Quantifiers:



Information ...

Three random variables: $(X, Y, Z) \sim p(x, y, z)$

Markov Chain: $X \rightarrow Y \rightarrow Z$

$$p(x, z|y) = p(x|y)p(z|y) \quad \text{or} \quad I(X; Z|Y) = 0$$

Y shields X and Z from each other: $X \perp_Y Z$

Properties:

$$(1) \quad X \rightarrow Y \rightarrow Z \Rightarrow Z \rightarrow Y \rightarrow X$$

$$(2) \quad Z = f(Y) \Rightarrow X \rightarrow Y \rightarrow Z$$

Information ...

Data Processing Inequality:

$$X \rightarrow Y \rightarrow Z \Rightarrow I(X; Y) \geq I(X; Z)$$

Corollary:

$$Z = g(Y) \Rightarrow I(X; Y) \geq I(X; g(Y))$$

Manipulation *cannot* increase information about X.

Information in Processes ...

Real Information Theory:

How to compress a process:

Can't do better than $H(X)$
(Shannon's First Theorem)

How to communicate a process's data:

Can transmit error-free at rates up to channel capacity
(Shannon's Second Theorem)

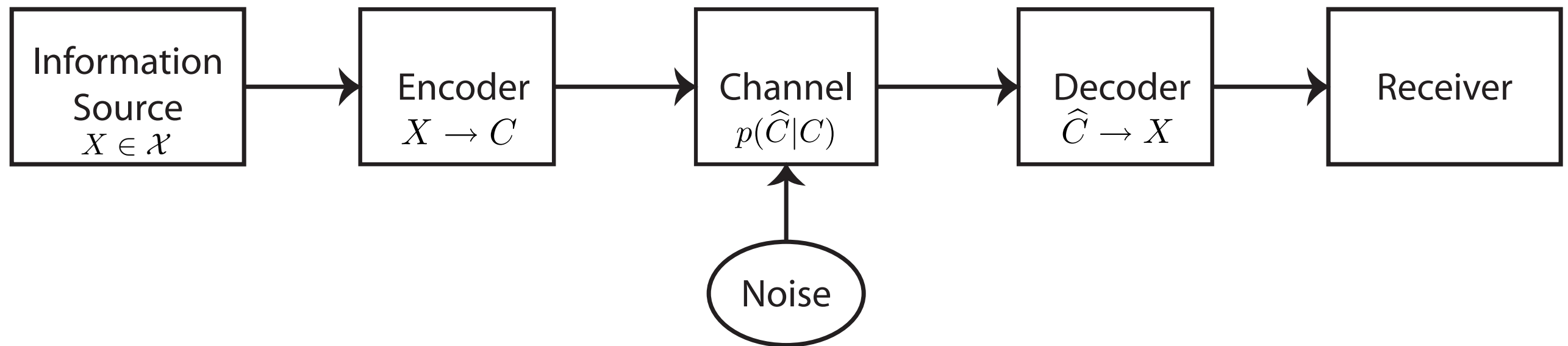
Both results give operational meaning to entropy.

Previously, entropy motivated as a measure of surprise.

Information in Processes ...

Communication channel:

| Messages | Codewords | Corrupted Codewords | Inferred Messages |
|---------------------|------------------------------|--|----------------------|
| $\dots x_3 x_2 x_1$ | $\dots C(x_3) C(x_2) C(x_1)$ | $\dots \hat{C}(x_3) \hat{C}(x_2) \hat{C}(x_1)$ | $\dots x_3 x_2 x_1$ |



Information in Processes ...

Codebook: C

Code rate: $R(C)$ = number bits per message.

Data Compression Theorem (Shannon's First Theorem):

$$R(C) \geq H(X)$$

Cannot compress source below its entropy rate.

Operational meaning of entropy: fundamental limit.

Information in Processes ...

Coding for Communication Channels ...

Discrete channel:

Input: $X \sim p(x)$

Output: $Y \sim p(y)$

Channel: $p(y|x)$

Memoryless channel:

$$p(y_t | x_t x_{t-1} \cdots) = p(y_t | x_t)$$

Channel Capacity:

$$\mathcal{C} = \max_{p(x)} I(X; Y)$$

Information in Processes ...

Channel Coding Theorem (Shannon's Second Theorem):

- (1) Capacity is the maximum reliable transmission rate.
- (2) Error-free codes exist if $R < \mathcal{C}$.

Idea:

Model as noisy channel with non-overlapping outputs.

Strategy:

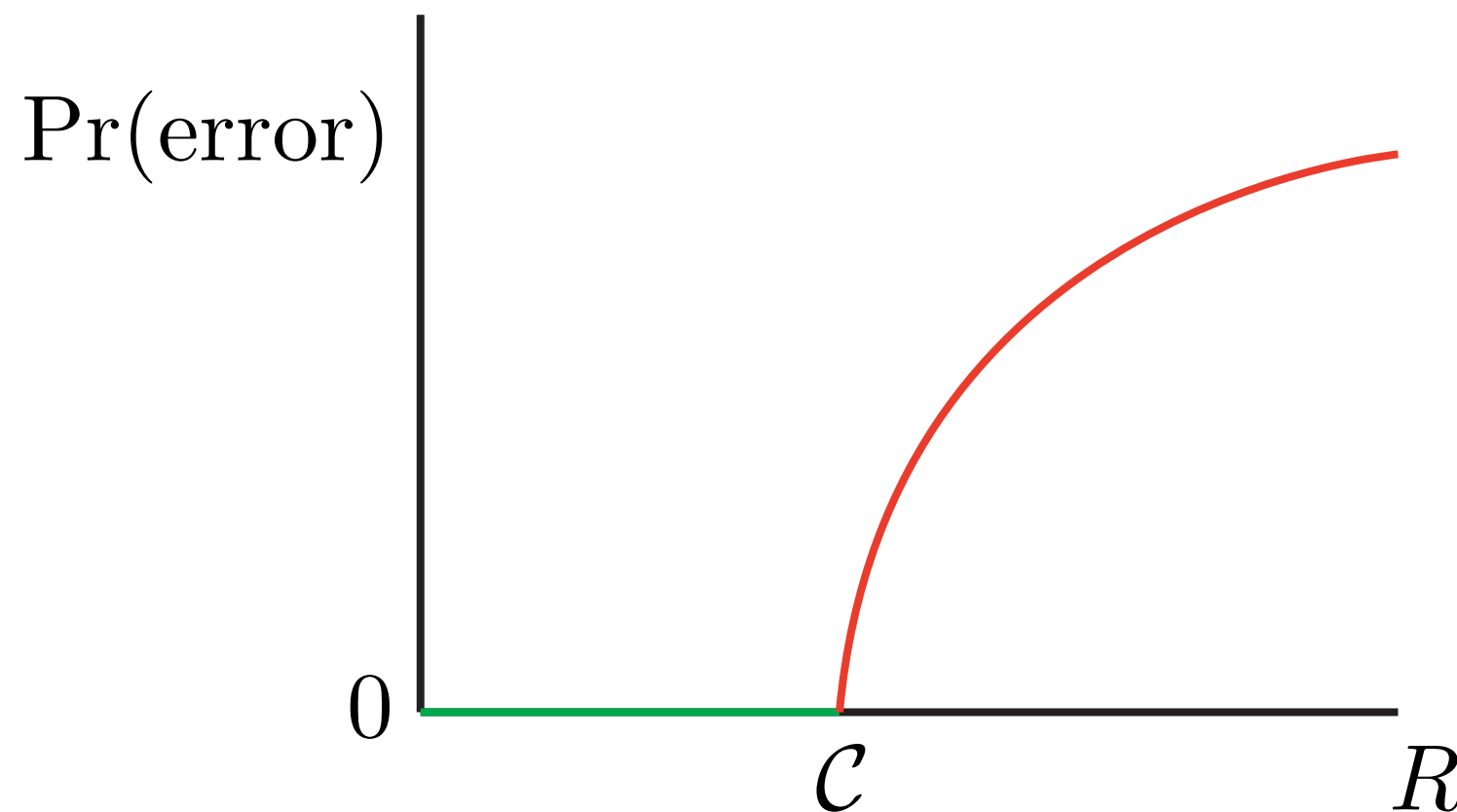
Code long block lengths: $|\mathcal{X}^L| \approx 2^{LH(X)}$

Choose codewords (channel inputs) that
produce non-overlapping outputs.

Information in Processes ...

Channel Coding Theorem ...

What happens when transmitting above capacity, $R > \mathcal{C}$?



(Typical of measurement systems?)