

# **Consciousness as a Pile of Sand**

If you take **one grain of sand at a time from a conical pile of sand** on a table, when does it become **a few grains on the table?**

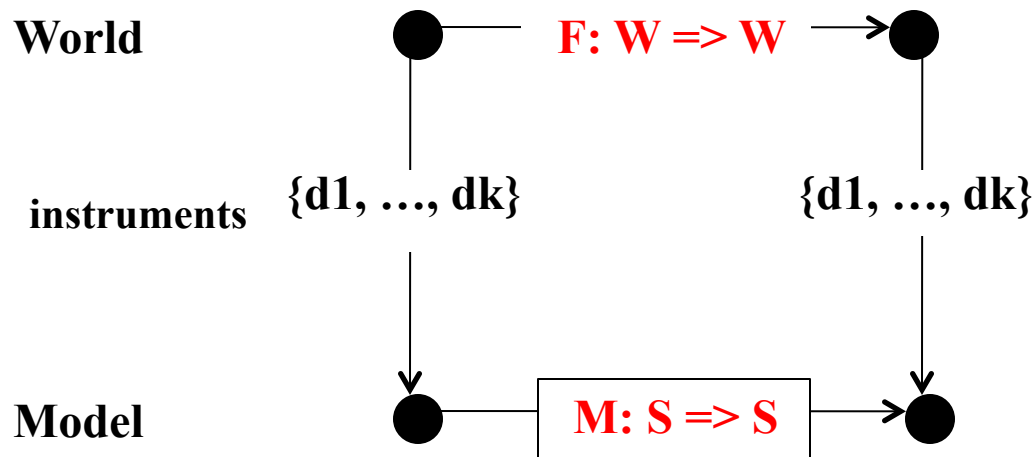
Clearly, a sharp demarcation (say, in terms of number of grains that constitutes a pile) is arbitrary.

Similar considerations apply to important areas in science, such as **life (biology), consciousness (psychology), and complex adaptive systems** in general.

# Models: Reduction and Emergence

The contemplation in natural science of a wider domain than the actual leads to a far better understanding of the actual.

-- A. S. Eddington



Gell-Mann points out that **3 orders of magnitude** in the scale of observations (e.g. from molecules to fluid flow) requires **new laws**. New laws are *constrained* by, but *not determined* by, the laws at lower levels.

# Default Rules

*Starting point:* **Default** Rule.

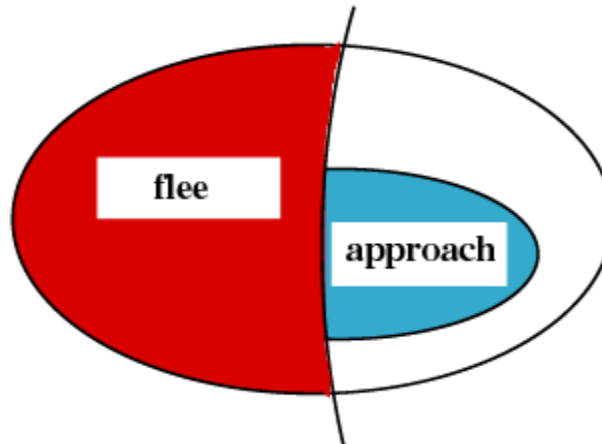
(A rule that is over-general: necessary but not sufficient.)

IF [moving object in vision cone] THEN <flee>

*Elaboration:* **Specialist** rule overrides Default.

(Specialist rule requires additional information.)

IF [moving object]&[small]&[winged] THEN <approach>



There is a **symbiosis** between defaults and specialists.

# Progressive Generalization

The # ( 'don' t care' ) symbol can be used to designate **sets of signals**.

For example, **1##...#** designates **all signals that have a 1 prefix**.

Instance 1

salient, large, blue ball

0000.1**11**1.0000

Instance 2

salient, small, red ball

0000.1**00**1.0000

Generalization of instances 1 and 2

0000.1**##**1.0000

# Procedures for Generating Rules

Initially, **default rule conditions** are formed using just **a few bit** values drawn from the current environment signal.

For example, signal **011010...0** can be used to form

**#1####...#**

or

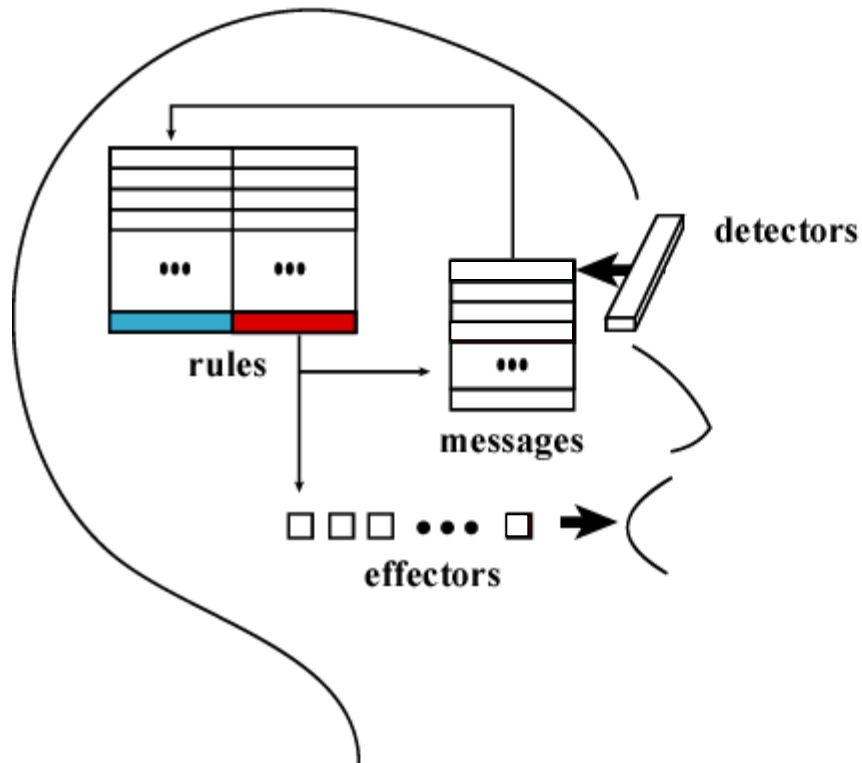
**###01#...#.**

For signals of length  $L=100$ , there just  $L(L+1)/2 = 2450$  defaults using 1 or 2 bits => **all possible *default rules* can be rapidly tested.**

The primary order of learning is both general-to-particular,  
**starting with default conditions,**  
and particular-to-general,  
**using #' s to generalize from specific signals.**

# Performance of a Rule-based Agent

**PARALELLISM:** *Many signals* (e.g. bit-strings) **can be present** at once, and **many signal-processing rules** <IF (signal present 11000) THEN (send signal 00111)> **can be active** simultaneously.



# Language Acquisition Illustrates the Emergence of Consciousness

## 1) Acquisition of **vocabulary**.

**Babbling** (random action) **samples possibilities** (diversity) for attaching utterance to situation.\

Some inputs invoke **imitation** (e.g., ‘shared salient object or action’, ‘Teacher’ utterance)

**‘Meaning’** emerges from **generalization** of conditions associated with the same utterance.

## 2) Acquisition of specific **utterance pairs**.

Sequences **reduce ambiguity**.

## 3) **Generalization of sequences** to ‘grammatical’ rules.



## Levels of Consciousness – Level 0

[An approach based on the research of **Helena Hong Gao**]

*‘Wired-in’ (inherited) cognitive abilities.*

Ability to **imitate** utterances and gestures.

Ability to distinguish between **objects** and **actions**.

Awareness of a mutually apprehended **salient** object or action.

Basic **learning** procedures (akin to Hebb’s learning rule).

IF (**any signal**) THEN (**random effector activity**)

# Levels of Consciousness – Level 1

*Control of motion (as precursor to gesture).*

**Task:** Bring hand in controlled motion across visual field.  
**Mode:** Innate reinforcement for predictable outcomes.  
**Anticipation:** Movement according to command.

**IF (hand in vision cone) THEN (<move hand right>)**

## Levels of Consciousness – Level 2

*Utterance for immediate, “wired-in” reward, e.g. ‘Teacher’s’ smile.*

**Task:** Social interaction.

**Mode:** Imitation of situated utterance.

**Anticipation:** Positive interaction.

**IF (milk bottle present) THEN (<utterance “milk”> )**

**This rule will be strengthened, over other random utterances, because [T-smile] increments sociality reservoir.**

## Levels of Consciousness – Level 3

*Utterance to “move” visible object.*

**Task:** Food acquisition (when food visible).  
**Mode:** Conditioning.  
**Anticipation:** Food.

**IF (milk bottle visible) THEN < “milk”>**

**‘Teacher’ moves milk bottle to mouth.**

**IF (<milk bottle at mouth>) THEN (<consume milk>)**

## Levels of Consciousness – Level 4

*Utterance to cause appearance of object.*

**Task:** Food acquisition (when food not visible).  
**Mode:** Internal model (lookahead) – autonomy required.  
**Anticipation:** Appearance of food (later generalized to arbitrary objects)

IF ([**hungry**] & **no food visible**) THEN <**“milk”**>  
‘Teacher’ acts to fetch milk bottle.

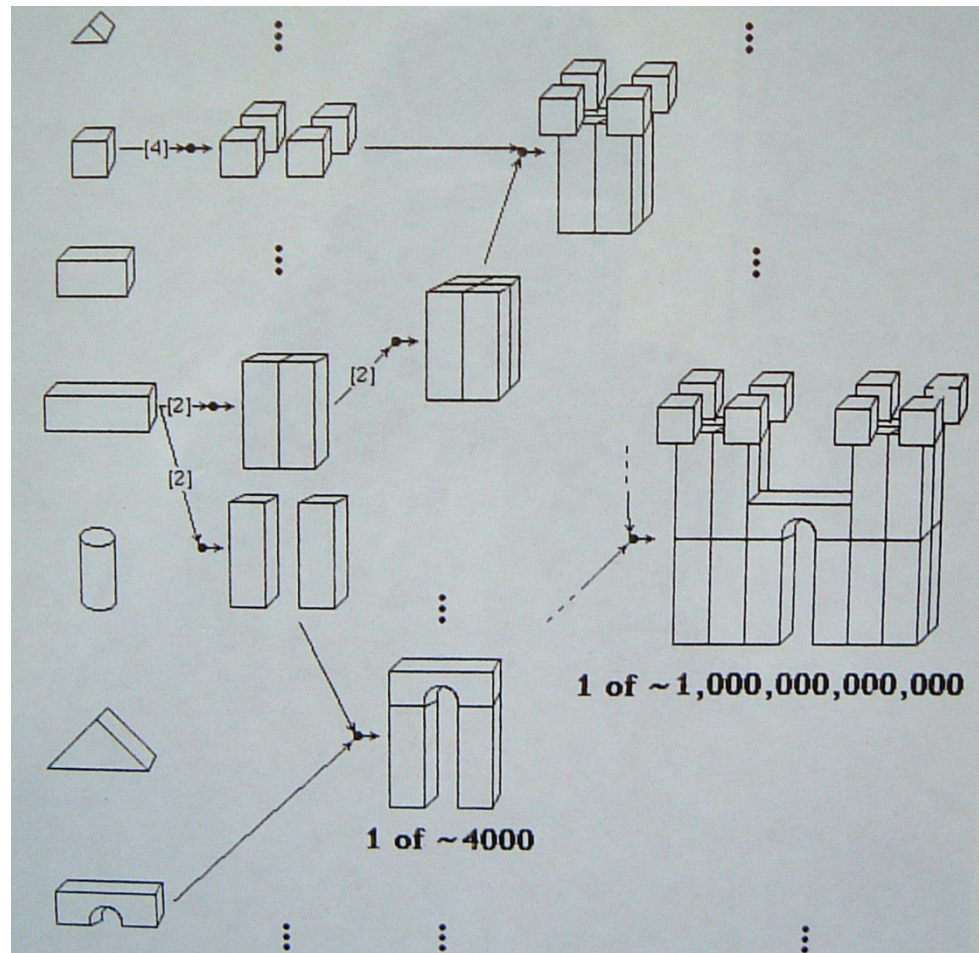
IF (<**T acts**>) THEN <**milk bottle visible**>

Acquired from previous levels:

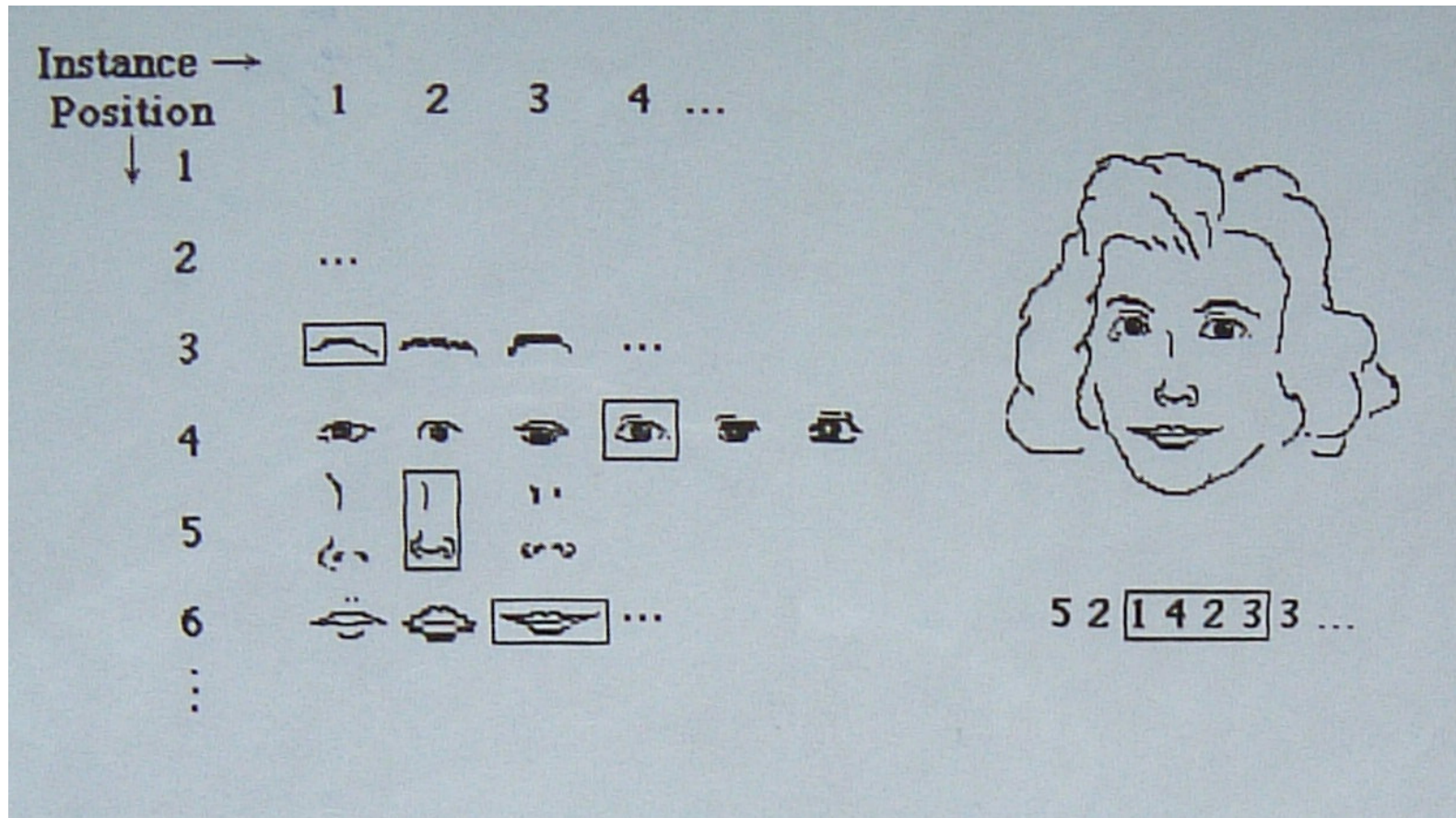
IF (milk bottle visible) THEN <“milk”>  
‘Teacher’ moves milk bottle to mouth.

IF (<milk bottle at mouth>) THEN (<consume milk>)

# Building Blocks and Emergence



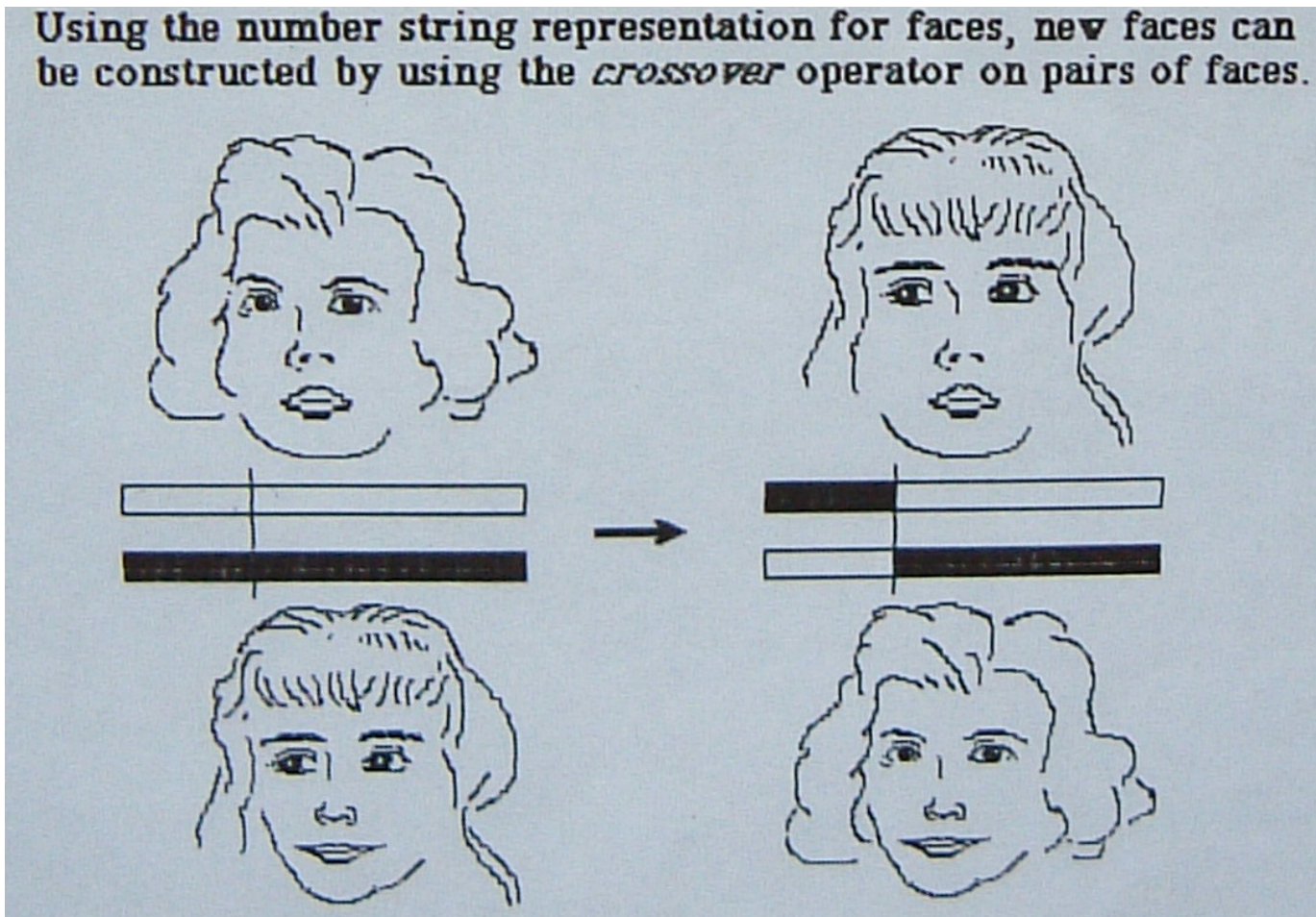
# Building Blocks for a Face





# Innovation by Recombination

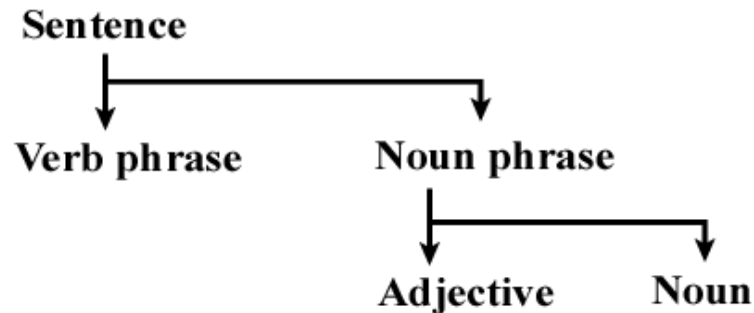
Using the number string representation for faces, new faces can be constructed by using the *crossover* operator on pairs of faces.





# Vocabulary as Building Blocks

**A grammar makes possible the combinatoric use of vocabulary.**



'fetch (to me)  
'take' (from me)  
'go' (to)  
'look' (at)

**60 meaningful triples can be constructed from the 12 utterances shown.**

**The number of meaningful triples increases exponentially with vocabulary size: If there are 20 utterances in each category, 8000 meaningful triples can be constructed.**

# Two Emergent Phenomena Closely Related to Consciousness

**Autonomy** (e.g. the internal models used in planning and lookahead) requires recurrence (e.g. networks with **many loops** a la Hebb).

**Input modulates but does not determine ongoing activity.**

**Pattern recognition by *saccades*:** Human pattern recognition proceeds by a series of highly localized ‘snapshots’ that reveal no detail about the overall scene.

That is, pattern recognition in humans does not use a pixel-by-pixel raster scan.

These **snapshots are directed and integrated by input from higher levels in the CNS.**