







Symmetrie

Symmetry, as wide or as narrow as you may define it, is one idea by which man through the ages has tried to comprehend and create order, beauty and perfection

Hermann Weyl

The power of symmetry

Symmetry as a natural language for structure:

- Symmetries ⇔ groups/algebra's
- Symmetries of things
- Symmetries of spaces (and time)
- Symmetries of (sets of) equations
- Symmetry as guiding principle in the search for hidden order
- Symmetry breaking and its generic features
- Symmetry breaking and phase transitions.



























Symmetries	and their	breaking	
Quantum electrodynamics	Fermi theory	Strong interactions	General relativity
Quantum electrodynamics Maxwell theory Electromagnetisn Optics	Fermi theory Weak interactions	I Strong interactions	General relativity Newton's gravity theory Grawity
Quantum electrodynamics Maxwel theory Electromagnetism Electronary Magnetism	Fermi theory Weak interactions	I Strong interactions	General relativity Newton's gravity theory Grawty









Symmetry breaking in Biology?

- Symmetry breaking, which may occur at multiple levels, is a prevalent process in biology, because organismal survival depends critically on well-defined structures and patterns at both microscopic and macroscopic scales indeed, patterns like those seen on the fearsome tiger are consequences of broken symmetry.
- P.W. Anderson, speculated that increasing levels of broken symmetry in many-body systems (systems of many interacting components) correlates with increasing complexity and functional specialization (Anderson 1972). This is certainly true in biology, as symmetry breaking along well- defined axes is intimately linked to functional diversification on every scale, from molecular assemblies, to subcellular structures, to cell types themselves, tissue architecture, and embryonic body axes.

Li and Bowerman, Cold Spring harbor perspectives in Biology (2010)





The physics of symmetry

- Systems (building blocks, constituents, cells)
- Interactions => Dynamics => collective behavior. Conservation laws.
- Geometric perspective
- Algebraic perspective
- Breaking of symmetries and their characteristics
- Phase transitions and symmetrybreaking





Representation of group on a vector space												
$G = \{g\} \iff \{n \times n \text{ matrices}\} \iff n-\text{dim vectors}$												
	1	0	0		0	0	1		0	1	0	
e=	0	1	0	r=	1	0	0	r ² =	0	0	1	
	0	0	1		0	1	0		1	0	0	
_	1	0	0		0	0	1		0	1	0	
s ₂₃ =	0	0	1	s ₁₃ =	0	1	0	s ₁₂ =	1	0	0	
	0	1	0		1	0	0		0	0	1	
$<1>= \begin{vmatrix} 1 \\ 0 \\ 0 \end{vmatrix} <2>= \begin{vmatrix} 0 \\ 1 \\ 0 \end{vmatrix} <3>= \begin{vmatrix} 1 \\ 0 \\ 0 \end{vmatrix} <3>= \begin{vmatrix} 1 \\ 0 \\ 0 \end{vmatrix} <1>$												





The Fisher-Griess Monstergroup F or M1 Largest finite group G={g_i ; g_i g_j = g_k} # of elements g_i equals: = 2⁴⁶ · 3²⁰ · 5⁹ · 7⁶ · 11² · 13³ · 17 · 19 · 23 · 29 · 31 · 41 · 47 · 59 · 71 = 808.017.424.794.512.875.886.459.904.961.710.757.005.754.368.000. 000.000

≈ 8 x 10⁵³.

Smallest faithful representation: 196882×196882 matrices



























Translations and their effect

- Transformation x => x' = x+a
- G = R is a continous group with $T_a T_b = T_{a+b}$
- f(x) => f'(x) = f(x') = f(x+a)
- Effect of a small translation $a=\varepsilon$ of a function: $f(x+\varepsilon) = f(x)+\varepsilon df/dx +\varepsilon^2 ... +...$
- The "derivative" p= d/dx "generates" an infinitesimal translation of the function at x
- Knowing df/dx in a point, tells you something about f in the neighborhood of that point
- Eigenfunctions $f_k(x)$ of p=d/dx => p $f_k = k f_k$ then $f_k = e^{kx}$
- The f_k form (irreducible) representations of R
- Tensor "multiplication" of irreps f_a f_b = f_{a+b}
- Invariant function requires : k= 0 so f= const.

Scale transformations

- x => λx
- Generator is D=x d/dx
- D $f_b = x \lambda^b b x^{b-1} = b f_b$
- Eigenfunctions: $f_b(x) = x^b =>$ $f'(x) = f(\lambda x) = \lambda^b x^b = \lambda^b f_b(x)$
- The f_b form representations with "scaling dimension" b
- Invariant function: f = const
- (Lie) Algebra of commutators of generators of T and D: [D,p] = x(d/dx)² - d/dx - x((d/dx)² = - p [p,p]=0 and [D,D]=0
- Non-commuting <=> non-abelian algebra (group)
- No common eigenfunctions of p and D except f = const









Equations

The symmetries that are important in nature, are not the symmetries of things but the symmetries of equations

Steven Weinberg

3. Symmetries and equations





Energy function H(p,q) and Newton's equations

Energy of particle in potential depends on momenta and coordinates only

$$H(q, p) = H_{kin} + H_{pot}$$
$$= p^2/2m + V(q)$$

Newton's laws

$$\begin{vmatrix} \dot{q} = \frac{\partial H}{\partial p} \\ \dot{p} = -\frac{\partial H}{\partial q} \end{vmatrix} \rightarrow \quad \dot{q} = \frac{p}{m}$$
$$\dot{p} = -\frac{\partial V}{\partial q} = F$$

Time evolution of some dynamical variable f(p,q)In general we may write $\frac{df}{dt} =$ $= \frac{\partial f}{\partial q}\dot{q} + \frac{\partial f}{\partial p}\dot{p}$ $= \frac{\partial f}{\partial q}\frac{\partial H}{\partial p} - \frac{\partial f}{\partial p}\frac{\partial H}{\partial q}$ We define a Poisson Bracket: $\{f,g\} \equiv \frac{\partial f}{\partial q}\frac{\partial g}{\partial p} - \frac{\partial f}{\partial p}\frac{\partial g}{\partial q}$ This yields the following equation fot the time derivative of f: $\frac{df}{dt} = \{f, H\}$



















Conformal algebra in d=2

С

Symmetry algebra is infinite dimensional:

$$[L_m, L_n] = (m-n)L_{m+n} + \frac{1}{12}cm(m^2 - 1)\delta_{m, -n}$$

Fields are organized in representations of conformal algebra And the lowest weight of such a representation corresponds to the Critical exponents (powers):

$$=c^{(m)}=1-\frac{6}{m(m+1)}, \qquad m=3,4,5,\ldots.$$

$$h_{p,q}^{(m)} = \frac{\left[(m+1)p - mq\right]^2 - 1}{4m(m+1)}, \qquad \begin{cases} 1 \le p \le m - 1\\ 1 \le q \le m \end{cases}$$

















Defects

- Defects are emergent structures
- They are characteristic for phases with broken symmetries (with groundstate degeneracy)
- They are locally topologically stable
- They play an important role in the dynamics of the phase transition (duality)
- They can be quite generally classified.









Defect classification

- G breaks to H (subgroup of G)
- Orbit of orderparameter φ under G equals G/H This is the so called vacuum manifold of degenerate groundstates
- Spatial manifold M with boundary dM
- Study (homotopy) classes of maps dM => G/H
- These classes form a group and label the topological charges of the defect

Defect Types

- D=1 dM = $Z_2 \pi_0$ (G/H) Kinks or walls
- D=2 dM=S¹ $\pi_1(G/H)$ Particles or line
- D=3 dM= S² $\pi_2(G/H) = \pi_1(H)$ Monopoles
- Non-abelian line defects e.g. if G =SO(3) and H discrete => π₁ = H













Euclidean space is homogeous en isotropic

Euclidean space R^3 : {x,y,z} The empty space looks the same from any point {x,y,z} and in any direction

⇒ Empty space is *invariant* under *translations* and *rotations*. This group is the Euclidean group $E_3 \simeq R^3 \rtimes O(3)$

















Summary

The notion of symmetry breaking has apotential for many applications.

the notion of symmetry

- of objects, spaces and equations
- discrete, continuous ; finite infinite

breaking symmetries

- order parameter
- phase transistions => critical point
- scale (conformal invariance at critical point
- classification of modes and defects
- duality