# Anatomy of an Observation: A Rope of Sand

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$$\cdots X_{-3} X_{-2} X_{-1} X_0 X_1 X_2 X_3 \cdots$$



$$X_0$$

$$\cdots X_{-3} X_{-2} X_{-1} X_0 X_1 X_2 X_3 \cdots$$



$$X_{:0}$$
  $X_{0}$   $\cdots$   $X_{-3}$   $X_{-2}$   $X_{-1}$   $X_{0}$   $X_{1}$   $X_{2}$   $X_{3}$   $\cdots$ 



$$X_{:0}$$
  $X_{0}$   $X_{1:}$   $\cdots$   $X_{-3}$   $X_{-2}$   $X_{-1}$   $X_{0}$   $X_{1}$   $X_{2}$   $X_{3}$   $\cdots$ 



$$X_{:0}$$
  $X_{0}$   $X_{1:}$   $\cdots$   $X_{-3}$   $X_{-2}$   $X_{-1}$   $X_{0}$   $X_{1}$   $X_{2}$   $X_{3}$   $\cdots$ 

We limit ourselves to timeseries which are:



$$X_{:0}$$
  $X_{0}$   $X_{1:}$   $\cdots$   $X_{-3}$   $X_{-2}$   $X_{-1}$   $X_{0}$   $X_{1}$   $X_{2}$   $X_{3}$   $\cdots$ 

We limit ourselves to timeseries which are:

• Ergodic



$$X_{:0}$$
  $X_{0}$   $X_{1:}$   $\cdots$   $X_{-3}$   $X_{-2}$   $X_{-1}$   $X_{0}$   $X_{1}$   $X_{2}$   $X_{3}$   $\cdots$ 

We limit ourselves to timeseries which are:

- Ergodic
- Stationary



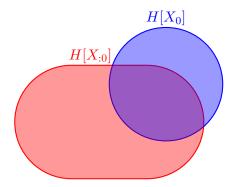
$$X_{:0}$$
  $X_{0}$   $X_{1:}$   $\cdots$   $X_{-3}$   $X_{-2}$   $X_{-1}$   $X_{0}$   $X_{1}$   $X_{2}$   $X_{3}$   $\cdots$ 

We limit ourselves to timeseries which are:

- Ergodic
- Stationary
- Discrete

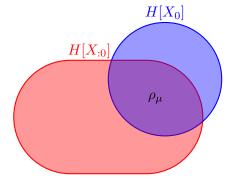


#### Past and Present





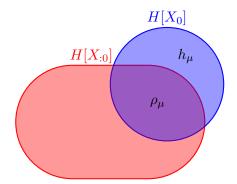
#### Past and Present



•  $\rho_{\mu} = I[X_{:0}; X_0]$ : redundant information

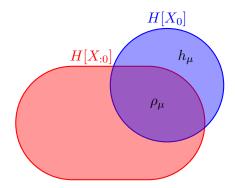


#### Past and Present

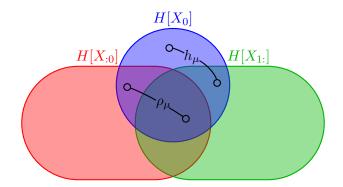


- $\rho_{\mu} = I[X_{:0}; X_0]$ : redundant information
- $h_{\mu} = H[X_0|X_{:0}]$ : unanticipated information

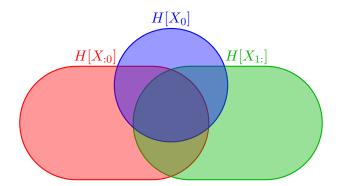




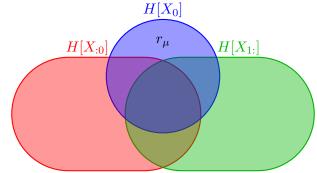






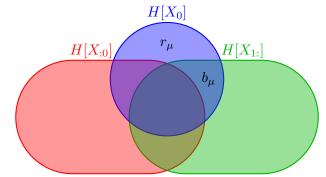






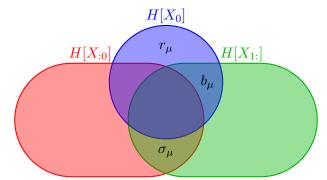
•  $r_{\mu} = H[X_0|X_{:0}, X_{1:}]$ : ephemeral information





- $r_{\mu} = H[X_0|X_{:0}, X_{1:}]$ : ephemeral information
- $b_{\mu} = I[X_0; X_{1:}|X_{:0}]$ : structural information





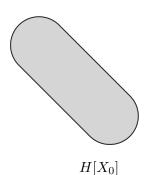
- $r_{\mu} = H[X_0|X_{:0}, X_{1:}]$ : ephemeral information
- $b_{\mu} = I[X_0; X_{1:}|X_{:0}]$ : structural information
- $\sigma_{\mu} = I[X_{:0}; X_{1:}|X_{0}]$ : evidence of internal states



$$H(\ell) = H[X_{0:\ell}]$$

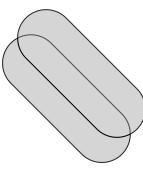


$$H(\ell) = H[X_{0:\ell}]$$





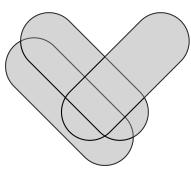
$$H(\ell) = H[X_{0:\ell}]$$



 $H[X_0, X_1]$ 



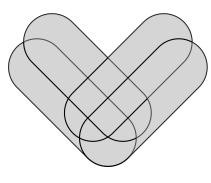
$$H(\ell) = H[X_{0:\ell}]$$



 $H[X_0, X_1, X_2]$ 



$$H(\ell) = H[X_{0:\ell}]$$



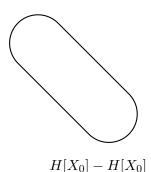
 $H[X_0, X_1, X_2, X_3]$ 



$$T(\ell) = \sum_{i=0}^{\ell} H[X_i] - H[X_{0:\ell}]$$

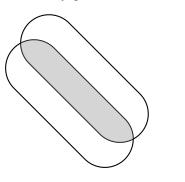


$$T(\ell) = \sum_{i=0}^{\ell} H[X_i] - H[X_{0:\ell}]$$





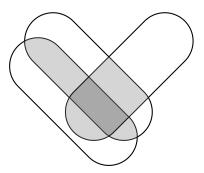
$$T(\ell) = \sum_{i=0}^{c} H[X_i] - H[X_{0:\ell}]$$



 $H[X_0] + H[X_1] - H[X_0, X_1]$ 



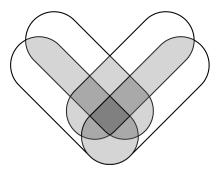
$$T(\ell) = \sum_{i=0}^{\ell} H[X_i] - H[X_{0:\ell}]$$



 $H[X_0] + H[X_1] + H[X_2] - H[X_0, X_1, X_2]$ 



$$T(\ell) = \sum_{i=0}^{\ell} H[X_i] - H[X_{0:\ell}]$$



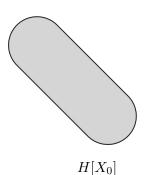
 $H[X_0] + H[X_1] + H[X_2] + H[X_3] - H[X_0, X_1, X_2, X_3]$ 



$$R(\ell) = \sum_{i=0}^{\ell} H[X_i | X_{0:\ell \setminus i}]$$

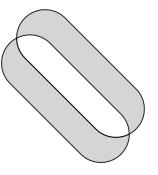


$$R(\ell) = \sum_{i=0}^{\ell} H[X_i | X_{0:\ell \setminus i}]$$





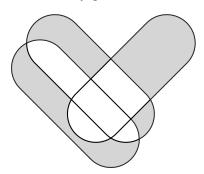
$$R(\ell) = \sum_{i=0}^{\ell} H[X_i | X_{0:\ell \setminus i}]$$



 $H[X_0|X_1] + H[X_1|X_0]$ 



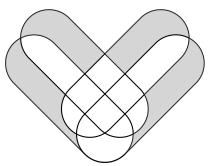
$$R(\ell) = \sum_{i=0}^{\ell} H[X_i | X_{0:\ell \setminus i}]$$



 $H[X_0|X_1,X_2] + H[X_1|X_0,X_2] + H[X_2|X_0,X_1]$ 



$$R(\ell) = \sum_{i=0}^{\ell} H[X_i | X_{0:\ell \setminus i}]$$



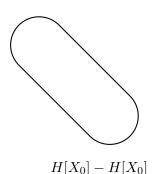
 $H[X_0|X_1,X_2,X_3] + H[X_1|X_0,X_2,X_3] + H[X_2|X_0,X_1,X_3] + H[X_3|X_0,X_1,X_2]$ 



$$B(\ell) = H[X_{0:\ell}] - \sum_{i=0}^{\ell} H[X_i | X_{0:\ell \setminus i}]$$

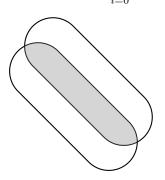


$$B(\ell) = H[X_{0:\ell}] - \sum_{i=0}^{\ell} H[X_i | X_{0:\ell \setminus i}]$$





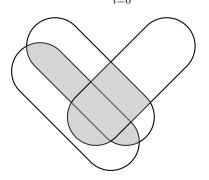
$$B(\ell) = H[X_{0:\ell}] - \sum_{i=0}^{\ell} H[X_i | X_{0:\ell \setminus i}]$$



 $H[X_0, X_1] - H[X_0|X_1] - H[X_1|X_0]$ 



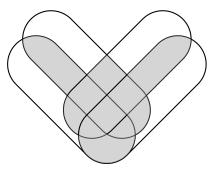
$$B(\ell) = H[X_{0:\ell}] - \sum_{i=0}^{\ell} H[X_i | X_{0:\ell \setminus i}]$$



 $H[X_0, X_1, X_2] - H[X_0|X_1, X_2] - H[X_1|X_0, X_2] - H[X_2|X_0, X_1]$ 



$$B(\ell) = H[X_{0:\ell}] - \sum_{i=0}^{\ell} H[X_i | X_{0:\ell \setminus i}]$$



 $H[X_0, X_1, X_2, X_3] - H[X_0|X_1, X_2, X_3] - H[X_1|X_0, X_2, X_3] - H[X_2|X_0, X_1, X_3] - H[X_3|X_0, X_1, X_2]$ 

